

June 2003

### LM4889 Boomer® Audio Power Amplifier Series

# 1 Watt Audio Power Amplifier

### **General Description**

The LM4889 is an audio power amplifier primarily designed for demanding applications in mobile phones and other portable communication device applications. It is capable of delivering 1 watt of continuous average power to an  $8\Omega$  BTL load with less than 2% distortion (THD+N) from a  $5V_{DC}$  power supply.

Boomer audio power amplifiers were designed specifically to provide high quality output power with a minimal amount of external components. The LM4889 does not require output coupling capacitors or bootstrap capacitors, and therefore is ideally suited for mobile phone and other low voltage applications where minimal power consumption is a primary requirement.

The LM4889 features a low-power consumption shutdown mode, which is achieved by driving the shutdown pin with a logic low. Additionally, the LM4889 features an internal thermal shutdown protection mechanism.

The LM4889 contains advanced pop & click circuitry to eliminate noise which would otherwise occur during turn-on and turn-off transitions.

The LM4889 is unity-gain stable and can be configured by external gain-setting resistors.

### **Key Specifications**

Improved PSRR at 217Hz, 5 - 3.3V
 Power Output at 5.0V & 2% THD
 Power Output at 3.3V & 1% THD
 Shutdown Current at 3.3 & 2.6V
 75dB
 1.0W(typ.)
 400mW(typ.)
 0.01μA(typ.)

#### **Features**

- Available in space-saving MSOP, SOIC, LLP, and micro SMD packages
- Ultra low current shutdown mode (3.3 to 2.6V 0.01µA)
- Can drive capacitive loads up to 500 pF
- Improved pop & click circuitry eliminates noises during turn-on and turn-off transitions
- 2.2 5.5V operation
- No output coupling capacitors, snubber networks or bootstrap capacitors required
- Unity-gain stable
- External gain configuration capability

## **Applications**

- Mobile Phones
- PDAs
- Portable electronic devices

## Typical Application

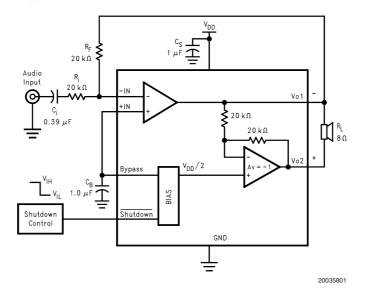
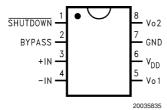


FIGURE 1. Typical Audio Amplifier Application Circuit

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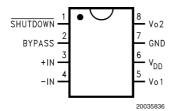
### **Connection Diagrams**

Small Outline (SO) Package



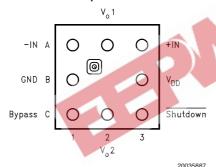
Top View Order Number LM4889MA See NS Package Number M08A

Mini Small Outline (MSOP) Package



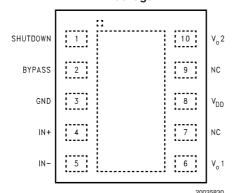
Top View Order Number LM4889MM See NS Package Number MUA08A

8 Bump micro SMD



Top View
Order Number LM4889ITL, LM4889ITLX
See NS Package Number TLA08AAA

LLP Package



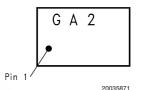
Top View Order Number LM4889LD See NS Package Number LDA10B

SO Marking



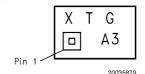
Top View
XY - Date Code
TT - Die Traceability
Bottom 2 lines - Part Number

**MSOP Marking** 



Top View
G - Boomer Family
A2 - LM4889MM

### 8 Bump micro SMD Marking



Top View
X - Date Code
T - Die Traceability
G - Boomer Family
A3 - LM4889ITL

10 Pin LLP Marking



Top View
Z - Assembly Plant Date Code (M for Malacca)
XY - 2 Digit Date Code
TT - Die Traceability
L4889 - LM4889LD

220°C/W

### **Absolute Maximum Ratings** (Note 2)

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

6.0V Supply Voltage

Storage Temperature -65°C to +150°C

Input Voltage -0.3V to  $V_{DD} + 0.3V$ 

Power Dissipation (Note 3)

ESD Susceptibility (Note 4) 2000V

200V ESD Susceptibility (Note 5) 150°C

Junction Temperature

Thermal Resistance

 $\theta_{JC}$  (SOP) 35°C/W 150°C/W  $\theta_{JA}$  (SOP)

 $\theta_{JA}$  (8 Bump micro SMD) (Note 10) 210°C/W  $\theta_{JC}$  (MSOP) 56°C/W  $\theta_{\mathsf{JA}}$  (MSOP) 190°C/W

Soldering Information

See AN-1112 "microSMD Wafers Level Chip Scale

Package".

 $\theta_{JA}$  (LLP)

### **Operating Ratings**

Temperature Range

 $-40^{\circ}C \leq T_{A} \leq 85^{\circ}C$  $T_{MIN} \leq T_A \leq T_{MAX}$ Supply Voltage  $2.2V \le V_{DD} \le 5.5V$ 

Electrical Characteristics  $V_{DD} = 5V$  (Notes 1, 2) The following specifications apply for  $V_{DD} = 5V$ ,  $A_V = 2$ , and  $8\Omega$  load unless otherwise specified. Limits apply for  $T_A = 25^{\circ}C$ .

