SONY

CXA3010Q

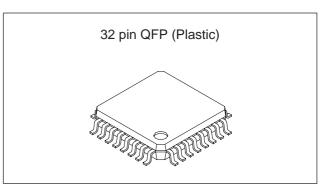
Read/Write Amplifier (with Built-in Filters) for FDDs

Description

The CXA3010Q is a monolithic IC designed for use with three-mode Floppy Disk Drives, and contains a read circuit (with a four-mode filter system), a write circuit, an erase circuit, and a supply voltage detection circuit, all on a single chip.

Features

- Single 5V power supply
- Filter system can be switched among four modes: 1M, 1.6M/2M, which are each inner track/outer track
- Filter characteristics can be set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track only, and to Butterworth for the other modes
- A custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track only
- · Permits customization of the fc ratio
- Low preamplifier input conversion noise voltage of 2.0nV/\sqrt{Hz} (typ.) keeps read data output jitter to a minimum
- Preamplifier voltage gain can be switched between 39dB and 45dB
- In inner track mode (OTF = Low), the voltage gain is boosted by 3dB, making it possible to minimize peak shift in inner tracks.
- Time domain filter can be switched between two modes: 1M, 1.6M/2M
- Write current can be switched among three modes: 1M/1.6M/2M. The inner/outer track current ratio is fixed for each mode, but can be customized.
- Erase current can be set by an external resistor, and remains constant. In addition, the current rise time Tr and fall time Tf are determined according to the head inductance and current. (Refer to page 20.)
- Damping resistor can be built in. Resistance can be customized between 2kΩ and 15kΩ in 1kΩ steps. A damping resistor can not be connected to this IC, however.
- Supply voltage detection circuit



Applications

Three-mode FDDs

Structure

Bipolar silicon monolithic IC

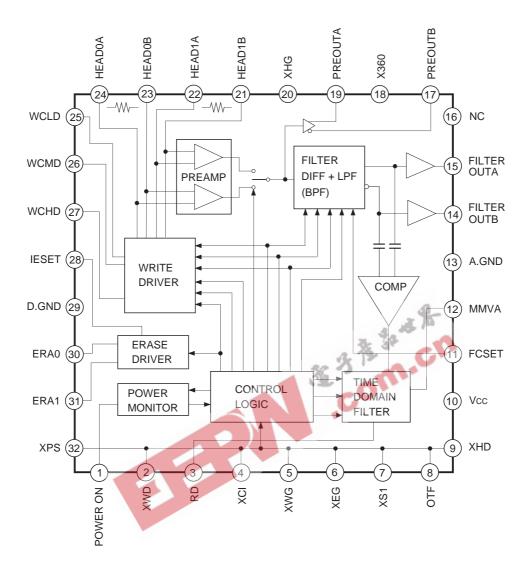
2								
Absolute Maximum Ratin	ıgs (Ta	= 25°C)						
Supply voltage	Vcc	7.0	V					
 Operating temperature 	Topr	-20 to +75	°C					
 Storage temperature 	Tstg	-65 to +150	O° C					
 Allowable power dissipat 	ion							
	PD	500	mW					
 Digital signal input pin Input voltage 								
	_(0.5 to Vcc +	0.3 V					
• Power ON output voltage	applied	Vcc + 0.3	V					
• Erase output voltage app	olied	Vcc + 0.3	V					
Write head voltage applie	ed	15	V					
 Write current 	Iw	20	mAo-p					
 Erase current 	lε	30	mA					
• Power on output current		7	mA					

Operating Conditions

Supply voltage 4.4 to 6.0

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Block Diagram and Pin Configuration



