SONY

CXA3010Q

Read/Write Amplifier (with Built-in Filters) for FDDs

Description

The CXA3010Q is a monolithic IC designed for use with three-mode Floppy Disk Drives, and contains a read circuit (with a four-mode filter system), a write circuit, an erase circuit, and a supply voltage detection circuit, all on a single chip.

Features

- **•** Single 5V power supply
- **•** Filter system can be switched among four modes: 1M, 1.6M/2M, which are each inner track/outer track
- **•** Filter characteristics can be set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track only, and to Butterworth for the other modes
- **•** A custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track only
- **•** Permits customization of the fc ratio
- **•** Low preamplifier input conversion noise voltage of 2.0nV/ $\sqrt{ }$ Hz (typ.) keeps read data output jitter to a minimum
- **•** Preamplifier voltage gain can be switched between 39dB and 45dB
- In inner track mode (OTF = Low), the voltage gain is boosted by 3dB, making it possible to minimize peak shift in inner tracks.
- **•** Time domain filter can be switched between two modes: 1M, 1.6M/2M
- **•** Write current can be switched among three modes: 1M/1.6M/2M. The inner/outer track current ratio is fixed for each mode, but can be customized.
- **•** Erase current can be set by an external resistor, and remains constant. In addition, the current rise time Tr and fall time Tf are determined according to the head inductance and current. (Refer to page 20.)
- **•** Damping resistor can be built in. Resistance can be customized between 2kΩ and 15kΩ in 1kΩ steps. A damping resistor can not be connected to this IC, however.
- **•** Supply voltage detection circuit

Applications

Three-mode FDDs

Structure

Bipolar silicon monolithic IC

Absolute Maximum Ratings (Ta = 25°C)

Operating Conditions

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Block Diagram and Pin Configuration

Pin Description

Electrical Characteristics

Current Consumption (Ta = 25°C, Vcc = 5V)

Item	Symbol	Conditions	Measure- ment circuit ment Point	Measure-	Min.	Typ.	Max.	Unit
Current consumption in read mode	ICCR	$XWG = High$			16	26	36	mA
Current consumption in write/erase mode	ICCWE	$XWG = Low,$ $XEG = Low$				13	19	mA
Current consumption in power saving mode	ICCPS	$XPS = Low$				0.95	1.9	mA

Power Supply Monitoring System (Ta = 25°C)

Item Symbol Conditions measure Micasure Min. Typ. Max. Unit Power supply on/off detector threshold voltage Power on output saturation voltage VTH VSP $VCC = 3.5V$ $I = 1mA$ — 签方 — — 3.5 — 3.9 — 4.3 0.5 V V Measure-Measure-

Read System (Ta = 25°C, Vcc = 5V)

 $(Ta = 25^{\circ}C, \text{Vcc} = 5V)$

∗**¹** Read data output: 0.5V to 2.4V

∗**²** Signal input level

Low gain/outer track: $V_1 = 0.5$ mV_p-p to 10mVp-p Low gain/inner track: $V_1 = 0.5$ mVp-p to 7mVp-p High gain/outer track: V_I = 0.25mVp-p to 5mVp-p High gain/inner track: $V = 0.25$ m Vp -p to 3.5m Vp -p

Fig. 1 1st and 2nd monostable multivibrator pulse width precision
and peak shift measurement conditions
white multivibrator pulse width precision
 πh and $XHD = High:$
 $\frac{T_1}{2.5 \mu s}$ -1) × 100 [%] **and peak shift measurement conditions**

• 1st monostable multivibrator pulse width precision When $X360 =$ High and $XHD =$ High:

$$
ETM1 = (\frac{T_1}{2.5\mu s} - 1) \times 100 [%]
$$

When $X360 =$ Low and $XHD = High$, or $X360 = X$ and $XHD = Low$:

$$
ETM1' = (\frac{T_1}{1.25\mu s} - 1) \times 100 [%]
$$

- 1st monostable multivibrator pulse width = T₂
- **•** Peak shift

$$
PS = \frac{1}{2} \left| \frac{T_A - T_B}{T_A + T_B} \right| \times 100 \, [\%]
$$

Read System (Filters) (Ta = 25°C, Vcc = 5V)

∗**³** Gpn = 20 log10 (VFilterout/Vpreout) VFilterout = Filter differential output voltage $(n = 1 to 4)$

Fig. 2. Filter frequency response measurement conditions

Write/Erase System (Ta = 25[°]C, Vcc = 5V)

^{*4} Write current output precision $E_W = (\frac{I_W}{6.78 \times 10^{-10} \text{ m}} - 1) \times 100$ [%] 2.72mAo-p

^{*5} Erase current output precision $E_E = (\frac{1E}{2.000 \text{ mA}} - 1) \times 100$ [%] 9.08mA

∗**⁶** Erase current rise/fall times show the values when the output pin is shorted with the power supply.

