

DATA SHEET

For a complete data sheet, please also download:

- The IC06 74HC/HCT/HCU/HCMOS Logic Family Specifications
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Information
- The IC06 74HC/HCT/HCU/HCMOS Logic Package Outlines

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74HC/HCT4516

Binary up/down counter

Product specification
File under Integrated Circuits, IC06

December 1990

Binary up/down counter

74HC/HCT4516

FEATURES

- Output capability: standard
- I_{CC} category: MSI

GENERAL DESCRIPTION

The 74HC/HCT4516 are high-speed Si-gate CMOS devices and are pin compatible with the “4516” of the “4000B” series. They are specified in compliance with JEDEC standard no. 7A.

The 74HC/HCT4516 are edge-triggered synchronous up/down 4-bit binary counters with a clock input (CP), an up/down count control input (UP/DN), an active LOW count enable input ($\overline{CE}$), an asynchronous active HIGH

parallel load input (PL), four parallel inputs (D₀ to D₃), four parallel outputs (Q₀ to Q₃), an active LOW terminal count output ($\overline{TC}$), and an overriding asynchronous master reset input (MR).

Information on D₀ to D₃ is loaded into the counter while PL is HIGH, independent of all other input conditions except the MR input, which must be LOW. When PL and $\overline{CE}$ are LOW, the counter changes on the LOW-to-HIGH transition of CP. UP/DN determines the direction of the count, HIGH for counting up, LOW for counting down. When counting up, $\overline{TC}$ is LOW when Q₀ to Q₃ are HIGH and $\overline{CE}$ is LOW. When counting down, $\overline{TC}$ is LOW when Q₀ to Q₃ and $\overline{CE}$ are LOW. A HIGH on MR resets the counter (Q₀ to Q₃ = LOW) independent of all other input conditions.

Logic equation for terminal count:

$$\overline{TC} = \overline{CE} \cdot \{(UP/DN) \cdot Q_0 \cdot Q_1 \cdot Q_2 \cdot Q_3 + (\overline{UP/DN}) \cdot \overline{Q_0} \cdot \overline{Q_1} \cdot \overline{Q_2} \cdot \overline{Q_3}\}$$

QUICK REFERENCE DATA

GND = 0 V; T_{amb} = 25 °C; t_r = t_f = 6 ns

SYMBOL	PARAMETER	CONDITIONS	TYPICAL		UNIT
			HC	HCT	
t _{PHL} /t _{PLH}	propagation delay CP to Q _n	C _L = 15 pF; V _{CC} = 5 V	19	19	ns
f _{max}	maximum clock frequency		45	57	MHz
C _I	input capacitance		3.5	3.5	pF
C _{PD}	power dissipation capacitance per package	notes 1 and 2	59	61	pF

Notes

1. C_{PD} is used to determine the dynamic power dissipation (P_D in μW):

$$P_D = C_{PD} \times V_{CC}^2 \times f_i + \sum (C_L \times V_{CC}^2 \times f_o) \text{ where:}$$