Pin Description

Pin No.	Symbol	Pin voltage	Equivalent circuit	Description
1	POWER ON	_	Vcc 100k	Reduced voltage detection output. This is an open collector pin that outputs a low signal when Vcc is below the specified value.
2	XWD		2 3V A.GND	Write data input. This pin is a Schmitt-type input that is triggered when the logical voltage goes from High to Low.
3	RD	_	Vcc 3 D.GND	Read data output. This pin is active when the logical voltage of the write gate signal and the erase gate signal is High.
4	XCI	_		Write current control. The write current increases when the logical voltage is Low.
5	XWG	_	3-	Write gate signal input. The write system becomes active when the logical voltage is Low.
6	XEG	_	(4) ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓ ↓	Erase gate signal input. The erase system becomes active when the logical voltage is Low.
7	XS1		5 1k 6 7 8 9 4.GND	Head side switching signal input. The HEAD1 system is active when the logical voltage is Low, and the HEAD0 system is active when the logical voltage is High, but only when the logical voltage for the write gate and the erase gate is High.
8	OTF	_		Filter inner track/outer track mode control. Inner track mode is selected when the logical voltage is Low.
9	XHD	_		Filter, time domain filter and write current 1M/2M mode control. 2M mode is selected when the logical voltage is Low.

Pin No.	Symbol	Pin voltage	Equivalent circuit	Description
18	X360	_		Filter, time domain filter and write current 1M/1.6M mode control. 1.6M mode is selected when the logical voltage is Low.
20	XHG	_	(20) - W - C - 2.1V A.GND	Preamplifier voltage gain selection. Gain is boosted by 6dB when the logical voltage is Low compared to when the logical voltage is High.
10	Vcc	_		Power supply (5V) connection.
11	FCSET	3.8V	1.2V	Filter cutoff frequency setting resistor connection. Connect the filter cutoff frequency setting resistor RF between this pin and Vcc in order to set the cutoff frequency.
12	MMVA	0.5V	Vcc Vcc 147 1.2V A.GND	Time domain filter 1st monostable multivibrator pulse width setting. Connect the 1st monostable multivibrator pulse width setting resistor RA between this pin and A.GND.
13	A.GND	_		Analog system GND connection.
14	FILTER OUTB	3.4V	Vcc 140 ≩ ₹140 140 140	Filter differential outputs.
15	FILTER OUTA	3.4V	300µ (15) 300µ A.GND	
16	(NC)			Not connected.
17	PRE OUTB	3.4V	140 ≩ ₹140 17	Preamplifier differential outputs.
19	PRE OUTA	3.4V	200µ (19) 200µ A.GND	

Pin No.	Symbol	Pin voltage	Equivalent circuit	Description				
21	HEAD 1B	_	24232221					
22	HEAD 1A	_		Magnetic head input/output connections. Connect the recording/playback magnetic head to these pins, and connect the center tap to Vcc. When the logical voltage for				
23	HEAD 0B	_		Pin 7 (XS1) is Low, the HEAD1 system is active; when the logical voltage is High, the HEAD0 system is active.				
24	HEAD 0A	_						
25	WCLD	5V when		1M write current setting resistor connection. Connect the write current setting resistor RwLD between this pin and Vcc to set the write current.				
26	WCMD	XWG = High 3.8V when		1.6M write current setting resistor connection. Connect the write current setting resistor Rwmp between this pin and Vcc to set the write current.				
27	WCHD	XWG = Low	A.GND	2M write current setting resistor connection Connect the write current setting resistor RWHD between this pin and Vcc to set the write current.				
28	IESET	5V when XEG = High 3.8V when XEG = Low	1.2V Vcc 147 (28) A.GND	Erase current setting resistor connection. Connect the erase current setting resistor RE between this pin and Vcc to set the erase current.				
29	D.GND	_		Digital system GND connection.				
30	ERA0			Erase current connection for the HEAD0 system.				
31	ERA1		A.GND	Erase current connection for the HEAD1 system.				

Pin No.	Symbol	Pin voltage	Equivalent circuit	Description
32	XPS		32 162k Vcc Vcc 2.1V A.GND	Power saving signal input. When the logical voltage is Low, the IC is in power saving mode. In power saving mode, only the power supply on/off detector operates.