Internally Limited

			LM4889		Heite
Symbol	Parameter	Conditions	Typical	Limit	Units (Limits)
			(Note 6)	(Notes 7, 9)	(Lillins)
	Quiescent Power Supply Current	$V_{IN} = 0V$ , $I_o = 0A$ , no Load	4	8	mA (max)
I <sub>DD</sub>		$V_{IN} = 0V$ , $I_o = 0A$ , with BTL Load	5	8	mA (max)
I <sub>SD</sub>	Shutdown Current	V <sub>shutdown</sub> = GND (Note 8)	0.1	1	μA (max)
$V_{SDIH}$	Shutdown Voltage Input High			1.2	V (min)
$V_{SDIL}$	Shutdown Voltage Input Low			0.4	V (max)
Po	Output Power	THD = 2% (max); f = 1 kHz	1		W
THD+N	Total Harmonic Distortion+Noise	$P_o = 0.4 \text{ Wrms}; f = 1 \text{kHz}$	0.1		%
PSRR	Power Supply Rejection Ratio	V <sub>ripple</sub> = 200mV sine p-p			
		f <sub>ripple</sub> = 217Hz	62		dB
		f <sub>ripple</sub> = 1kHz	66		dB
		V <sub>ripple</sub> = 200mV sine p-p			
		Input Floating	75	68	dB

Electrical Characteristics  $V_{DD}$  = 3.3V (Notes 1, 2) The following specifications apply for  $V_{DD}$  = 3.3V,  $A_{V}$  = 2, and  $8\Omega$  load unless otherwise specified. Limits apply for  $T_{A}$  = 25°C.

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Symbol	Parameter	Conditions	Typical	Limit	Units (Limits)
			(Note 6)	(Notes 7, 9)	(Lillins)
I <sub>DD</sub>	Quiescent Power Supply Current	$V_{IN} = 0V$ , $I_o = 0A$ , no Load	3.5	7	mA (max)
		$V_{IN} = 0V$ , $I_o = 0A$ , with BTL Load	4.5	7	mA (max)
I <sub>SD</sub>	Shutdown Current	V <sub>shutdown</sub> = GND (Note 8)	0.01	1	μA (max)
V <sub>SDIH</sub>	Shutdown Voltage Input High			1.2	V (min)
V <sub>SDIL</sub>	Shutdown Voltage Input Low			0.4	V (max)
Po	Output Power	THD = 1% (max); f = 1kHz	0.4		W
THD+N	Total Harmonic Distortion+Noise	$P_o = 0.25Wrms$ ; $f = 1kHz$	0.1		%
		V <sub>ripple</sub> = 200mV sine p-p			
PSRR	Power Supply Rejection Ratio	$f_{ripple} = 217Hz$	60		dB
		f <sub>ripple</sub> =1kHz	62		dB

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Electrical Characteristics  $V_{DD}$  = 2.6V (Notes 1, 2) The following specifications apply for  $V_{DD}$  = 2.6V,  $A_V$  = 2, and  $8\Omega$  load unless otherwise specified. Limits apply for  $T_A$  = 25°C.

			LM4889		l luite
Symbol	Parameter	Conditions	Typical	Limit	Units (Limits)
			(Note 6)	(Notes 7, 9)	(Lillins)
I <sub>DD</sub>	Quiescent Power Supply Current	$V_{IN} = 0V$ , $I_o = 0A$ , no Load	2.6	6	mA (max)
		$V_{IN} = 0V$ , $I_o = 0A$ , with BTL Load	3.0	6	mA (max)
I <sub>SD</sub>	Shutdown Current	V <sub>shutdown</sub> = GND (Note 8)	0.01	1	μA (max)
D	Output Power (8Ω)	THD = 1% (max); f = 1 kHz	0.2		W
Po	Output Power (4Ω)	THD = 1% (max); f = 1 kHz	0.22		W
THD+N	Total Harmonic Distortion+Noise	$P_o = 0.1Wrms; f = 1kHz$	0.08		%
		V <sub>ripple</sub> = 200mV sine p-p			
PSRR	Power Supply Rejection Ratio	f <sub>ripple</sub> = 217Hz	44		dB
		$f_{ripple} = 1kHz$	44		dB

Note 1: All voltages are measured with respect to the ground pin, unless otherwise specified.

Note 2: Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is functional, but do not guarantee specific performance limits. Electrical Characteristics state DC and AC electrical specifications under particular test conditions which guarantee specific performance limits. This assumes that the device is within the Operating Ratings. Specifications are not guaranteed for parameters where no limit is given, however, the typical value is a good indication of device performance.