f_i = input frequency in MHz

f_o = output frequency in MHz

∑ (C_L × V_{CC}² × f_o) = sum of outputs

C_L = output load capacitance in pF

V_{CC} = supply voltage in V

2. For HC the condition is V_I = GND to V_{CC}
For HCT the condition is V_I = GND to V_{CC} – 1.5 V

ORDERING INFORMATION

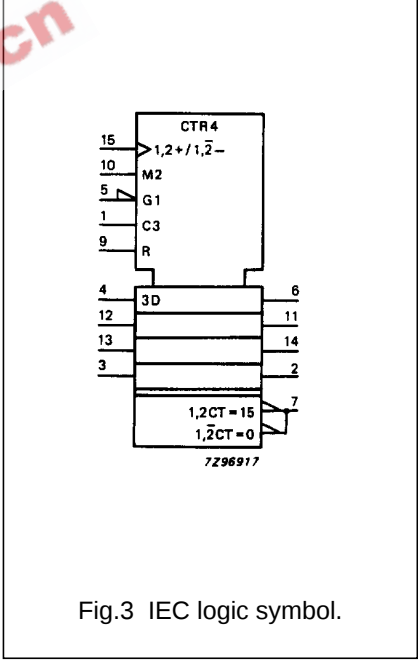
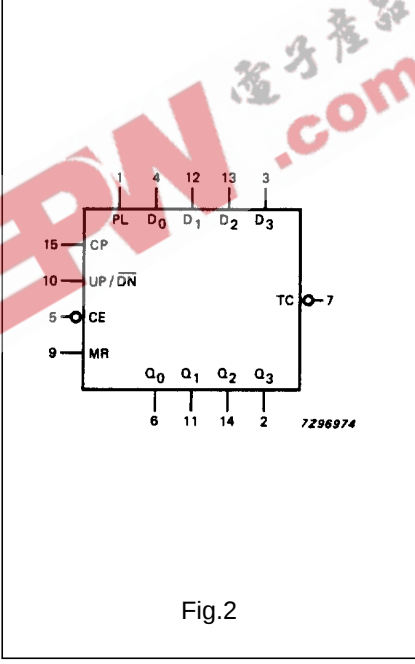
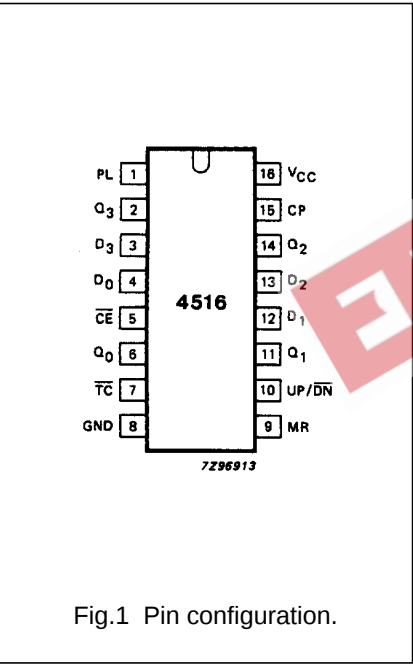
See “74HC/HCT/HCU/HCMOS Logic Package Information”.

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PIN DESCRIPTION

PIN NO.	SYMBOL	NAME AND FUNCTION
1	PL	parallel load input (active HIGH)
4, 12, 13, 3	D_0 to D_3	parallel inputs
5	$\overline{CE}$	count enable input (active LOW)
6, 11, 14, 2	Q_0 to Q_3	parallel outputs
7	$\overline{TC}$	terminal count output (active LOW)
8	GND	ground (0 V)
9	MR	asynchronous master reset input (active HIGH)
10	UP/ $\overline{DN}$	up/down control input
15	CP	clock input (LOW-to-HIGH, edge-triggered)
16	V_{CC}	positive supply voltage



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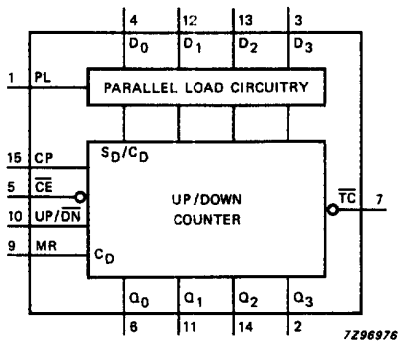


Fig.4 Functional diagram.

FUNCTION TABLE

MR	PL	UP/DN	$\overline{CE}$	CP	MODE
L	H	X	X	X	parallel load
L	L	X	H	X	no change
L	L	L	L	$\uparrow$	count down
L	L	H	L	$\uparrow$	count up
H	X	X	X	X	reset

Notes

- 1. H = HIGH voltage level
- L = LOW voltage level
- X = don't care
- $\uparrow$ = LOW-to-HIGH clock transition

