FAIRCHILD

SEMICONDUCTOR

74F162A Synchronous Presettable BCD Decade Counter

General Description

The 74F162A is a high-speed synchronous decade counter operating in the BCD (8421) sequence. They are synchronously presettable for applications in programmable dividers. The F162A has a Synchronous Reset input that overrides counting and parallel loading and allows all outputs to be simultaneously reset on the rising edge of the clock. The F162A is a high speed version of the F162.

Features

Synchronous counting and loading

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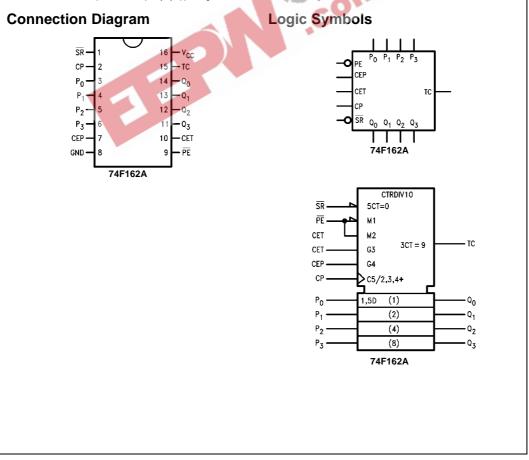
April 1988

Revised January 2004

- High-speed synchronous expansion
- Typical count rate of 120 MHz

Ordering Code:

Order Number	Package Number	Package Description	-
74F162ASC	M16A	16-Lead Small Outline Integrated Circuit (SOIC), JEDEC MS-012, 0.150" Narrow	
74F162APC	N16E	16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300" Wide	
Dovices also ovoilable	in Tana and Real Specify	by apponding the suffix lotter "Y" to the ordering code	-



Unit Loading/Fan Out

Pin Names		U.L.	Input I _{IH} /I _{IL}
	Description	HIGH/LOW	Output I _{OH} /I _{OL}
CEP	Count Enable Parallel Input	1.0/1.0	20 µA/–0.6 mA
CET	Count Enable Trickle Input	1.0/2.0	20 µA/–1.2 mA
СР	Clock Pulse Input (Active Rising Edge)	1.0/1.0	20 µA/–0.6 mA
SR	Synchronous Reset Input (Active LOW)	1.0/2.0	20 µA/–1.2 mA
P ₀ -P ₃	Parallel Data Inputs	1.0/1.0	20 µA/–0.6 mA
PE	Parallel Enable Input (Active LOW)	1.0/2.0	20 µA/–1.2 mA
Q ₀ –Q ₃	Flip-Flop Outputs	50/33.3	–1 mA/20 mA
тс	Terminal Count Output	50/33.3	–1 mA/20 mA

Functional Description

The 74F162A count modulo-10 in the BCD (8421) sequence. From state 9 (HLLH) they increment to state 0 (LLLL). The clock inputs of all flip-flops are driven in parallel through a clock buffer. Thus all changes of the Q outputs occur as a result of, and synchronous with, the LOW-to-HIGH transition of the CP input signal. The circuits have four fundamental modes of operation, in order of precedence: synchronous reset, parallel load, count-up and hold. Four control inputs- Synchronous Reset (SR), Parallel Enable (PE), Count Enable Parallel (CEP) and Count Enable Trickle (CET)-determine the mode of operation, as shown in the Mode Select Table. A LOW signal on SR overrides counting and parallel loading and allows all outputs to go LOW on the next rising edge of CP. A LOW signal on PE overrides counting and allows information on the Parallel Data (Pn) inputs to be loaded into the flip-flops on the next rising edge of CP. With PE and SR HIGH, CEP and CET permit counting when both are HIGH. Conversely, a LOW signal on either CEP or CET inhibits counting.

The F162A uses D-type edge-triggered flip-flops and changing the SR, PE, CEP and CET inputs when the CP is

Mode Select Table

	SR	PE	CET	CEP	Action on the Rising Clock Edge (∠─)
	L	Х	Х	Х	Reset (Clear)
	н	L	Х	Х	Load $(P_n \rightarrow Q_n)$
	н	н	н	н	Count (Increment)
	н	н	L	Х	No Change (Hold)
	н	н	Х	L	No Change (Hold)
н	= HIGH	Voltage	Level		

L = LOW Voltage Level

X = Immaterial

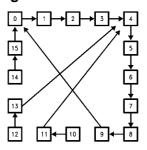
in either state does not cause errors, provided that the recommended setup and hold times, with respect to the rising edge of CP, are observed.