Note 3: The maximum power dissipation must be derated at elevated temperatures and is dictated by  $T_{JMA}X$ ,  $\theta_{JA}$ , and the ambient temperature  $T_A$ . The maximum Note 3: The maximum power dissipation must be delated at elevated temperatures and is dictated by J<sub>JMAX</sub>, θ<sub>JA</sub>, and the ambient temperature T<sub>A</sub>. The maximum allowable power dissipation is P<sub>DMAX</sub> = (T<sub>JMAX</sub>-T<sub>A</sub>)/θ<sub>JA</sub> or the number given in Absolute Maximum Ratings, whichever is lower. For the LM4889, see power derating currents for additional information.

Note 4: Human body model, 100 pF discharged through a 1.5 kΩ resistor.

Note 5: Machine Model, 220 pF–240 pF discharged through all pins.

Note 6: Typicals are measured at 25°C and represent the parametric norm.

Note 7: Limits are guaranteed to National's AOQL (Average Outgoing Quality Level)

Note 8: For micro SMD only, shutdown current is measured in a Normal Room Environment. Exposure to direct sunlight will increase I<sub>SD</sub> by a maximum of 2μA.

Note 9: Datasheet min/max specification limits are guaranteed by design, test or statistical analysis

Note 10: All bumps have the same thermal resistance and contribute equally when used to lower thermal resistance. The LM4889ITL demo board (views featured in the Application Information section) has two inner layers, one for  $V_{DD}$  and one for GND. The planes each measure 600mils x 600mils (15.24mm x 15.24mm) and aid in spreading heat due to power dissipation within the IC.

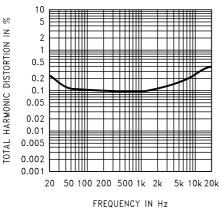
## **External Components Description**

(Figure 1)

	Functional Description		
Ri	Inverting input resistance which sets the closed-loop gain in conjunction with R <sub>f</sub> . This resistor also forms a		
	high pass filter with $C_i$ at $f_C = 1/(2\pi R_i C_i)$ .		
Ci	Input coupling capacitor which blocks the DC voltage at the amplifiers input terminals. Also creates a		
	highpass filter with $R_i$ at $f_c = 1/(2\pi R_i C_i)$ . Refer to the section, <b>Proper Selection of External Components</b> ,		
	for an explanation of how to determine the value of C <sub>i</sub> .		
$R_f$	Feedback resistance which sets the closed-loop gain in conjunction with $R_i$ . $A_{VD} = 2*(R_i/R_i)$ .		
Cs	Supply bypass capacitor which provides power supply filtering. Refer to the Power Supply Bypassing		
	section for information concerning proper placement and selection of the supply bypass capacitor.		
Св	Bypass pin capacitor which provides half-supply filtering. Refer to the section, Proper Selection of External		
	Components, for information concerning proper placement and selection of C <sub>B</sub> .		
	C <sub>i</sub>		

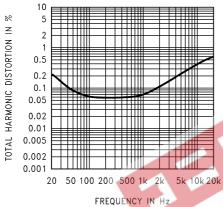
### **Typical Performance Characteristics**

### THD+N vs Frequency at $\text{V}_{\text{DD}}$ = 5V, $8\Omega$ R<sub>L</sub>, and PWR = 250mW



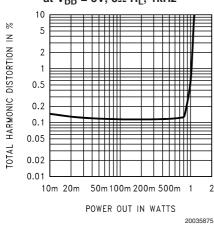
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### THD+N vs Frequency at $V_{DD}$ = 2.6V, $8\Omega$ R<sub>L</sub>, and PWR = 100mW

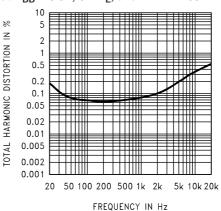


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### THD+N vs Power Out at $V_{DD}$ = 5V, $8\Omega R_L$ , 1kHz

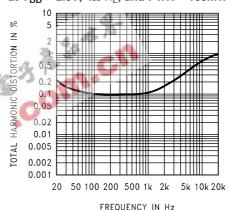


THD+N vs Frequency at  $V_{DD}$  = 3.3V,  $8\Omega$  R<sub>L</sub>, and PWR = 150mW



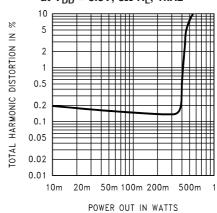
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### THD+N vs Frequency at $\mbox{V}_{\mbox{\scriptsize DD}}$ = 2.6V, $4\Omega$ $\mbox{R}_{\mbox{\scriptsize L}},$ and PWR = 100mW



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### THD+N vs Power Out at $V_{DD}$ = 3.3V, $8\Omega$ R<sub>L</sub>, 1kHz

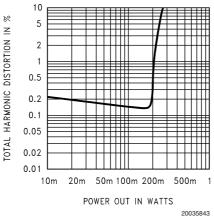


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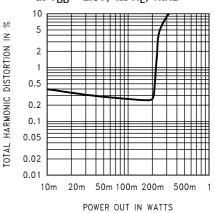
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### **Typical Performance Characteristics** (Continued)