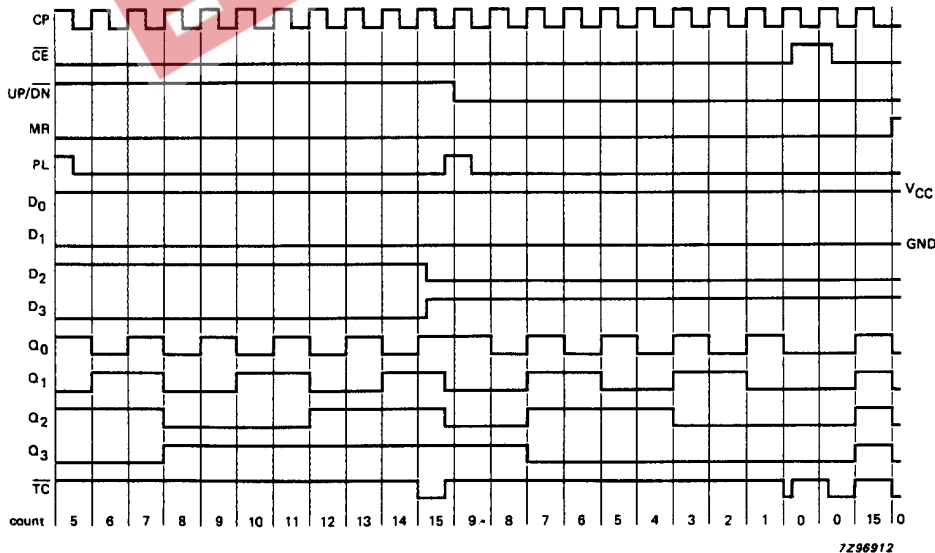


Fig.5 Timing diagram.

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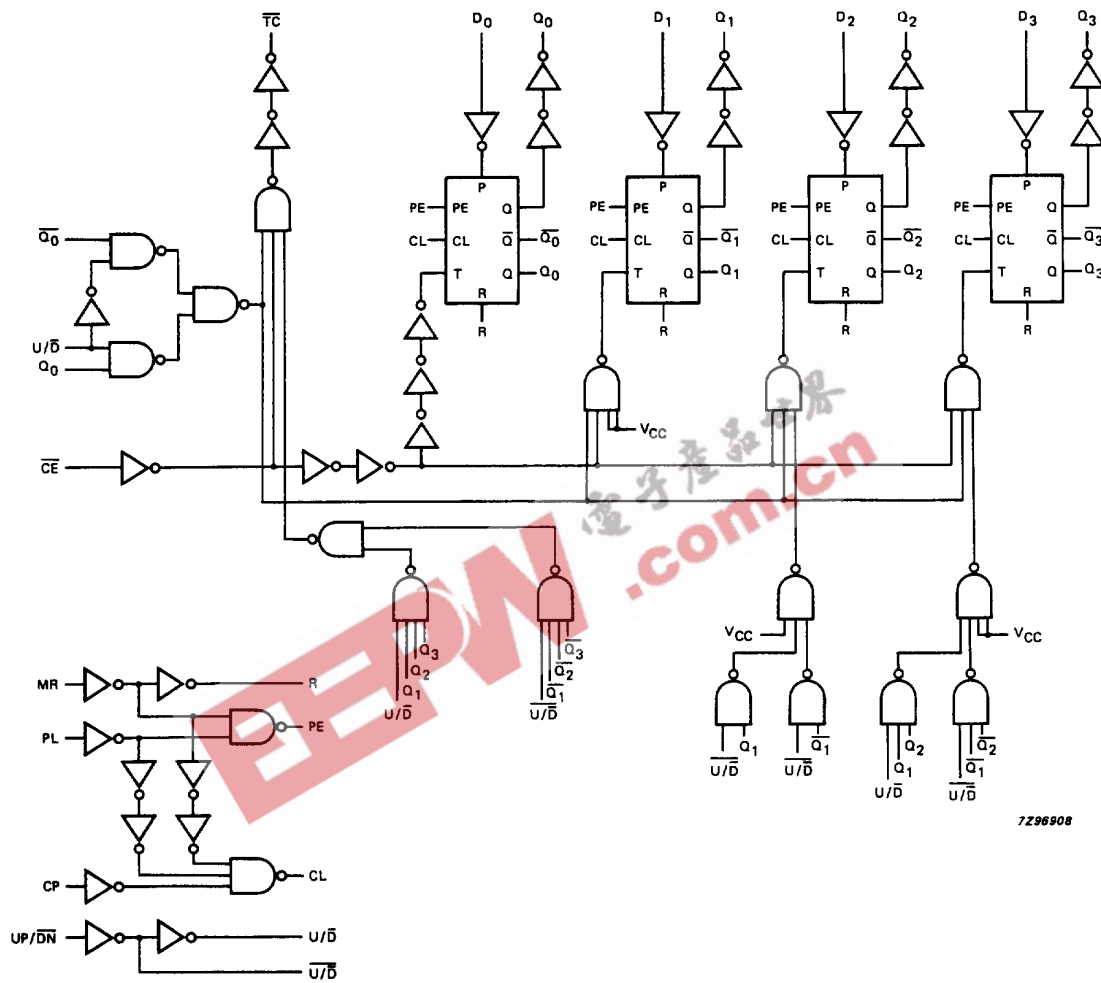