Electrical Characteristics

Current Consumption

 $(Ta = 25^{\circ}C, Vcc = 5V)$

Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
Current consumption in read mode	ICCR	XWG = High	_	_	16	26	36	mA
Current consumption in write/erase mode	ICCWE	XWG = Low, XEG = Low	_	_	7	13	19	mA
Current consumption in power saving mode	ICCPS	XPS = Low	_	_		0.95	1.9	mA

Power Supply Monitoring System

Measure-Measure-Item Symbol Conditions Min. Тур. Max. Unit ment circuit ment Point Power supply on/off Com.C detector threshold VTH V 3.5 3.9 4.3 voltage Power on output Vcc = 3.5VVSP 0.5 V saturation voltage I = 1mA

Read System

 $(Ta = 25^{\circ}C, Vcc = 5V)$

(Ta = 25°C)

Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
Preamplifier voltage gain Low gain/outer track	GVLO	f = 100kHz OTF = High, XHG = High	1	D, E	37.1	39.0	40.6	dB
Preamplifier voltage gain Low gain/inner track	GVLI	f = 100kHz OTF = Low, XHG = High	1	D, E	40.1	42.0	43.6	dB
Preamplifier voltage gain High gain/outer track	GVHO	f = 100kHz OTF = High, XHG = Low	1	D, E	43.1	45.0	46.6	dB
Preamplifier voltage gain High gain/inner track	GVHI	f = 100kHz OTF = Low, XHG = Low	1	D, E	46.1	48.0	49.6	dB
Preamplifier frequency response	BW	G∨/G∨ (100kHz) = −3dB	1	D, E	5	_		MHz
Preamplifier input conversion noise voltage	EN	Band Width = 400Hz to 1MHz, Vı = 0	1	D, E	_	2.0	2.9	nV/√ Hz
Preamplifier differential output offset voltage	VOFSP	V1 = 0	1	D, E	-500	_	+500	mV
Filter differential output offset voltage	VOFSF	VI = 0	1	B, C	-100	_	+100	mV
Filter differential output voltage amplitude	VOF		1	В, С	2.8			Vp-р

Read System	lead System							
Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
		X360 = High, XHD = High (1M mode)	1	A, F	2.25	2.5	2.75	μs
Time domain filter monostable multivibrator pulse width	T1	X360 = Low, XHD = High (1.6M mode) or X360 = X, XHD = Low (2M mode) Refer to Fig. 1	1	A, F	1.13	1.25	1.38	ha
Read data pulse width	T2	Refer to Fig. 1	1	A	260	400	540	ns
Read data output low output voltage	VOL	Iol = 2mA	1	А			0.5	V
Read data output high output voltage	VOH	Іон = -0.4mA	1	А	2.8	_		V
Read data output ^{*1} rise time	tr	$R_{L} = 2k\Omega$ $C_{L} = 20pF$	1	А		_	100	ns
Read data output ^{*1} fall time	tf	$R_{L} = 2k\Omega$ $C_{L} = 20pF$	1	A	. —		100	ns
Peak shift ^{*2}	PS	$V_{I} = 0.25mVp-p to$ $3.5mVp-p$ $XHG = Low, XHD = Low$ $OTF = Low$ $f = 125kHz, 2M/$ inner track mode Refer to Fig. 1	1 3 20	M _A .C	<u> </u>		1	%

Read System

*1 Read data output: 0.5V to 2.4V

*2 Signal input level

Low gain/outer track: $V_1 = 0.5mVp-p$ to 10mVp-pLow gain/inner track: $V_1 = 0.5 \text{mVp-p}$ to 7 mVp-pHigh gain/outer track: $V_1 = 0.25mVp-p$ to 5mVp-pHigh gain/inner track: VI = 0.25mVp-p to 3.5mVp-p