THD+N vs Power Out at  $V_{DD}$  = 2.6V,  $8\Omega$  R<sub>L</sub>, 1kHz

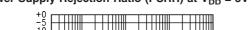


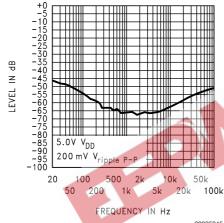
THD+N vs Power Out at  $V_{DD}$  = 2.6V,  $4\Omega$  R<sub>L</sub>, 1kHz



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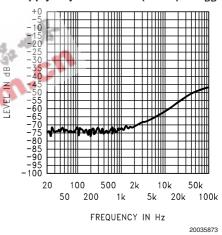
Power Supply Rejection Ratio (PSRR) at  $V_{\rm DD}$  = 5V





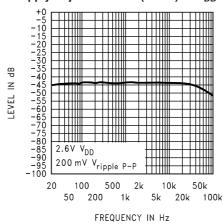
Input terminated with 10 $\Omega$  R

Power Supply Rejection Ratio (PSRR) at  $V_{\rm DD}$  = 5V



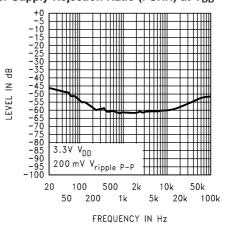
Input Floating

Power Supply Rejection Ratio (PSRR) at  $V_{DD} = 2.6V$ 



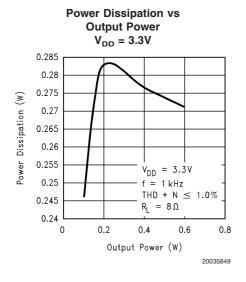
Input terminated with 10 $\Omega$  R

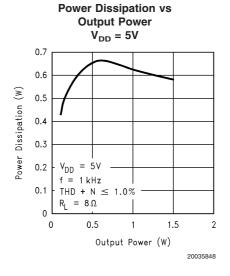
Power Supply Rejection Ratio (PSRR) at V<sub>DD</sub> = 3.3V

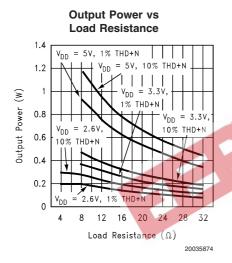


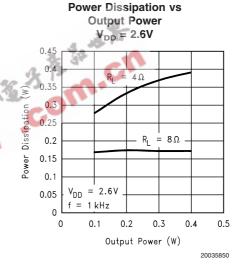
Input terminated with 10 $\Omega$  R

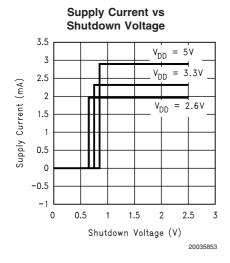
## **Typical Performance Characteristics** (Continued)

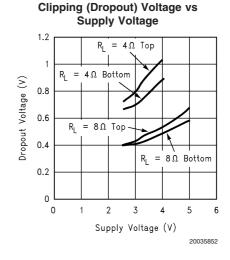






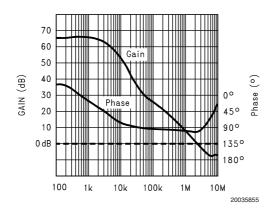




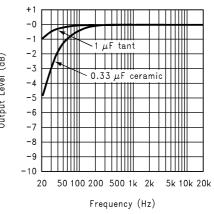


## Typical Performance Characteristics (Continued)

### **Open Loop Frequency Response**

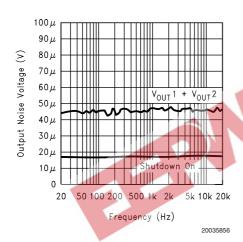


#### Frequency Response vs Input Capacitor Size

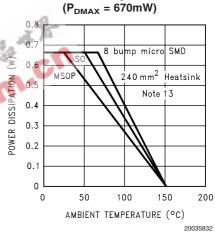


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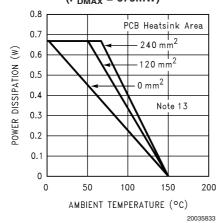
**Noise Floor** 



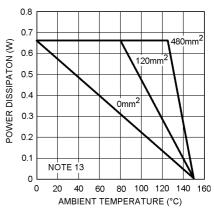
Power Derating Curves
(Power = 670mW)



Power Derating Curves - 8 bump  $\mu$ SMD ( $P_{DMAX}$  = 670mW)



Power Derating Curves - 10 Pin LD pkg  $(P_{DMAX} = 670mW)$ 



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### **Application Information**

#### **BRIDGE CONFIGURATION EXPLANATION**

As shown in *Figure 1*, the LM4889 has two operational amplifiers internally, allowing for a few different amplifier configurations. The first amplifier's gain is externally configurable, while the second amplifier is internally fixed in a unity-gain, inverting configuration. The closed-loop gain of the first amplifier is set by selecting the ratio of  $R_{\rm f}$  to  $R_{\rm i}$  while the second amplifier's gain is fixed by the two internal  $20 k\Omega$  resistors. *Figure 1* shows that the output of amplifier one serves as the input to amplifier two which results in both amplifiers producing signals identical in magnitude, but out of phase by 180°. Consequently, the differential gain for the IC is

$$A_{VD} = 2 * (R_f/R_i)$$

By driving the load differentially through outputs Vo1 and Vo2, an amplifier configuration commonly referred to as "bridged mode" is established. Bridged mode operation is different from the classical single-ended amplifier configuration where one side of the load is connected to ground.

