[AK5393]

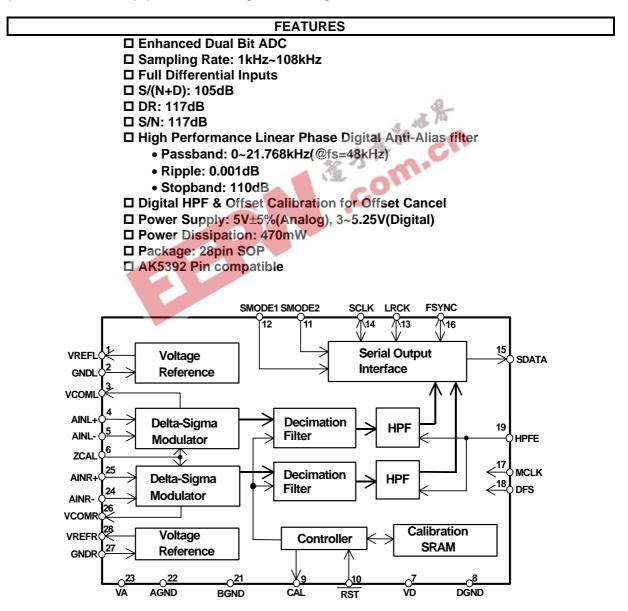


AK5393

Enhanced Dual Bit $\Delta\Sigma$ 96kHz 24-Bit ADC

GENERAL DESCRIPTION

The AK5393 is a 24bit, 128x oversampling 2ch A/D Converter for professional digital audio systems. The modulator in the AK5393 uses the new developed Enhanced Dual Bit architecture. This new architecture achieves the wide dynamic range, while keeping much the same superior distortion characteristics as conventional Single Bit way. The AK5393 performs 117dB dynamic range, so the device is suitable for professional studio equipment such as digital mixer, digital VTR etc.

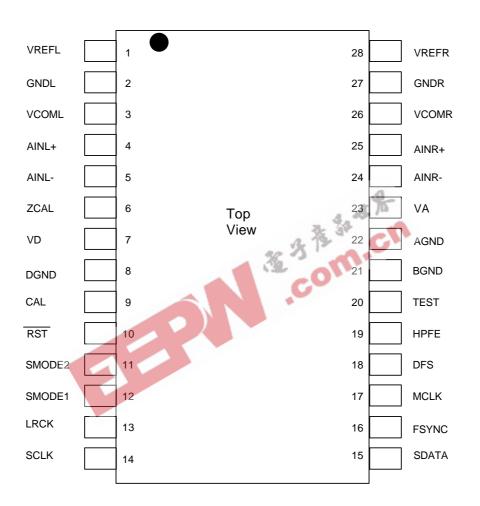


Ordering Guide

 AK5393-VS
 -10 ~ +70°C
 28pin SOP

 AKD5393
 AK5393 Evaluation Board

Pin Layout



■ Compatibility with AK5392

	AK5392	AK5393
Pin 18	CMODE	DFS
fs (max)	54kHz	108kHz
MCLK (DFS ="L"@fs=48kHz)	256fs/384fs	256fs
MCLK (DFS ="H"@fs=96kHz)	N/A	128fs

[AK5393]

			PIN/FUNCTION
No.	Pin Name	I/O	Function
1	VREFL	0	Lch Reference Voltage Pin, 3.75V
			Normally connected to GNDL with a 10µF electrolytic capacitor and
			a 0.1µF ceramic capacitor.
2	GNDL	-	Lch Reference Ground Pin, 0V
3	VCOML	0	Lch Common Voltage Pin, 2.75V
4	AINL+	Ι	Lch Analog positive input Pin
5	AINL-	Ι	Lch Analog negative input Pin
6	ZCAL	Ι	Zero Calibration Control Pin
			This pin controls the calibration reference signal.
			"L" :VCOML and VCOMR
			"H" : Analog Input Pins (AINL±, AINR±)
7	VD	-	Digital Power Supply Pin, 3.3V
8	DGND	-	Digital Ground Pin, 0V
9	CAL	0	Calibration Active Signal Pin
			"H" means the offset calibration cycle is in progress. Offset calibration starts when RST goes "H". CAL goes "L" after 8704 LRCK cycles for DFS="L",
			17408 LRCK cycles for DFS ="H".
10	RST	I	Reset Pin
10	K51	-	When "L", Digital section is powered-down. Upon returning "H", an
			offset calibration cycle is started. An offset calibration cycle should always
			be initiated after power-up.
11	SMODE2	Ι	Serial Interface Mode Select Pin
12	SMODE1	Ι	MSB first, 2's compliment.
			SMODE2 SMODE1 MODE LRCK
			L L Slave mode : MSB justified : H/L
			L H Master mode : Similar to I^2S : H/L
			H L Slave mode : I^2S : L/H
10	LDCK	1/0	H H Master mode : I^2S : L/H
13	LRCK	I/O	Left/Right Channel Select Clock Pin
			LRCK goes "H" at SMODE2="L" and "L" at SMODE2="H" during reset when SMODE1 "H".