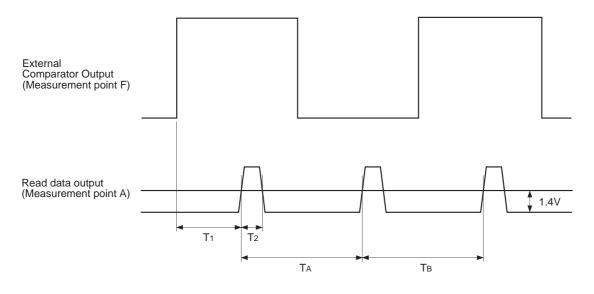


Fig. 1 1st and 2nd monostable multivibrator pulse width precision ·Com.cn and peak shift measurement conditions

• 1st monostable multivibrator pulse width precision When X360 = High and XHD = High:

ETM1 =
$$(\frac{T_1}{2.5\mu s} - 1) \times 100 \, [\%]$$

When X360 = Low and XHD = High, or X360 = X and XHD = Low:

ETM1' =
$$\left(\frac{T_1}{1.25\mu s} - 1\right) \times 100 [\%]$$

- 1st monostable multivibrator pulse width = T2
- · Peak shift

$$\mathsf{PS} = \frac{1}{2} \left| \frac{\mathsf{T}_{\mathsf{A}} - \mathsf{T}_{\mathsf{B}}}{\mathsf{T}_{\mathsf{A}} + \mathsf{T}_{\mathsf{B}}} \right| \times 100 \, [\%]$$

Read System (Filters)

(Ta = 25°C, Vcc = 5V)

								′	
	Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
	Peak frequency	f01	X360 = High XHD = High OTF = High	1	B, C	153.0	170.0	187.0	kHz
1M outer	Peak voltage gain ^{*3}	Gp1	Refer to Fig. 2 at fo1	1	D, E B, C	4.3	6.2	7.8	dB
track	Frequency response (1)	G11	Refer to Fig. 2 at 1/3fo1	1	B, C	-7.6	-7.1	-6.6	dB
	Frequency response (2)	G12	Refer to Fig. 2 at 3fo1	1	B, C	-24.7	-22.8	-21.2	dB
	Peak frequency	fo2	X360 = High XHD = High OTF = Low	1	B, C	163.8	182.0	200.2	kHz
1M inner track	Peak voltage gain ^{*3}	Gp2	Refer to Fig. 2 at fo2	1	D, E B, C	4.3	6.2	7.8	dB
	Frequency response (1)	G21	Refer to Fig. 2 at 1/3fo2	1	в, С	-7.6	-7.1	-6.6	dB
	Frequency response (2)	G22	Refer to Fig. 2 at 3fo2	37 34	B, C	-24.7	-22.8	-21.2	dB
1.6M/ 2M outer	Peak frequency	fo3	X360 = Low XHD = High OTF = High (1.6M/outer track) or X360 = X XHD = Low OTF = High (2M/outer track)	1	B, C	288.0	320.0	352.0	kHz
track	Peak voltage gain ^{*3}	Gрз	Refer to Fig. 2 at fo3	1	D, E B, C	4.4	6.3	7.9	dB
	Frequency response (1)	G31	Refer to Fig. 2 at 1/3fo3	1	B, C	-7.6	-7.1	-6.6	dB
	Frequency response (2)	G32	Refer to Fig. 2 at 3fo3	1	В, С	-25.0	-23.1	-21.5	dB

Item		Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
1.6M/ 2M inner	Peak frequency	f04	X360 = Low XHD = High OTF = Low (1.6M/inner track) or X360 = X XHD = Low OTF = Low (2M/inner track)	1	B, C	310.5	345.0	379.5	kHz
track	Peak voltage gain ^{*3}	Gp4	Refer to Fig. 2 at fo4	1	D, E B, C	5.9	7.8	9.4	dB
	Frequency response (1)	G41	Refer to Fig. 2 at 1/3f ₀₄	1	B, C	-8.5	-8.0	-7.5	dB
	Frequency response (2)	G42	Refer to Fig. 2 at 3fo4	1	B, C	-36.9	-35.0	-33.4	dB