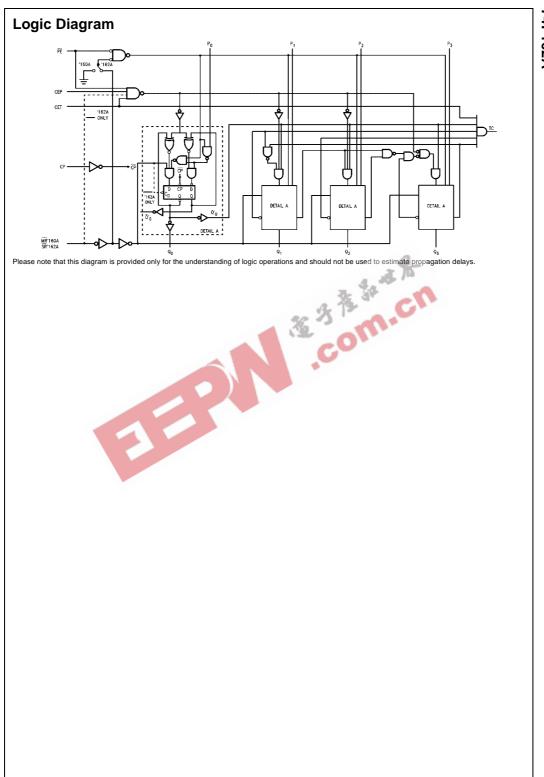
The Terminal Count (TC) output is HIGH when CET is HIGH and counter is in state 9. To implement synchronous multistage counters, the TC outputs can be used with the CEP and CET inputs in two different ways. Please refer to the F568 datasheet. The TC output is subject to decoding spikes due to internal race conditions and is therefore not recommended for use as a clock or asynchronous reset for flip-flops, counters or registers. In the F162A decade counters, the TC output is fully decoded and can only be HIGH in state 9. If a decade counter is preset to an illegal state, or assumes an illegal state when power is applied, it will return to the normal sequence within two counts, as shown in the State Diagram.

Logic Equations: Coun

unt Enable = CEP × CET × PE
TC =
$$Q_0 \times \overline{Q}_1 \times \overline{Q}_2 \times Q_3 \times CET$$

State Diagram





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Absolute Maximum Ratings(Note 1)

Storage Temperature	-65°C to +150°C
Ambient Temperature under Bias	$-55^{\circ}C$ to $+125^{\circ}C$
Junction Temperature under Bias	$-55^{\circ}C$ to $+150^{\circ}C$
$V_{CC} Pin Potential$ to Ground Pin	-0.5V to +7.0V
Input Voltage (Note 2)	-0.5V to +7.0V
Input Current (Note 2)	-30 mA to +5.0 mA
Voltage Applied to Output	
in HIGH State (with $V_{CC} = 0V$)	
Standard Output	-0.5V to V _{CC}
3-STATE Output	-0.5V to +5.5V
Current Applied to Output	
in LOW State (Max)	twice the rated I_{OL} (mA)
ESD Last Passing Voltage (Min)	4000V

Recommended Operating Conditions

Free Air Ambient Temperature Supply Voltage 0°C to +70°C +4.5V to +5.5V

Note 1: Absolute maximum ratings are values beyond which the device may be damaged or have its useful life impaired. Functional operation under these conditions is not implied.

Note 2: Either voltage limit or current limit is sufficient to protect inputs.