A bridge amplifier design has an advantage over the single-ended configuration, as it provides differential drive to the load, thus doubling output swing for a specified supply voltage. Four times the output power is possible as compared to a single-ended amplifier under the same conditions. This increase in attainable output power assumes that the amplifier is not current limited or clipped. In order to choose an amplifier's closed-loop gain without causing excessive clipping, please refer to the **Audio Power Amplifier Design** section.

A bridge configuration, such as the one used in LM4889, also creates a second advantage over single-ended amplifiers. Since the differential outputs, Vo1 and Vo2, are biased at half-supply, no net DC voltage exists across the load. This eliminates the need for an output coupling capacitor which is required in a single supply, single-ended amplifier configuration. Without an output coupling capacitor, the half-supply bias across the load would result in both increased internal IC power dissipation and also possible loudspeaker damage.

#### POWER DISSIPATION

Power dissipation is a major concern when designing a successful amplifier, whether the amplifier is bridged or single-ended. A direct consequence of the increased power delivered to the load by a bridge amplifier is an increase in internal power dissipation. Since the LM4889 has two operational amplifiers in one package, the maximum internal power dissipation is 4 times that of a single-ended amplifier. The maximum power dissipation for a given application can be derived from the power dissipation graphs or from Equation 1.

$$P_{DMAX} = 4*(V_{DD})^2/(2\pi^2R_L)$$
 (1)

It is critical that the maximum junction temperature  $T_{\rm JMAX}$  of 150°C is not exceeded.  $T_{\rm JMAX}$  can be determined from the power derating curves by using  $P_{\rm DMAX}$  and the PC board foil area. By adding additional copper foil, the thermal resistance of the application can be reduced from a free air value of 150°C/W, resulting in higher  $P_{\rm DMAX}$ . Additional copper foil can be added to any of the leads connected to the LM4889. It is especially effective when connected to  $V_{\rm DD}$ ,  $G_{\rm ND}$ , and the output pins. Refer to the application information on the LM4889 reference design board for an example of good heat sinking. If  $T_{\rm JMAX}$  still exceeds 150°C, then additional changes must be made. These changes can include re-

duced supply voltage, higher load impedance, or reduced ambient temperature. Internal power dissipation is a function of output power. Refer to the **Typical Performance Characteristics** curves for power dissipation information for different output powers and output loading.

### **POWER SUPPLY BYPASSING**

As with any amplifier, proper supply bypassing is critical for low noise performance and high power supply rejection. The capacitor location on both the bypass and power supply pins should be as close to the device as possible. Typical applications employ a 5V regulator with 10  $\mu F$  tantalum or electrolytic capacitor and a ceramic bypass capacitor which aid in supply stability. This does not eliminate the need for bypassing the supply nodes of the LM4889. The selection of a bypass capacitor, especially  $C_{\rm B}$ , is dependent upon PSRR requirements, click and pop performance (as explained in the section, **Proper Selection of External Components**), system cost, and size constraints.

#### SHUTDOWN FUNCTION

In order to reduce power consumption while not in use, the LM4889 contains a shutdown pin to externally turn off the amplifier's bias circuitry. This shutdown feature turns the amplifier off when a logic low is placed on the shutdown pin. By switching the shutdown pin to ground, the LM4889 supply current draw will be minimized in idle mode. While the device will be disabled with shutdown pin voltages less than  $0.5V_{\rm DC}$ , the idle current may be greater than the typical value of  $0.1\mu\rm A$ . (Idle current is measured with the shutdown pin grounded).

In many applications, a microcontroller or microprocessor output is used to control the shutdown circuitry to provide a quick, smooth transition into shutdown. Another solution is to use a single-pole, single-throw switch in conjunction with an external pull-up resistor. When the switch is closed, the shutdown pin is connected to ground and disables the amplifier. If the switch is open, then the external pull-up resistor will enable the LM4889. This scheme guarantees that the shutdown pin will not float thus preventing unwanted state changes.

#### PROPER SELECTION OF EXTERNAL COMPONENTS

Proper selection of external components in applications using integrated power amplifiers is critical to optimize device and system performance. While the LM4889 is tolerant of external component combinations, consideration to component values must be used to maximize overall system quality.

The LM4889 is unity-gain stable which gives the designer maximum system flexibility. The LM4889 should be used in low gain configurations to minimize THD+N values, and maximize the signal to noise ratio. Low gain configurations require large input signals to obtain a given output power. Input signals equal to or greater than 1 Vrms are available from sources such as audio codecs. Please refer to the section, **Audio Power Amplifier Design**, for a more complete explanation of proper gain selection.

Besides gain, one of the major considerations is the closed-loop bandwidth of the amplifier. To a large extent, the bandwidth is dictated by the choice of external components shown in *Figure 1*. The input coupling capacitor, C<sub>i</sub>, forms a first order high pass filter which limits low frequency response. This value should be chosen based on needed frequency response for a few reasons.