*3 Gpn = 20 log10 (VFilterout/Vpreout) VFilterout = Filter differential output voltage (n = 1 to 4)

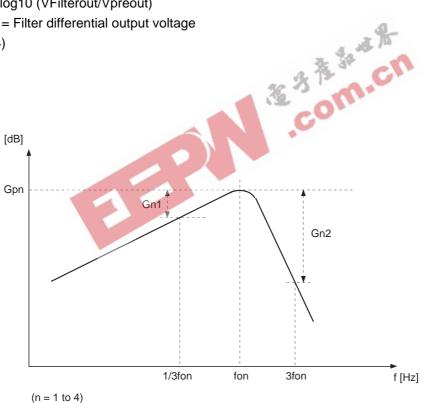


Fig. 2. Filter frequency response measurement conditions

Write/Erase System

 $(Ta = 25^{\circ}C, Vcc = 5V)$

						``	,	,
Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
Damping resistor precision	RD	Vcc = 0V SW2 = b	2	J', K' L', M'	-20	_	+20	%
Write current output precision ^{*4}	EW	XWG = Low RW = 1.3kΩ	2	J, K L, M	-7	_	+7	%
Write current output unbalance	DW	XWG = Low RW = 1.3kΩ	2	J, K L, M	-1	_	+1	%
Head I/O pin leak current for writes	ILKW	XWG = Low	2	J, K L, M	_	_	10	μA
Write head pin current at saturation	ISW	$\begin{array}{l} XWG = Low \\ RW = 1.3k\Omega \\ VSW = 1V \\ SW1 = b \end{array}$	2	J, K L, M	2.47	2.70	2.97	mAo-p
Erase current output precision ^{*5}	EE	XEG = Low RE = 1.3kΩ	2	N, O	-10	_	+10	%
Erase current output pin leak current	ILKE	XEG = Low	2	N, O	-	_	10	μA
Erase current rise time ^{*6}	TRE	Defined at 10% to 90% of IE	2	N', O'	0.6	1.3	2.1	μs
Erase current fall time ^{*6}	TFE	Defined at 90% to 10% of IE	2.0	N', O'	0.6	1.3	2.1	μs

*4 Write current output precision $E_w = (\frac{I_w}{2.72 \text{mAo-p}} - 1) \times 100 \text{ [%]}$

*5 Erase current output precision $E_E = (\frac{I_E}{9.08mA} - 1) \times 100 [\%]$

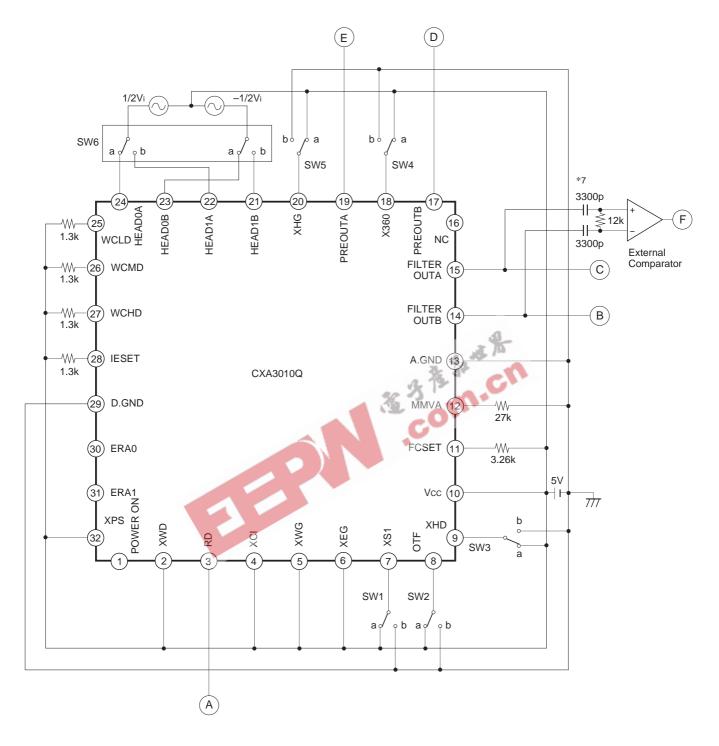
*6 Erase current rise/fall times show the values when the output pin is shorted with the power supply.