14	SCLK	I/O	Serial Data Clock Pin
			Data is clocked out on the falling edge of SCLK.
			Slave mode:
			SCLK requires more than 48fs clock.
			Master mode:
			SCLK outputs a 128fs(DFS="L") or 64fs(DFS="H") clock.
			SCLK stays "L" during reset.
15	SDATA	Ο	Serial Data Output Pin
			MSB first, 2's complement. SDATA stays "L" during reset.
16	FSYNC	I/O	Frame Synchronization Signal Pin
			Slave mode:
			When "H", the data bits are clocked out on SDATA. In I ² S mode, FSYNC is
			don't care.
			Master mode:
			FSYNC outputs 2fs clock. FSYNC stays "L" during reset.
17	MCLK	Ι	Master Clock Input Pin
			256fs at DFS="L", 128fs at DFS="H".
18	DFS	Ι	Double Speed Sampling Mode Pin "L": Normal Speed "H": Double Speed High Pass Filter Enable Pin "L": Disable "H": Enable Test Pin (pull-down pin) Should be connected to GND.
			"L": Normal Speed
			"H": Double Speed
19	HPFE	Ι	High Pass Filter Enable Pin
			"L": Disable
			"H": Enable
20	TEST	Ι	Test Pin (pull-down pin)
			Should be connected to GND.
21	BGND	_	Substrate Ground Pin, 0V
22	AGND		Analog Ground Pin, 0V
23	VA		Analog Supply Pin, 5V
24	AINR-	I	Rch Analog negative input Pin
25	AINR+	Ι	Rch Analog positive input Pin
26	VCOMR	0	Rch Common Voltage Pin, 2.75V
27	GNDR	-	Rch Reference Ground Pin, 0V
28	VREFR	0	Rch Reference Voltage Pin, 3.75V
			Normally connected to GNDR with a $10\mu F$ electrolytic capacitor and a $0.1\mu F$
			ceramic capacitor

Note: All digital inputs should not be left floating.

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Symbol	min	max	Units
VA	-0.3	6.0	V
VD	-0.3	6.0	V
ΔGND	-	0.3	V
IIN	-	±10	mA
VINA	-0.3	VA+0.3	V
VIND	-0.3	VD+0.3	V
Та	-10	70	°C
Tstg	-65	150	°C
	VA VD ΔGND IIN VINA VIND Ta	VA -0.3 VD -0.3 ΔGND - IIN - VINA -0.3 VIND -0.3 Ta -10	VA -0.3 6.0 VD -0.3 6.0 ΔGND - 0.3 IIN - ±10 VINA -0.3 VA+0.3 VIND -0.3 VD+0.3 Ta -10 70

Notes: 1. All voltages with respect to ground.

2. AGND, BGND and DGND must be connected to the same analog ground plane.

WARNING: Operation at or beyond these limits may result in permanent damage to the device. Normal operation is not guaranteed at these extremes.

			- 8-		
RECOMME	NDED OPERA	TING COND	TIONS		
(AGND,BGND,DGND=0V; Note 1)		2 3	C		
Parameter	Symbol	🖌 min 🧹	typ	max	Units
Power Supplies: Analog	VA	4.75	5.0	5.25	V
(Note 3) Digital	VD	3.0	3.3	5.25	V

Notes: 1. All voltages with respect to ground.

3. The power up sequence between VA and VD is not critical.

* AKM assumes no responsibility for the usage beyond the conditions in this data sheet.