Fig.6 Logic diagram.

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DC CHARACTERISTICS FOR 74HC

For the DC characteristics see *"74HC/HCT/HCU/HCMOS Logic Family Specifications"*.

Output capability: standard

I_{CC} category: MSI

AC CHARACTERISTICS FOR 74HC

GND = 0 V; t_r = t_f = 6 ns; C_L = 50 pF

SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HC								V _{CC} (V)	WAVEFORMS
		+25			−40 to+85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t _{PHL} / t _{PLH}	propagation delay CP to Q _n		72 26 21	220 44 37		275 55 47		330 66 56	ns	2.0 4.5 6.0	Fig.7
t _{PHL}	propagation delay MR to Q _n		69 25 20	210 42 36		265 53 45		315 63 54	ns	2.0 4.5 6.0	Fig.10
t _{PLH} / t _{PHL}	propagation delay PL to Q _n		83 30 24	250 50 43		315 63 54		375 75 64	ns	2.0 4.5 6.0	Fig.9
t _{PHL} / t _{PLH}	propagation delay CP to $\overline{TC}$		74 27 22	260 52 44		325 65 55		395 78 66	ns	2.0 4.5 6.0	Fig.7
t _{PHL} / t _{PLH}	propagation delay $\overline{CE}$ to $\overline{TC}$		36 13 10	125 25 21		155 31 26		190 38 32	ns	2.0 4.5 6.0	Fig.8
t _{PLH}	propagation delay MR to $\overline{TC}$		69 25 20	235 47 40		295 59 50		355 71 60	ns	2.0 4.5 6.0	Fig.10
t _{PLH} / t _{PHL}	propagation delay PL to $\overline{TC}$		91 33 26	300 60 51		375 75 64		450 90 77	ns	2.0 4.5 6.0	Fig.9
t _{TLH} / t _{THL}	output transition time		19 7 6	75 15 13		95 19 16		110 22 19	ns	2.0 4.5 6.0	Fig.9
t _w	clock pulse width CP, $\overline{CE}$ HIGH or LOW	80 16 14	25 9 7		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.7
t _w	parallel load pulse width HIGH	80 16 14	28 10 8		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.10
t _w	master reset pulse width HIGH	80 16 14	19 7 6		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.10

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SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HC								V _{CC} (V)	WAVEFORMS
		+25			−40 to+85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t _{rem}	removal time MR to CP	80 16 14	28 10 8		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.10
t _{rem}	removal time PL to CP	80 16 14	25 9 7		100 20 17		120 24 20		ns	2.0 4.5 6.0	Fig.10
t _{su}	set-up time UP/DN to CP	100 20 17	30 11 9		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.8
t _{su}	set-up time CE to CP	100 20 17	19 7 6		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.8
t _{su}	set-up time D _n to PL	100 20 17	17 6 5		125 25 21		150 30 26		ns	2.0 4.5 6.0	Fig.11
t _h	hold time CE to CP	5 5 5	0 0 0		5 5 5		5 5 5		ns	2.0 4.5 6.0	Fig.8
t _h	hold time D _n to PL	3 3 3	−6 −2 −2		3 3 3		3 3 3		ns	2.0 4.5 6.0	Fig.11
t _h	hold time UP/DN to CP	0 0 0	−19 −7 −6		0 0 0		0 0 0		ns	2.0 4.5 6.0	Fig.8
f _{max}	maximum clock pulse frequency	6.0 30 35	16 49 58		4.8 24 28		4.0 20 24		MHz	2.0 4.5 6.0	Fig.7

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DC CHARACTERISTICS FOR 74HCT

For the DC characteristics see *"74HC/HCT/HCU/HCMOS Logic Family Specifications"*.