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#### SELECTION OF INPUT CAPACITOR SIZE

Large input capacitors are both expensive and space hungry for portable designs. Clearly, a certain sized capacitor is needed to couple in low frequencies without severe attenuation. But in many cases the speakers used in portable systems, whether internal or external, have little ability to reproduce signals below 100 Hz to 150 Hz. Thus, using a large input capacitor may not increase actual system performance.

In addition to system cost and size, click and pop performance is effected by the size of the input coupling capacitor,  $C_{\rm i}$  A larger input coupling capacitor requires more charge to reach its quiescent DC voltage (nominally 1/2  $V_{\rm DD}).$  This charge comes from the output via the feedback and is apt to create pops upon device enable. Thus, by minimizing the capacitor size based on necessary low frequency response, turn-on pops can be minimized.

Besides minimizing the input capacitor size, careful consideration should be paid to the bypass capacitor value. Bypass capacitor,  $C_{\rm B}$ , is the most critical component to minimize turn-on pops since it determines how fast the LM4889 turns on. The slower the LM4889's outputs ramp to their quiescent DC voltage (nominally 1/2  $V_{\rm DD}$ ), the smaller the turn-on pop. Choosing  $C_{\rm B}$  equal to 1.0  $\mu F$  along with a small value of  $C_{\rm i}$  (in the range of 0.1  $\mu F$  to 0.39  $\mu F$ ), should produce a virtually clickless and popless shutdown function. While the device will function properly, (no oscillations or motorboating), with  $C_{\rm B}$  equal to 0.1  $\mu F$ , the device will be much more susceptible to turn-on clicks and pops. Thus, a value of  $C_{\rm B}$  equal to 1.0  $\mu F$  is recommended in all but the most cost sensitive designs.

#### **AUDIO POWER AMPLIFIER DESIGN**

#### A 1W/8Ω AUDIO AMPLIFIER

Given:

Power Output 1 Wrms Load Impedance  $8\Omega$  Input Level 1 Vrms Input Impedance  $20 \text{ k}\Omega$  Bandwidth  $100 \text{ Hz}-20 \text{ kHz} \pm 0.25 \text{ dB}$ 

A designer must first determine the minimum supply rail to obtain the specified output power. By extrapolating from the Output Power vs Supply Voltage graphs in the **Typical Performance Characteristics** section, the supply rail can be easily found. A second way to determine the minimum supply rail is to calculate the required  $\rm V_{opeak}$  using Equation 2 and add the output voltage. Using this method, the minimum

supply voltage would be  $(V_{ODEAR} + (V_{ODTOP} + V_{ODBOT}))$ , where  $V_{ODBOT}$  and  $V_{ODTOP}$  are extrapolated from the Dropout Voltage vs Supply Voltage curve in the **Typical Performance Characteristics** section.

$$V_{\text{opeak}} = \sqrt{(2R_{L}P_{0})}$$
 (2)

5V is a standard voltage in most applications, it is chosen for the supply rail. Extra supply voltage creates headroom that allows the LM4889 to reproduce peaks in excess of 1W without producing audible distortion. At this time, the designer must make sure that the power supply choice along with the output impedance does not violate the conditions explained in the **Power Dissipation** section.

Once the power dissipation equations have been addressed, the required differential gain can be determined from Equation 3.

$$A_{VD} \ge \sqrt{(P_0 R_L)}/(V_{IN}) = V_{orms}/V_{inrms}$$
(3)

$$R_f/R_i = A_{VD}/2$$

From Equation 3, the minimum  $A_{VD}$  is 2.83; use  $A_{VD}$  = 3.

Since the desired input impedance was 20 k $\Omega$ , and with a A $_{VD}$  impedance of 2, a ratio of 1.5:1 of R $_{\rm f}$  to R $_{\rm i}$  results in an allocation of R $_{\rm i}$  = 20 k $\Omega$  and R $_{\rm f}$  = 30 k $\Omega$ . The final design step is to address the bandwidth requirements which must be stated as a pair of -3 dB frequency points. Five times away from a -3 dB point is 0.17 dB down from passband response which is better than the required ±0.25 dB specified.

$$f_L = 100 \text{ Hz/5} = 20 \text{ Hz}$$

$$f_H = 20 \text{ kHz} * 5 = 100 \text{ kHz}$$

As stated in the **External Components** section,  $R_i$  in conjunction with  $C_i$  create a highpass filter.

$$C_i \geq 1/(2\pi^*20~k\Omega^*20~Hz)$$
 = 0.397  $\mu F;$  use 0.39  $\mu F$ 

The high frequency pole is determined by the product of the desired frequency pole,  $f_{\rm H},$  and the differential gain,  $A_{\rm VD}.$  With a  $A_{\rm VD}=3$  and  $f_{\rm H}=100$  kHz, the resulting GBWP = 300kHz which is much smaller than the LM4889 GBWP of 2.5MHz. This calculation shows that if a designer has a need to design an amplifier with a higher differential gain, the LM4889 can still be used without running into bandwidth limitations.