		ANALOG (CHARACTE	RISTICS		
(Ta=25°C; VA	A=5.0V; VD=3.3V; A	AGND,BGND,D	GND=0V; fs=	48kHz; Signa	l Frequency=	1kHz;
24bit Output;	Measurement freque	ncy=10Hz~20kH	Iz; unless othe	erwise specifi	ed)	
Parameter			min	typ	max	Units
Resolution				24	Bits	
Analog Input C	haracteristics:					
S/(N+D)	fs=48kHz	-1dBFS	98	105		dB
		-20dBFS	-	94		dB
		-60dBFS	-	54		dB
	fs=96kHz	-1dBFS	96	103		dB
	BW=40kHz	-20dBFS	-	85		dB
		-60dBFS	-	45		dB
Dynamic Range	(-60dBFS with A-W	Veighted)	112	117		dB
S/N (A-Weighted)		112	117		dB	
Interchannel Isolation		110	120		dB	
Interchannel Gain Mismatch			0.1	0.5	dB	
Gain Drift	1				150	ppm/°C
Offset Error	after calibration, HI	PF=OFF		±200	±1000	LSB ₂₄
	after calibration, HI	PF=ON		±1	-	LSB ₂₄
Offset Drift	(HI	PF=OFF)		±10	C.	LSB ₂₄ /°C
Offset Calibratio	on Range (H	PF=OFF)		±50		mV
Input Voltage	(AIN+)-(AIN-)		±2.3	±2.45	±2.6	V
Input Impedance	2		2.4	4		kΩ
Power Supplies						
Power Supply C	urrent					
VA				90	130	mA
VD (f	fs=48kHz; DFS="L"))		6	9	mA
(f	s=96kHz; DFS="H")			9	14	mA
Power Dissipation	on			470	680	mW
Power Supply Re	ejection (Note 4))		70		dB

Note: 4. DC to 26kHz. 110dB(typ) beyond 26kHz.

FILTER CHARACTERISTICS(fs=48kHz) (Ta=25°C; VA=5.0V±5%; VD=3.0~5.25V; fs=48kHz, DFS="L") Parameter Symbol min max Units typ ADC Digital Filter(Decimation LPF): Passband (Note 5) PB 0 21.768 kHz Stopband 26.232 (Note 5) SB kHz Passband Ripple PR ±0.001 dB Stopband Attenuation SA 110 dB (Note 6) Group Delay Distortion ΔGD 0 us (Note 7) 38.7 Group Delay GD 1/fs **ADC Digital Filter(HPF):** Frequency response (Note 5) -3dB FR 1.0 Hz -0.1dB 6.5 Hz

	FILTER CH	ARACTE	RISTICS(fs=9	6kHz)		
(Ta=25°C; VA=5.0V±59	%; VD=3.0~5.25V; fs=	=96kHz, Dl	FS="H")	A		
Parameter		Symbol	min	typ	max	Units
ADC Digital Filter(Decin	nation LPF):		弦	34 _ (
Passband	(Note 5)	PB	0		43.536	kHz
Stopband	(Note 5)	SB	52.464			kHz
Passband Ripple		PR	C		±0.003	dB
Stopband Attenuation	(Note 8)	SA	110			dB
Group Delay Distortion		ΔGD		0		us
Group Delay	(Note 7)	GD		38.8		1/fs
ADC Digital Filter(HPF)						
Frequency response (N	lote 5) -3dB	FR		2.0		Hz
-	-0.1dB			13.0		Hz

Notes: 5. The passband and stopband frequencies scale with fs.

- 6. The analog modulator samples the input at 6.144MHz for an output word rate of 48kHz. There is no rejection of input signals which are multiples of the sampling frequency (that is: there is no rejection for n x 6.144MHz \pm 21.768kHz, where n=1,2,3...).
- 7. The calculating delay time which occurred by digital filtering. This time is from the input of analog signal to setting the 24bit data of both channels to the output register. 40.7/fs(DFS="L"),40.8/fs(DFS="H")typ. at HPF:ON.
- 8. The analog modulator samples the input at 6.144MHz for an output word rate of 96kHz. There is no rejection of input signals which are multiples of the sampling frequency (that is: there is no rejection for n x 6.144MHz \pm 43.536kHz, where n=1,2,3...).