Logic Input Block

(Ta = 25°C, Vcc = 5V)

Item	Symbol	Conditions	Measure- ment circuit	Measure- ment Point	Min.	Тур.	Max.	Unit
Digital signal input low input voltage	VLD		2	BCDE FGHIP		_	0.8	V
Digital signal input high input voltage	VHD		2	BCDE FGHIP	2.0			V
Schmitt-type digital signal input low input voltage	VLSD		2	A		_	0.8	V
Schmitt-type digital signal input high input voltage	VHSD		2	A	2.0			V
Digital signal input low input current	ILD	VL = 0V	2	ABCDE FGHIP	-20	_		μA
Digital signal input high input current	IHD	VH = 5V	2	ABCDE FGHIP	_		10	μA

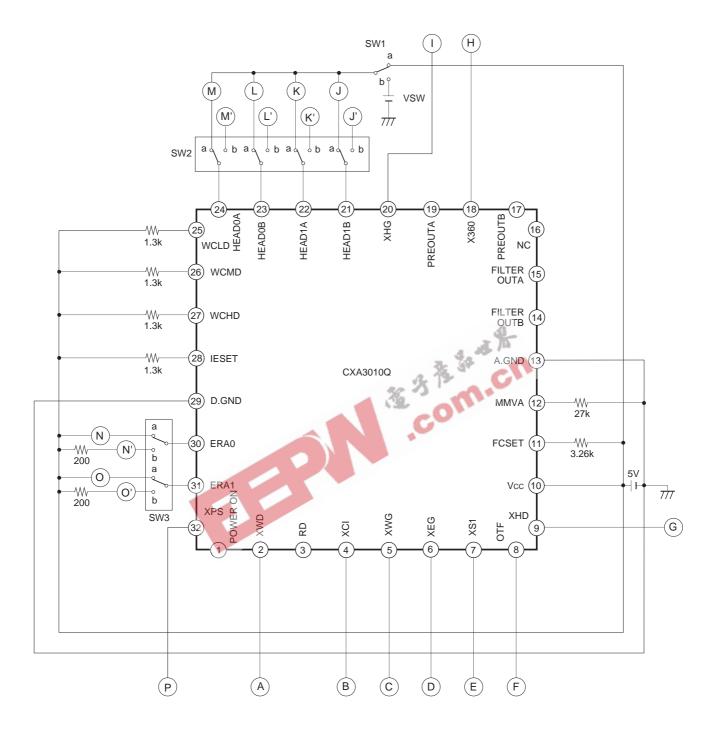
Electrical Characteristics Measurement Circuit 1



Note) Unless otherwise specified, switches are assumed to be set to "a".

*7 CR time constant of external comparator input stage is equivalent to the time constant of comparater with a built-in IC.

Electrical Characteristics Measurement Circuit 2



Note) Unless otherwise specified, switches are assumed to be set to "a".

Description of Operation

Active filter block

(1) Read system

Preamplifier

The preamplifier amplifies input signals. The voltage gain can be switched between 39dB and 45dB, using Pin 20. In addition, an additional 3dB boost in the voltage gain is possible by setting Pin 8 low.

Filters

The filters differentiate the signals amplified by the preamplifier. The high-band noise components are attenuated by the low-pass filter. The filters can be switched among four modes, depending on the settings of Pins 8, 9 and 18. In 1M/outer track mode, the peak frequency for is set by external resistor RF.

fo for the other three modes is switched by the internal settings of the IC, with for used as a reference (1.00).