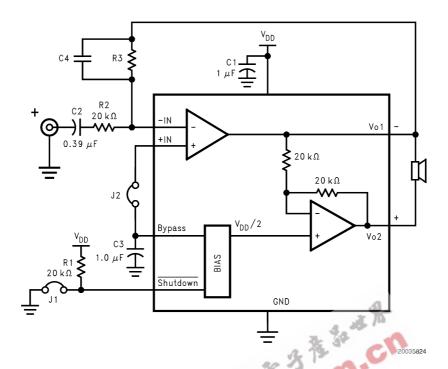


FIGURE 2. Higher Gain Audio Amplifier

The LM4889 is unity-gain stable and requires no external components besides gain-setting resistors, an input coupling capacitor, and proper supply bypassing in the typical application. However, if a closed-loop differential gain of greater than 10 is required, a feedback capacitor (C4) may be needed as shown in Figure 2 to bandwidth limit the amplifier. This feedback capacitor creates a low pass filter that elimi-

nates possible high frequency oscillations. Care should be taken when calculating the -3dB frequency in that an incorrect combination of  $\mathsf{R}_3$  and  $\mathsf{C}_4$  will cause rolloff before 20kHz. A typical combination of feedback resistor and capacitor that will not produce audio band high frequency rolloff is  $\mathsf{R}_3=20k\Omega$  and  $\mathsf{C}_4=25pf$ . These components result in a -3dB point of approximately 320kHz.

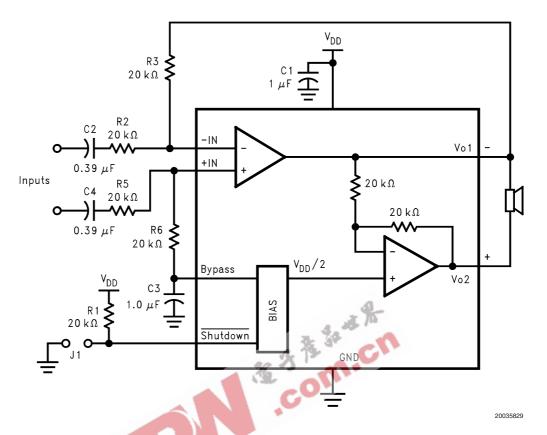


FIGURE 3. Differential Amplifier Configuration for LM4889

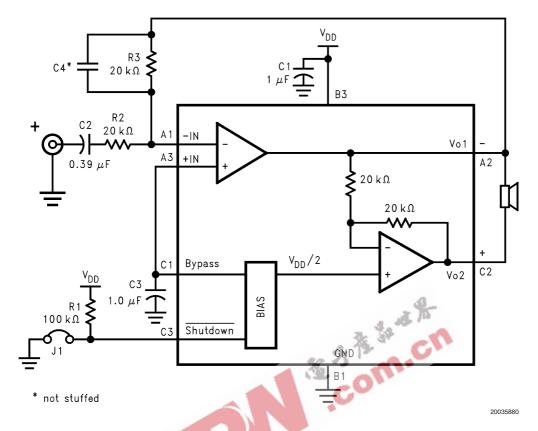
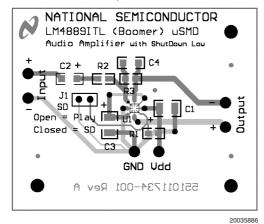


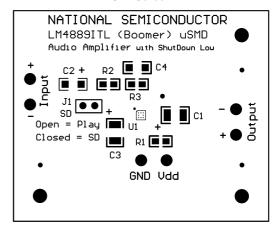
FIGURE 4. Reference Design Board and Layout - micro SMD