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DIGITAL CHARACTERISTICS							
(Ta=25°C; VA=5.0V±5%; VD=3.0 ~ 5.25V)							
Parameter	Symbol	min	typ	max	Units		
High-Level Input Voltage	VIH	70%VD	-	-	V		
Low-Level Input Voltage	VIL	-	-	30% VD	V		
High-Level Output Voltage Iout=-20µA	VOH	VD-0.1	-	-	V		
Low-Level Output Voltage Iout=20µA	VOL	-		0.1	V		
Input Leakage Current	Iin	_	-	±10	μA		

SWITCHING CHARACTERISTICS

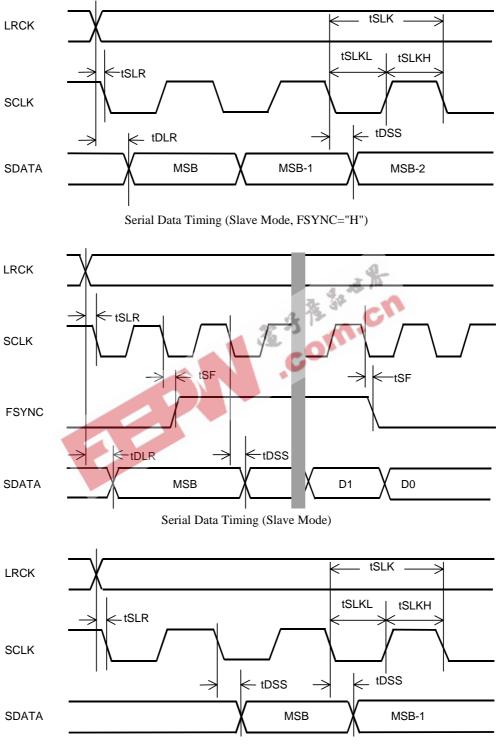
(Ta=25°C; VA=5.0V±5%; VD=3.0 ~ 5.25V; C _L =20pF	7)				
Parameter	Symbol	min	typ	max	Units
Control Clock Frequency					
Master Clock 256fs:	fCLK	0.256	12.288	13.824	MHz
Pulse width Low	tCLKL	29			ns
Pulse width High	tCLKH	29			ns
Serial Data Output Clock (SCLK)	fSLK		6.144	6.912	MHz
Channel Select Clock (LRCK)	fs	1	48	108	kHz
duty cycle		25		75	%
Serial Interface Timing (Note 9)		R 12	G		
Slave Mode(SMODE1="L")					
SCLK Period	tSLK	144.7			ns
SCLK Pulse width Low	tSLKL	65			ns
Pulse width High	tSLKH	65			ns
SCLK falling to LRCK Edge (Note 10)	tSLR	-45		45	ns
LRCK Edge to SDATA MSB Valid	tDLR			45	ns
SCLK falling to SDATA Valid	tDSS			45	ns
SCLK falling to FSYNC Edge	tSF	-45		45	ns
Master Mode(SMODE1="H")					
SCLK Frequency (DFS="L")	fSLK		128fs		Hz
SCLK Frequency (DFS="H")	fSLK		64fs		Hz
duty cycle			50		%
FSYNC Frequency	fFSYNC		2fs		Hz
duty cycle			50		%
SCLK falling to LRCK Edge	tSLR	-20		20	ns
LRCK Edge to FSYNC rising	tLRF		1		tslk
SCLK falling to SDATA Valid	tDSS			45	ns
SCLK falling to FSYNC Edge	tSF	-20		20	ns
Reset/Calibration timing					
RST Pulse width	tRTW	150			ns
RST falling to CAL rising	tRCR			50	ns
RST rising to CAL falling (Note 11)	tRCF		8704		1/fs
RST rising to SDATA Valid (Note 11)	tRTV		8960		1/fs

Notes: 9. Refer to Serial Data interface.

10. Specified LRCK edges not to coincide with the rising edges of SCLK.

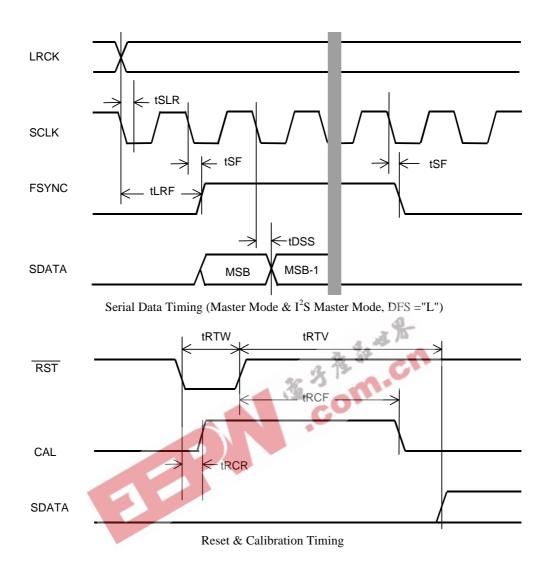
11. The number of the LRCK rising edges after RST brought high at DFS="L". The value is in master mode. In slave mode it becomes one LRCK clock(1/fs) longer. When DFS="H", tRCF=17408 and tRTV=17920.