Logic Input Block (Ta = 25°C, Vcc = 5V)

Electrical Characteristics Measurement Circuit 1

Note) Unless otherwise specified, switches are assumed to be set to "a".

∗**⁷** CR time constant of external comparator input stage is equivalent to the time constant of comparater with a built-in IC.

Electrical Characteristics Measurement Circuit 2

Note) Unless otherwise specified, switches are assumed to be set to "a".

Description of Operation

(1) Read system

Preamplifier

The preamplifier amplifies input signals. The voltage gain can be switched between 39dB and 45dB, using Pin 20. In addition, an additional 3dB boost in the voltage gain is possible by setting Pin 8 low.

Filters

The filters differentiate the signals amplified by the preamplifier. The high-band noise components are attenuated by the low-pass filter. The filters can be switched among four modes, depending on the settings of Pins 8, 9 and 18. In 1M/outer track mode, the peak frequency for is set by external resistor RF.

fo for the other three modes is switched by the internal settings of the IC, with fo1 used as a reference (1.00) .

Active filter block

The center frequency fob of the BPF is fixed to 1.2 times the cutoff frequency fo of the LPF. The LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for all other modes.

The formula for determining the peak frequency fo1 for 1M/outer track mode is shown below: fo₁ = 534/RF + 6.2 [kHz] RF: filter setting resistance [kΩ]

Comparator

The comparator detects the crosspoint of the filter differential output.

Time domain filter

The time domain filter converts the comparator output to read data.

This filter is equipped with two monostable multivibrators. 1st monostable multivibrator eliminates unnecessary pulses, and 2nd monostable multivibrator determines the pulse width of the read data.

The 1st monostable multivibrator pulse width T1 is determined by the resistor RA between Pin 12 and A.GND. T1 can be switched as follows by the settings of Pins 9 and 18:

When XHD = High and X360 = High T1(1M) = 88RA + 124 [ns] RA [kΩ]

When $XHD = High$ and $X360 = Low$ or

 $XHD = Low and X360 = X$ T1(1.6M/2M) = 44RA + 62 [ns]

The pulse width for 2nd monostable multivibrator is fixed at 400ns.

(2) Write system

Write data input through Pin 2 is frequency-divided by the T flip-flop and generates the recording current for the head. The recording current can be switched by the settings of Pins 9 and 18.

The write current Iw is set by the resistors Rw connected between Pin 25 and Vcc, between Pin 26 and Vcc, and between Pin 27 and Vcc.
IW = $3.53/RW$ ImA Ω is and PW is Ω and between Pin 27 and Vcc.

 $Iw = 3.53/Rw$ [mAo-P] Rw [kΩ]

Furthermore, the inner/outer track write current Iw can be changed for each mode by switching Pin 4. However, the current ratio between the inner and outer tracks is fixed.

(3) Erase current

The erase current IE is set by the resistor RE between Pin 28 and Vcc.

IE = 11.8/RE [mA] RE [kΩ]

Pins 30 and 31 are constant current outputs.

In addition, in order to minimize the R/W head crosstalk time constants are provided for the rise and fall of the erase current. For details, refer to page 20 and page 21.

(4) Power on/off detection system

The power on/off detection system detects a reduced voltage in the supply voltage.

When Vcc is below the specified value, the write system and erase system cease operation, disabling the write and erase functions.

Notes on Operation

• Select the voltage gain so that the preamplifier output amplitude is 1Vp-p or less.

If the preamplifier output amplitude exceeds 1Vp-p, the filter output waveform becomes distorted.

- **•** Observe the following point when mounting this device.
	- The ground should be as large as possible.

Application Circuit

Application circuits shown are typical examples illustrating the operation of the devices. Sony cannot assume responsibility for any problems arising out of the use of these circuits or for any infringement of third party patent and other right due to same.

Notes

- 1. If a resistor for setting the write current is not used, connect that pin to Vcc. However, if connected to Vcc, do not select that mode for writes, as doing so could cause a large current flow that could damage the IC.
- 2. When using two modes (1M and 2M), connect X360 (Pin 18) to Vcc and set XHD (Pin 9) high or low to switch modes.

Filter Frequency Response

The LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for the other modes. In addition, a custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track mode only; in that case, it is not possible to change between 1.6M/inner track and 2M/inner track. As a result, the 1.6M and 2M characteristics and fc ratio are identical.