Output capability: standard

I_{CC} category: MSI

Note to HCT types

The value of additional quiescent supply current (ΔI_{CC}) for a unit load of 1 is given in the family specifications.

To determine ΔI_{CC} per input, multiply this value by the unit load coefficient shown in the table below.

INPUT	UNIT LOAD COEFFICIENT
D _n	0.75
PL, $\overline{CE}$	1.00
UP/DN	1.00
CP	1.25
MR	1.50

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AC CHARACTERISTICS FOR 74HCT

GND = 0 V; $t_r = t_f = 6$ ns; $C_L = 50$ pF

SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HCT								V _{CC} (V)	WAVEFORMS
		+25			−40 to +85		−40 to+125				
		min.	typ.	max.	min.	max.	min.	max.			
t _{PHL} / t _{PLH}	propagation delay CP to Q _n		28	50		63		75	ns	4.5	Fig.7
t _{PHL}	propagation delay MR to Q _n		24	42		53		63	ns	4.5	Fig.10
t _{PLH} / t _{PHL}	propagation delay PL to Q _n		32	53		66		80	ns	4.5	Fig.9
t _{PHL} / t _{PLH}	propagation delay CP to $\overline{TC}$		29	58		73		87	ns	4.5	Fig.7
t _{PHL} / t _{PLH}	propagation delay $\overline{CE}$ to $\overline{TC}$		18	31		39		47	ns	4.5	Fig.8
t _{PLH}	propagation delay MR to $\overline{TC}$		31	50		63		75	ns	4.5	Fig.10
t _{PLH} / t _{PHL}	propagation delay PL to $\overline{TC}$		34	68		85		102	ns	4.5	Fig.9
t _{TLH} / t _{THL}	output transition time		7	15		19		22	ns	4.5	Fig.9
t _w	clock pulse width CP, $\overline{CE}$ HIGH or LOW	16	9		20		24		ns	4.5	Fig.7
t _w	parallel load pulse width HIGH	16	8		20		24		ns	4.5	Fig.10
t _w	master rest pulse width HIGH	20	5		25		30		ns	4.5	Fig.10
t _{rem}	removal time MR to CP	23	14		29		35		ns	4.5	Fig.10
t _{rem}	removal time PL to CP	17	10		21		26		ns	4.5	Fig.10
t _{su}	set-up time UP/DN to CP	20	11		25		30		ns	4.5	Fig.8
t _{su}	set-up time $\overline{CE}$ to CP	20	9		25		30		ns	4.5	Fig.8
t _{su}	set-up time D _n to PL	20	9		25		30		ns	4.5	Fig.11
t _h	hold time $\overline{CE}$ to CP	10	9		13		15		ns	4.5	Fig.8

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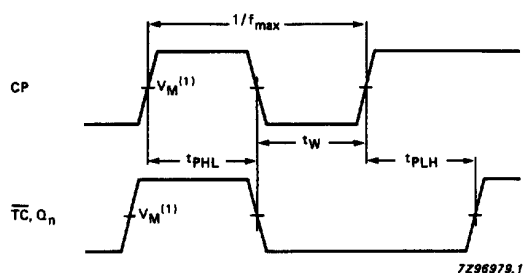
SYMBOL	PARAMETER	T _{amb} (°C)							UNIT	TEST CONDITIONS	
		74HCT								V _{CC} (V)	WAVEFORMS
		+25			−40 to +85		−40 to +125				
		min.	typ.	max.	min.	max.	min.	max.			
t _h	hold time D _n to PL	5	−6		5		5		ns	4.5	Fig.11
t _h	hold time UP/DN to CP	0	−5		0		0		ns	4.5	Fig.8
f _{max}	maximum clock pulse frequency	30	52		24		20		MHz	4.5	Fig.7