Timing Diagram



Serial Data Timing (I²S Slave Mode, FSYNC = Don't Care)

[AK5393]



OPERATION OVERVIEW

System Clock Input

The external clocks which are required to operate the AK5393 are MCLK, LRCK(fs), SCLK. MCLK should be synchronized with LRCK but the phase is free of care. MCLK should be 256fs in normal sampling mode(DFS="L") and double sampling mode needs 128fs as MCLK. Table 2 illustrates standard audio word rates and corresponding frequencies used in the AK5393.

As the AK5393 includes the phase detect circuit for LRCK, the AK5393 is reset automatically when the synchronization is out of phase by changing the clock frequencies. Therefore, the reset is only needed for power-up.

All external clocks must be present unless $\overline{RST} = "L"$, otherwise excessive current may result from abnormal operation of internal dynamic logic.

Speed		Normal(DFS	Normal(DFS ="L")		DFS ="H")
LRCK	(max)	54kHz		108kHz	
SCLK		~128fs		~	64fs
MCLK		256fs		128fs	
	fs	Table 1. System	2	CLK	cn
	32.0kHz	8.1920MHz		60MHz	
	44.1kHz	11.2896MHz	5.64	48MHz	
	48.0kHz	12.2880MHz	6.14	40MHz	
	96.0kHz	12.2880MHz	6.1440MHz		
	Table 2. E	xamples of System	n Clock I	Frequency	

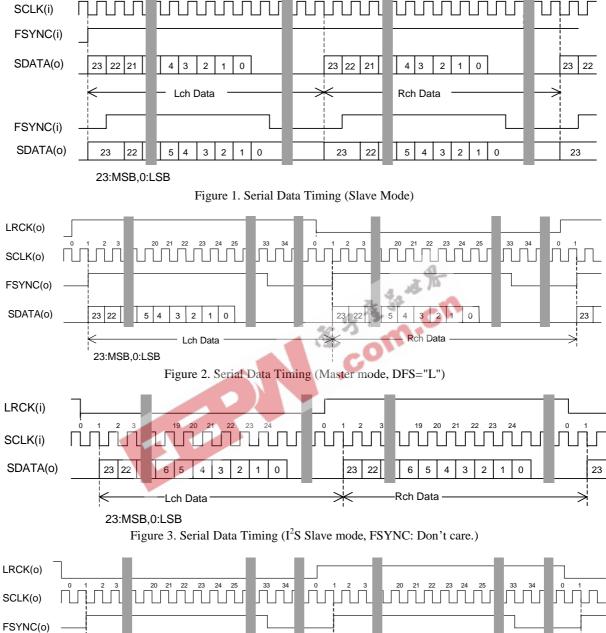
Serial Data Interface

The AK5393 supports four serial data formats which can be selected via SMODE1 and SMODE2 pins(Table 3). The data format is MSB-first, 2's complement.

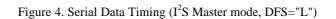
Figure	SMODE2	SMODE1	Mode	LRCK
Figure 1	L	L	Slave Mode	Lch = H, Rch = L
Figure 2	L	Н	Master Mode	Lch =H, Rch =L
Figure 3	Н	L	I ² S Slave Mode	Lch =L, Rch =H
Figure 4	Н	Н	I ² S Master Mode	Lch =L, Rch =H

Table 3. Serial I/F Format

21 22 22 23 תתתת



SDATA(o) 23 22 0 23 22 5 4 3 5 4 3 2 1 2 0 1 Rch Data Lch Data



23:MSB,0:LSB

ASAHI KASEI

LRCK(i)

23

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Offset Calibration

When RST pin goes to "L", the digital section is powered-down. Upon returning "H", an offset calibration cycle is started. An offset calibration cycle should always be initiated after power-up.