Preamplifier output A (19) Preamplifier output B (17` Filter output A Preamplifier output BPF LPF HPF ilter output B Secondary Tertiary Primary ain · 8dF fсн **= 5k**Н $fob = 1.2 \times fc$ fc: variable Q = 0.577

The center frequency for of the BPF is fixed to 1.2 times the cutoff frequency for of the LPF. The LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for all other modes.

Pin8 OTF	Pin9 XHD	Pin18 X360	LPF characteristics	fo ratio
н	Н	Н	1M/outer track: Butterworth	1.00
L	Н	Н	1M/inner track: Butterworth	1.07
н	Н	L	1.6M/outer track: Butterworth	1.88
L	Н	L	1.6M/inner track: Chebyshev 1dB ripple	2.03
н	L	Х	2M/outer track: Butterworth	1.88
L	L	Х	2M/inner track: Chebyshev 1dB ripple	2.03

The formula for determining the peak frequency for 1M/outer track mode is shown below: $fo_1 = 534/RF + 6.2 [kHz] RF$: filter setting resistance [k Ω]

Comparator

The comparator detects the crosspoint of the filter differential output.

Time domain filter

The time domain filter converts the comparator output to read data.

This filter is equipped with two monostable multivibrators. 1st monostable multivibrator eliminates unnecessary pulses, and 2nd monostable multivibrator determines the pulse width of the read data.

The 1st monostable multivibrator pulse width T1 is determined by the resistor RA between Pin 12 and A.GND. T1 can be switched as follows by the settings of Pins 9 and 18:

When XHD = High and X360 = High T1(1M) = 88RA + 124 [ns] RA [kΩ]

When XHD = High and X360 = Low or

XHD = Low and X360 = X T1(1.6M/2M) = 44RA + 62 [ns]

The pulse width for 2nd monostable multivibrator is fixed at 400ns.

(2) Write system

Write data input through Pin 2 is frequency-divided by the T flip-flop and generates the recording current for the head. The recording current can be switched by the settings of Pins 9 and 18.

The write current lw is set by the resistors Rw connected between Pin 25 and Vcc, between Pin 26 and Vcc, 30 × Th and between Pin 27 and Vcc.

Iw = 3.53/Rw [mAO-P] $Rw [k\Omega]$

Furthermore, the inner/outer track write current lw can be changed for each mode by switching Pin 4. However, the current ratio between the inner and outer tracks is fixed.

(3) Erase current

The erase current le is set by the resistor Re between Pin 28 and Vcc.

 $I_E = 11.8/R_E [mA]$ $RE[k\Omega]$

Pins 30 and 31 are constant current outputs.

In addition, in order to minimize the R/W head crosstalk time constants are provided for the rise and fall of the erase current. For details, refer to page 20 and page 21.

(4) Power on/off detection system

The power on/off detection system detects a reduced voltage in the supply voltage.

When Vcc is below the specified value, the write system and erase system cease operation, disabling the write and erase functions.

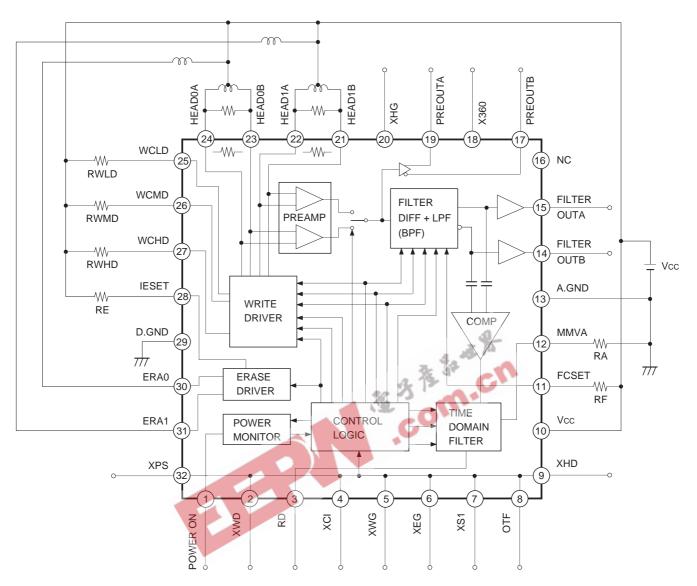
Notes on Operation

Select the voltage gain so that the preamplifier output amplitude is 1Vp-p or less.