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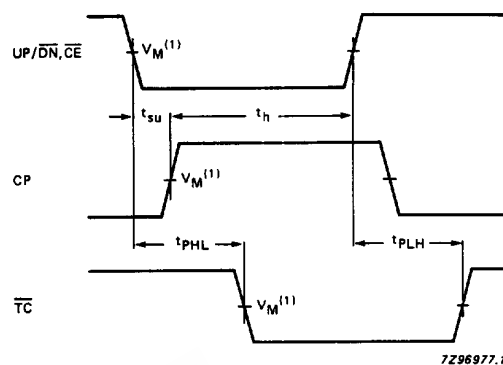
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AC WAVEFORMS



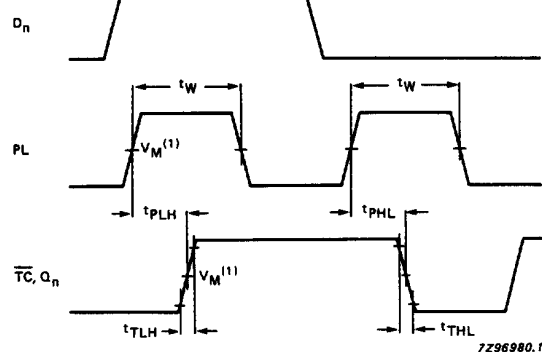
- (1) HC : $V_M = 50\%$; $V_I = \text{GND to } V_{CC}$.
HCT: $V_M = 1.3 \text{ V}$; $V_I = \text{GND to } 3 \text{ V}$.

Fig.7 Waveforms showing the clock (CP) to output (Q_n) and terminal count ($\overline{TC}$) propagation delays, the clock pulse width and the maximum clock pulse frequency.



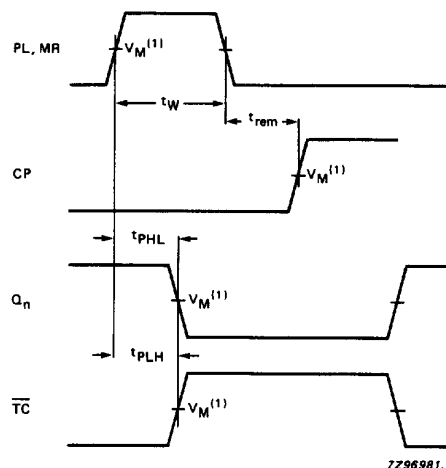
- (1) HC : $V_M = 50\%$; $V_I = \text{GND to } V_{CC}$.
HCT: $V_M = 1.3 \text{ V}$; $V_I = \text{GND to } 3 \text{ V}$.

Fig.8 Waveforms showing the set-up and hold times for count enable ($\overline{CE}$) and up/down ($\overline{UP/DN}$) control inputs to the clock pulse (CP), the propagation delays from UP/ $\overline{DN}$, $\overline{CE}$ to $\overline{TC}$.



- (1) HC : $V_M = 50\%$; $V_I = \text{GND to } V_{CC}$.
HCT: $V_M = 1.3 \text{ V}$; $V_I = \text{GND to } 3 \text{ V}$.

Fig.9 Waveforms showing the preset enable pulse width, preset enable to output delays and output transition times.



- (1) HC : $V_M = 50\%$; $V_I = \text{GND to } V_{CC}$.
HCT: $V_M = 1.3 \text{ V}$; $V_I = \text{GND to } 3 \text{ V}$.

Fig.10 Waveforms showing the master reset pulse, master reset to terminal count and Q_n delay and master reset to clock removal time.

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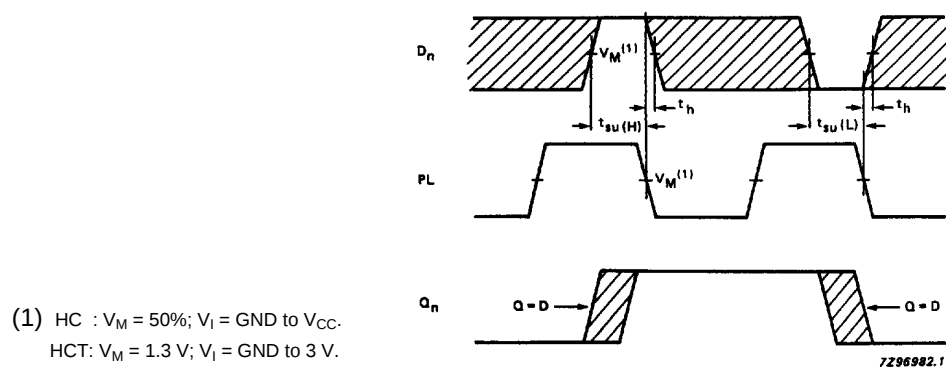


Fig.11 Waveforms showing the data set-up and hold times to parallel load (PL).