During the offset calibration cycle, the digital section of the part measures and stores the values of calibration input of each channel in registers. The calibration input value is subtracted from all future outputs. The calibration input may be obtained from either the analog input pins (AIN+/-) or the VCOM pins depending on the state of the ZCAL pin. With ZCAL "H", the analog input pin voltages are measured, and with ZCAL "L", the VCOM pin voltages are measured. The CAL output is "H" during calibration.

Digital High Pass Filter

The AK5393 also has a digital high pass filter for DC offset cancel. The cut-off frequency of the HPF is 1Hz at fs=48kHz and also scales with sampling rate(fs).



SYSTEM DESIGN

Figure 5 and 6 show the system connection diagram. An evaluation board[AKD5393] is available which demonstrates the optimum layout, power supply arrangements and measurement results.

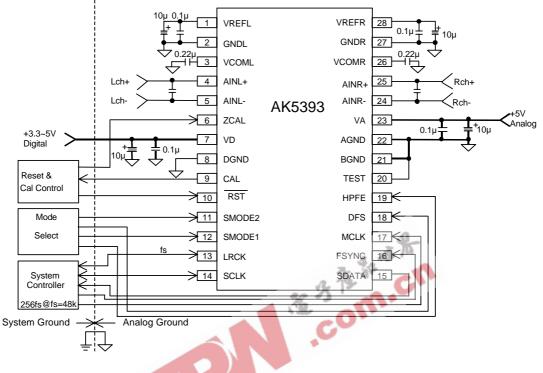


Figure 5. Typical Connection Diagram

Notes:

- LRCK = fs, SCLK=64fs.
- Power lines of VA and VD should be distributed separately from the point with low impedance of regulator etc.
- GND, BGND and DGND must be connected to the same analog ground plane.
- All input pins except pull-down/pull-up pins should not be left floating.

Digita	Il Ground	Analog Grour	nd			
		1	VREFL		VREFR	28
		2	GNDL		GNDR	27
[3	VCOML		VCOMR	26
		4	AINL+		AINR+	25
	System	5	AINL-	AK5393	AINR-	24
		6	ZCAL	/	VA	23
	Controller	7	VD		AGND	22
		8	DGND		BGND	21
		9	CAL		TEST	20
l		10	RST		HPFE	19
		11	SMODE2		DFS	18
		12	SMODE1		MCLK	17
		13	LRCK		FSYNC	16
		14	SCLK		SDATA	15

Figure 6 Ground layout

1. Grounding and Power Supply Decoupling

The AK5393 requires careful attention to power supply and grounding arrangements. Analog ground and digital ground should be separate and connected together near to where the supplies are brought onto the printed circuit board. Decoupling capacitors should be as near to the AK5393 as possible, with the small value ceramic capacitor being the nearest.

2. On-chip voltage reference and VCOM

The reference voltage for A/D converter is a differential voltage between the VREFL/R output voltage and the GNDL/R input voltage. The GNDL/R are connected to AGND and a 10uF electrolytic capacitor parallel with a 0.1uF ceramic capacitor between the VREFL/R and the GNDL/R eliminate the effects of high frequency noise. Especially a ceramic capacitor should be as near to the pins as possible. And all digital signals, especially clocks, should be kept away from the VREFL/R pins in order to avoid unwanted coupling into the AK5393. No load current may be taken from the VREFL/R pins.

VCOM is a common voltage of the analog signal. In order to eliminate the effects of high frequency noise, a 0.22µF ceramic capacitor should be connected as near to the VCOM pin as possible. And all signals, especially clocks, should be kept away from the VCOM pin in order to avoid unwanted coupling into the AK5393. No load current may be drawn from the VCOM pin.

3. Analog Inputs

Analog signal is differentially input into the modulator via the AIN+ and the AIN- pins. The input voltage is the difference between AIN+ and AIN- pins. The full-scale of each pin is nominally ± 2.45 Vpp(typ). The AK5393 can accept input voltages from AGND to VA. The ADC output data format is 2's complement. The output code is 7FFFFH(@24bit) for input above a positive full scale and 800000H(@24bit) for input below a negative full scale. The ideal code is 000000H (@24bit) with no input signal. The DC offset is removed by the offset calibration.

The AK5393 samples the analog inputs at 128fs(6.144MHz @fs=48kHz,DFS="L"). The digital filter rejects noise above the stop band except for multiples of 128fs. A simple RC filter may be used to attenuate any noise around 128fs and most audio signals do not have significant energy at 128fs.