The BPF center frequency fob is fixed at 1.2 times the LPF cutoff frequency.

 f OB = 1.2 fc

In the comprehensive characteristics, the relationship between the peak frequencies fo and fc is as follows, depending on the differences of the LPF type:

Butterworth characteristics $fcn = 1.28$ fon $(n = 1, 2, 3)$

Chebyshev (1dB ripple characteristics) fo

$$
cn = 1.2870n (n = 1, 227)
$$

$$
c4 = 1.1264 - 18 - 18
$$

Custom Selection of Filters

Regarding the LPF cutoff frequency fo, assuming the LPF cutoff frequency fc1 in 1M/outer track mode as 1.00, the fc ratio can be selected for the other three modes.

In addition, the LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for the other modes. However, a custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track mode only. (However, the 1.6M and 2M characteristics and fc ratio are identical.)

Note that the BPF center frequency fob is fixed at 1.2 times fc. In addition, the ratio between fo and fc conforms with the relationship shown on the previous page.

∗ The boxed ratio indicates the setting for the CXA3010Q.

Write Current Setting Method

Assuming the outer track as 1.00, the write current ratio is fixed within the IC for each mode. The write current for the outer track is set in each mode by the resistors connected to Pins 25, 26, and 27. The current ratio for the inner track in each mode can be selected according to the following table.

The setting is for the outer track current when XCI is Low, and for the inner track current when XCI is High.

Write current inner track setting ratios

∗ The boxed ratio indicates the setting for the CXA3010Q.

The write current setting for the outer track is determined according to the following formula:

Iw = $3.53/Rw$ (mAo-P) Rw: [kΩ]

Erase Current Setting Method

The erase circuit in this IC generates the erase current by using a constant current circuit; the current value is determined according to the following formula, based on the resistor RE connected to Pin 28.

IE = 11.8/RE [mA] RE: [kΩ]

Erase Current Rise and Fall Times (Refer to Fig. 3)

In this IC, time constants are provided for the erase current rise and fall in order to prevent bad writes due to write head crosstalk.

The current rise and fall times of the constant current circuit in the IC is 1.3µs, but the potential difference VA that develops in the head when the erase current is turned on and off is as shown below. Because the circuit clamp is generated according to this VA value, the rise and fall times differ. Therefore, refer to the explanation provided below when using this IC.

VA = L $\times \frac{di}{dt}$ (L: head inductance; di: erase current; dt: 1.3µs) dt

1. When erase current turns on

(1) When the potential difference VA in the head is $(Vcc - 1.8V)$ or more

When the current turns on, potential difference VA is generated in the head; if VA is equal to (Vcc $-1.8V$) or more, the erase output transistor Q1 shown in the circuit in Fig. 3 becomes saturated, and the pin voltage is

 20^{9}

clamped at approximately 1.8V. Voltage driving results, and the rise time Tr is as follows:
\n
$$
Tr = \frac{L \times IE}{\sqrt{c} - 1.8} \times \frac{1}{1000} \text{ [ps]} \text{ L: [µH], IE: [mA], Vcc: [V]}
$$

(2) When the potential difference VA in the head is $(Vcc - 1.8V)$ or less

In this case, because VA does not reach clamping level, the rise time becomes the rise time of IE in the circuits within the IC.

Current rise time $Tr = 1.3 \mu s$

2. When erase current turns off

(1) When the potential difference VA in the head is 0.7V or more

When the current turns off, potential difference VA is generated in the head by counterelectromotive force; if VA is equal to approximately 0.7V or more, the positive protective diode D1 shown in the circuit in Fig. 3 turns on, and the pin voltage is clamped at approximately (Vcc $+$ 0.7V). As when the erase current is turned on, voltage driving results, and the fall time Tf is as follows:

$$
Tf = \frac{L \times I\epsilon}{0.7} \times \frac{1}{1000} \text{ [µs]} \quad L: [\mu H], \text{ I}\epsilon: [mA]
$$

Current fall time $Tf = 1.3 \mu s$

(2) When the potential difference VA in the head is 0.7V or less

In this case, because VA does not reach clamping level, the fall time becomes the fall time of IE in the circuits within the IC.

Vcc GND D1 (positive protective diode) $O₁$ IE (rise/fall time: 1.3µs) ERA0 Circuits within IC For ERA1 D2 (negative protective diode) IE $Hiah =$ approx. 2.25 V $\log_2 0$ L 30 **Fig. 3. Erase equivalent circuit**

However, in the specifications, because the value indicated is with the erase head pin shorted with the power supply so that the head voltage described earlier is not generated, the rise and fall times for the constant current circuit itself are given.

 $-22-$

Package Outline Unit: mm

32PIN QFP (PLASTIC)