#### LM4889 micro SMD DEMO BOARD ARTWORK

#### **Composite View**

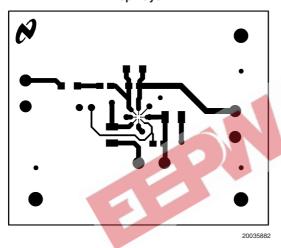


Silk Screen

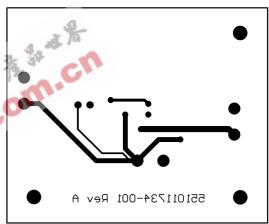


20035881

**Top Layer** 

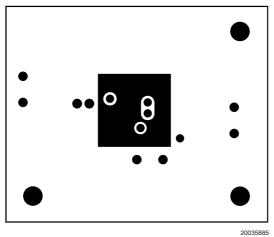


**Bottom Layer** 

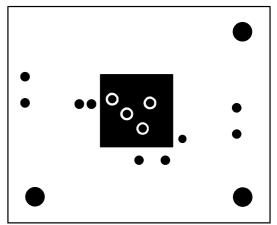


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Inner Layer Ground



Inner Layer V<sub>DD</sub>



20035884

REFERENCE DESIGN BOARD and PCB LAYOUT GUIDE-LINES - MSOP & SO Boards

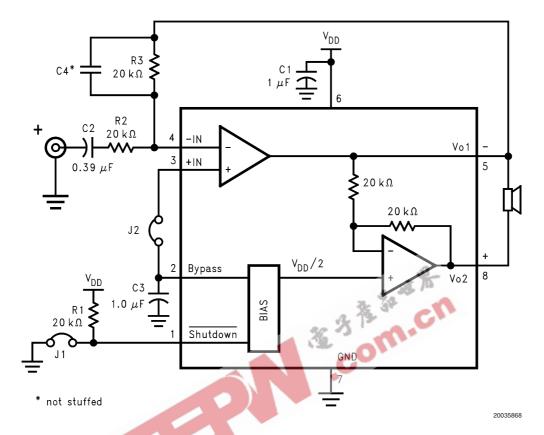
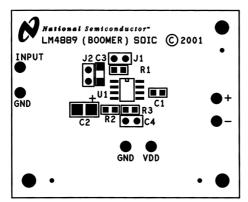


FIGURE 5. Reference Design Board

LM4889 SO DEMO BOARD ARTWORK

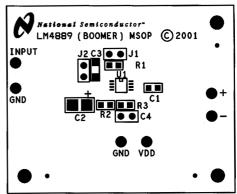
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20035876

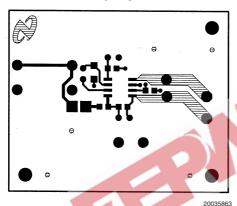
LM4889 MSOP DEMO BOARD ARTWORK

Silk Screen

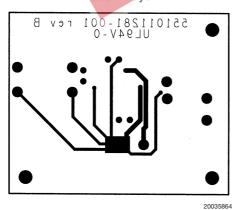


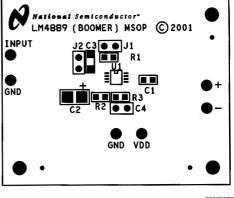
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Top Layer

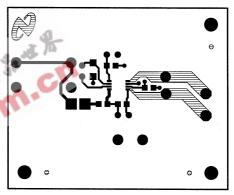


**Bottom Layer** 



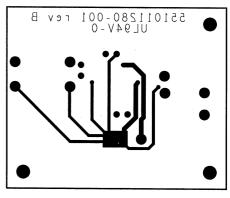


**Top Layer** 



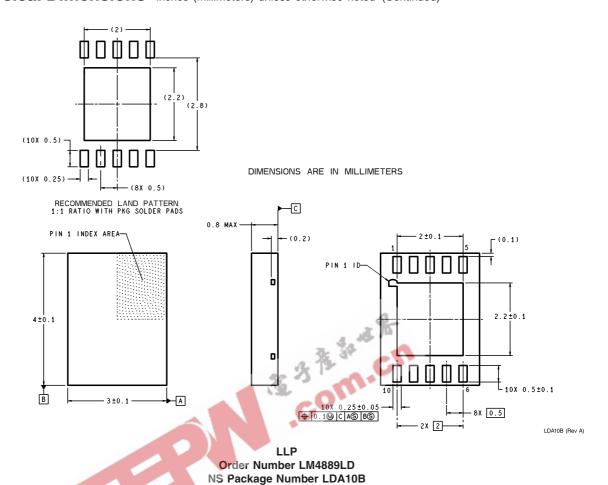
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**Bottom Layer** 



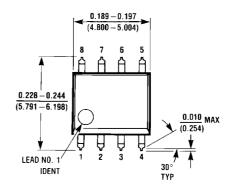
# Physical Dimensions inches (millimeters) unless otherwise noted 8x Ø 0.275 0.250 **DIMENSIONS ARE IN MILLIMETERS** (0.5)В LAND PATTERN RECOMMENDATION C → 0.125 0.050 TOP SIDE COATING-SYMM 0.5 BUMP A1 CORNER A SILICON TLA08XXX (Rev B) 8-Bump micro SMD Order Number LM4889ITL, LM4889ITLX В (.189 ) [4.8] .193±.006 [4.9±0.15] .118±.004 PIN 1 IDENT LAND PATTERN RECOMMENDATION 6X [.0256 [0.65] -GAGE PLANE R.005 TYP R.005 TYP [0.13] △ .004 [0.1] A .007±.002 TYP [0.18±0.05] .002-.006 [0.06-0.15] TYP SEATING PLANE ⊕ .002 [0.05] M BS CS (.0375 TYP: CONTROLLING DIMENSION IS INCH VALUES IN [ ] ARE MILLIMETERS MUA08A (Rev E) **MSOP** Order Number LM4889MM **NS Package Number MUA08A**

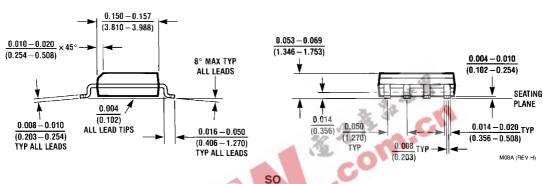
# Physical Dimensions inches (millimeters) unless otherwise noted (Continued)



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### Physical Dimensions inches (millimeters) unless otherwise noted (Continued)





Order Number LM4889MA NS Package Number M08A

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