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Fig.12 Cascading counter packages (parallel clocking).

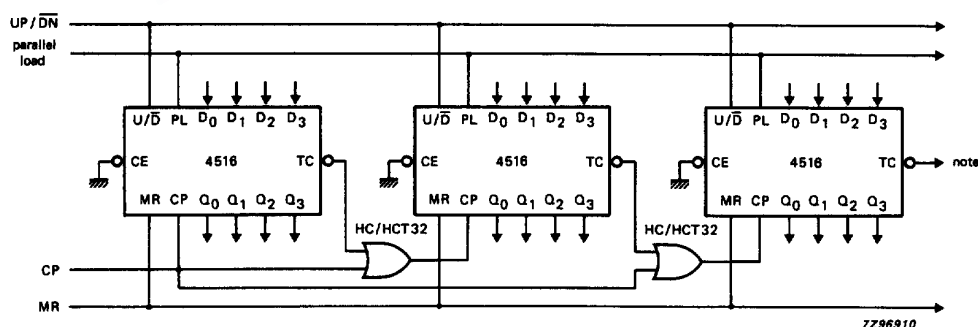


Fig.13 Cascading counter packages (ripple clocking).

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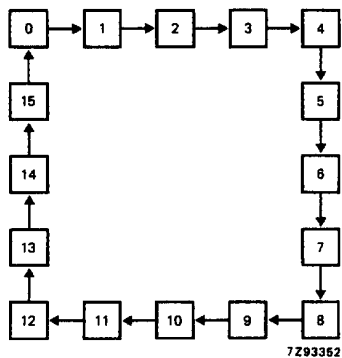
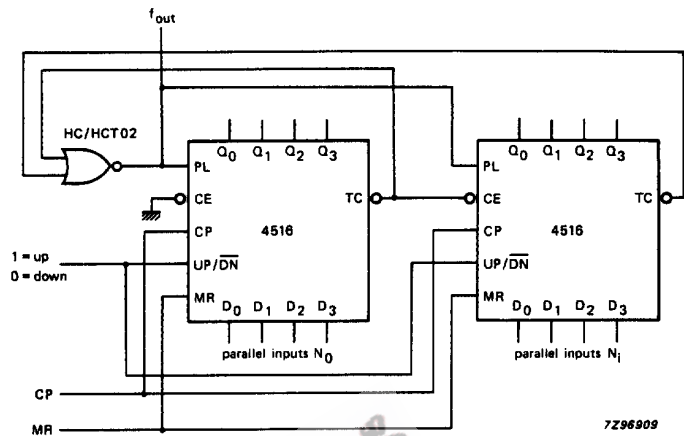


Fig.14 State diagram.



Use the following formulae to calculate N_{total} :

$$N_{total} = \left\{ \begin{matrix} i \\ 1 \end{matrix} \pi (16 \times N_i) \right\} + N_0$$
$$f_{out} = f_{in} / N_{total}$$

Fig.15 Programmable cascaded frequency divider.

PACKAGE OUTLINES

See "74HC/HCT/HCU/HCMOS Logic Package Outlines".

parallel inputs				count-up	count-down
D ₃	D ₂	D ₁	D ₀	n	n
0	0	0	0	15	(1)
0	0	0	1	14	1
0	0	1	0	13	2
0	0	1	1	12	3
0	1	0	0	11	4
0	1	0	1	10	5
0	1	1	0	9	6
0	1	1	1	8	7
1	0	0	0	7	8
1	0	0	1	6	9
1	0	1	0	5	10
1	0	1	1	4	11
1	1	0	0	3	12
1	1	0	1	2	13
1	1	1	0	1	14
1	1	1	1	(1)	15

Note

1. no count; f_{out} is HIGH.