DC Electrical Characteristics

Symbol	mbol Parameter		Тур	Max	Units	Vcc	Conditions
V _{IH}	Input HIGH Voltage	2.0			V	a.	Recognized as a HIGH Signal
VIL	Input LOW Voltage			0.8	V		Recognized as a LOW Signal
V _{CD}	Input Clamp Diode Voltage			-1.2	V	Min	I _{IN} = -18 mA
V _{OH}	Output HIGH 10% V _{CC}	2.5		62	V	Min	$I_{OH} = -1 \text{ mA}$
	Voltage 5% V _{CC}	2.7			- Ó	IVIIII	$I_{OH} = -1 \text{ mA}$
V _{OL}	Output LOW 10% V _{CC}			0.5	V	Min	I _{OL} = 20 mA
	Voltage		1.1	0.5	V	IVIIII	10L - 20 IIIA
I _{IH}	Input HIGH			5.0	μA	Max	V _{IN} = 2.7V
	Current			0.0	μΛ	IVIAA	VIN - 2.7 V
I _{BVI}	Input HIGH Current			7.0	μA	Max	V _{IN} = 7.0V
	Breakdown Test			7.0	μΛ	IVIAA	VIN - 7.0V
ICEX	Output HIGH			50	μA	Max	$V_{OUT} = V_{CC}$
	Leakage Current			50	μΛ	IVIAA	001 - 000
V _{ID}	Input Leakage	4.75			V	0.0	I _{ID} = 1.9 μA
	Test	4.75			v	0.0	All Other Pins Grounded
I _{OD}	Output Leakage			3.75	μA	0.0	$V_{IOD} = 150 \text{ mV}$
	Circuit Current			0.70	μιτ	0.0	All Other Pins Grounded
IIL	Input LOW			-0.6	mA	Max	$V_{IN} = 0.5V (CP, CEP, P_n, \overline{MR} (F160A))$
	Current			-1.2	mA	Max	$V_{IN} = 0.5V \text{ (CET, } \overline{SR} \text{ (F162A), } \overline{PE} \text{)}$
l _{os}	Output Short-Circuit Current	-60		-150	mA	Max	$V_{OUT} = 0V$
I _{CC}	Power Supply Current		37	55	mA	Max	V _O = HIGH

AC Electrical Characteristics

Symbol	Parameter		T _A = +25°C V _{CC} = +5.0V C _L = 50 pF			$T_{A} = -55^{\circ}C \text{ to } +125^{\circ}C$ $V_{CC} = +5.0V$ $C_{1} = 50 \text{ pF}$		$T_{A} = 0^{\circ}C \text{ to } +70^{\circ}C$ $V_{CC} = +5.0V$ $C_{L} = 50 \text{ pF}$		
		Min	Тур	Max	Min	Max	Min	Max	l	
f _{MAX}	Maximum Count Frequency	90	120		75		80		MHz	
t _{PLH}	Propagation Delay, Count	3.5	5.5	7.5	3.5	9.0	3.5	8.5		
t _{PHL}	CP to Q _n (PE Input HIGH)	3.5	7.5	10.0	3.5	11.5	3.5	11.0	ns	
t _{PLH}	Propagation Delay, Load	4.0	6.0	8.5	4.0	10.0	4.0	9.5		
t _{PHL}	CP to Q _n (PE Input LOW)	4.0	6.0	8.5	4.0	10.0	4.0	9.5	ns	
t _{PLH}	Propagation Delay	5.0	10.0	14.0	5.0	16.5	5.0	15.0		
t _{PHL}	CP to TC	5.0	10.0	14.0	5.0	15.5	5.0	15.0	ns	
t _{PLH}	Propagation Delay	2.5	4.5	7.5	2.5	9.0	2.5	8.5		
t _{PHL}	CET to TC	2.5	4.5	7.5	2.5	9.0	2.5	8.5	ns	

AC Operating Requirements

Symbol	Parameter	T _A = +25°C V _{CC} = +5.0V		$T_A = -55^{\circ}C \text{ to } +125^{\circ}C$ $V_{CC} = +5.0V$	$T_{A} = 0^{\circ}C \text{ to } +70^{\circ}C$ $V_{CC} = +5.0V$	Units
Cymbol	i diamotor	Min Max		Min Max	Min_ Max	
t _S (H)	Setup Time, HIGH or LOW	5.0		A Star	5.0	
t _S (L)	P _n to CP	5.0		x -	5.0	
t _H (H)	Hold Time, HIGH or LOW	2.0	1	2.5	2.0	ns
t _H (L)	P _n to CP	2.0		2.5	2.0	
t _S (H)	Setup Time, HIGH or LOW	11.0		13.5	11.5	
t _S (L)	PE or SR to CP	8.5		10.5	9.5	
t _H (H)	Hold Time, HIGH or LOW	2.0		2.0	2.0	ns
t _H (L)	PE or SR to CP	0		0	0	
t _S (H)	Setup Time, HIGH or LOW	11.0	-	13.0	11.5	
t _S (L)	CEP or CET to CP	5.0	I	6.0	5.0	-
t _H (H)	Hold Time, HIGH or LOW	0		0	0	ns
t _H (L)	CEP or CET to CP	0	I	0	0	
t _W (H)	Clock Pulse Width (Load)	5.0		5.0	5.0	
t _W (L)	HIGH or LOW	5.0	I	5.0	5.0	ns
t _W (H)	Clock Pulse Width (Count)	4.0		5.0	4.0	
t _W (L)	HIGH or LOW	6.0	1	8.0	7.0	ns

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