The AK5393 accepts +5V supply voltage. Any voltage which exceeds the upper limit of VA+0.3V and lower limit of AGND-0.3V and any current beyond 10mA for the analog input pins(AIN+ /-) should be avoided. Excessive currents to the input pins may damage the device. Hence input pins must be protected from signals at or beyond these limits. Use caution specially in case of using $\pm 15V$ in other analog circuits.

Figure 7shows an input buffer circuit example 1. This is a full-differential input buffer circuit with an inverted-amp (gain :-10dB). The capacitor of 10nF between AIN+ /- decreases the clock feed through noise of modulator, and composes a 1st order LPF(fc=360kHz) with 220hm resistor before the capacitor. This circuit also has a 1st order LPF(fc=370kHz) composed of op-amp. In this example, the internal offset is removed by self calibration. The evaluation board should be referred about the detail.

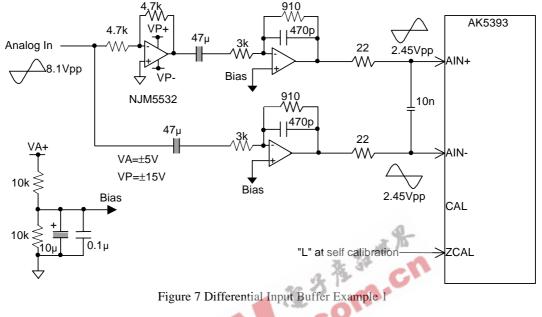


Figure 8 shows an input buffer circuit example 2. (1st order HPF; fc=0.66Hz, Table 4, 1st order LPF; fc=590kHz, gain=-14dB, Table 5). The analog signal is able to input through XLR or BNC connectors. (short JP1 and JP2 for BNC input, open JP1 and JP2 for XLR input). The input level of this circuit is +/-12.4Vpp (AK5393: +/-2.45Vpp Typ.).

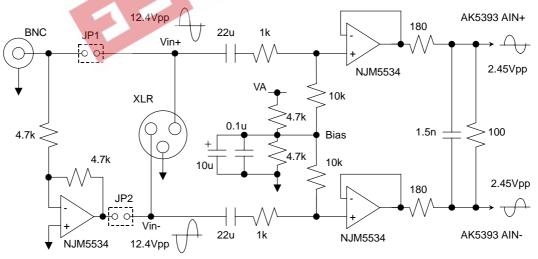
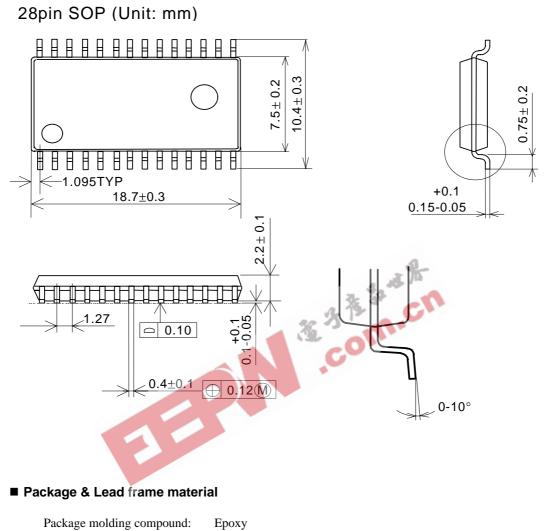


Figure 8 Differential Input Buffer Example 2

	fin	1H	Hz 1	0Hz
	Frequency Response		6dB -0	.02dB
Table 4. Frequency Response of HPF				
	fin	20kHz	40kHz	6.144MHz
Freq	uency Response	-0.005dB	-0.02dB	-15.6dB
Table 5 Frequency Destronce of LDE				

Table 5. Frequency Response of LPF

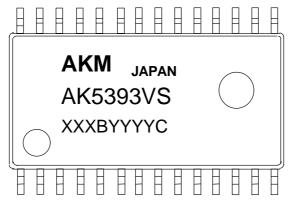
PACKAGE



Lead frame surface treatment: So

Cu Solder plate

MARKING



Contents of XXXBYYYYC

XXXB: Lot # (X : numbers, B : alphabet) YYYYC: Data Code (Y : numbers, C : alphabet) いろう きっせん

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