If the preamplifier output amplitude exceeds 1Vp-p, the filter output waveform becomes distorted.

- Observe the following point when mounting this device.
 - The ground should be as large as possible.

Application Circuit



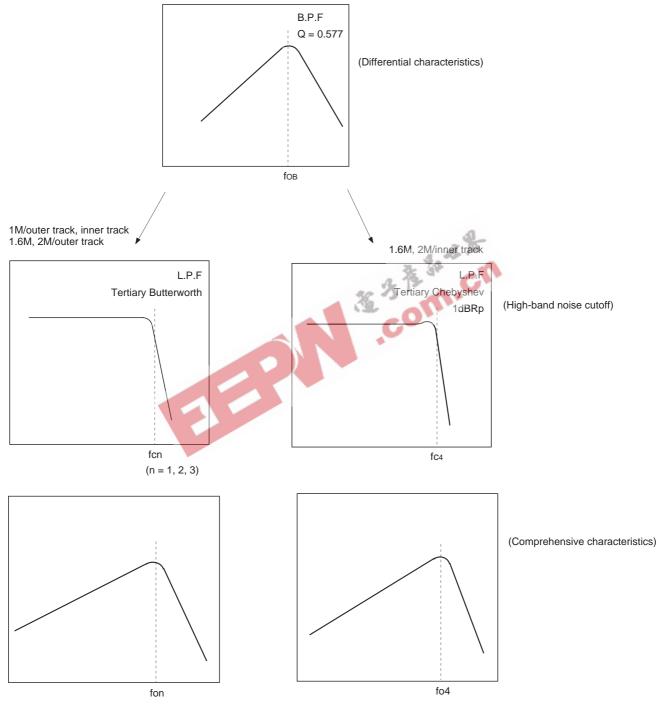
Application circuits shown are typical examples illustrating the operation of the devices. Sony cannot assume responsibility for any problems arising out of the use of these circuits or for any infringement of third party patent and other right due to same.

Notes

- 1. If a resistor for setting the write current is not used, connect that pin to Vcc. However, if connected to Vcc, do not select that mode for writes, as doing so could cause a large current flow that could damage the IC.
- 2. When using two modes (1M and 2M), connect X360 (Pin 18) to Vcc and set XHD (Pin 9) high or low to switch modes.

Filter Frequency Response

The LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for the other modes. In addition, a custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track mode only; in that case, it is not possible to change between 1.6M/inner track and 2M/inner track. As a result, the 1.6M and 2M characteristics and fc ratio are identical.



The BPF center frequency for is fixed at 1.2 times the LPF cutoff frequency.

fов = 1.2fc

In the comprehensive characteristics, the relationship between the peak frequencies fo and fc is as follows, depending on the differences of the LPF type:

Butterworth characteristics for

Chebyshev (1dB ripple characteristics)

Custom Selection of Filters

Regarding the LPF cutoff frequency fo, assuming the LPF cutoff frequency fc1 in 1M/outer track mode as 1.00, the fc ratio can be selected for the other three modes.

In addition, the LPF characteristics are set to Chebyshev (1dB ripple) for 1.6M, 2M/inner track mode only, and to Butterworth for the other modes. However, a custom selection can be made between Chebyshev (1dB ripple) and Butterworth for the filter characteristics for 1.6M, 2M/inner track mode only. (However, the 1.6M and 2M characteristics and fc ratio are identical.)

Note that the BPF center frequency for is fixed at 1.2 times fc. In addition, the ratio between fo and fc conforms with the relationship shown on the previous page.

Mode	LPF type	fc ratio when fc1 is assumed as 1			
1M/outer track	Butterworth	1.0			
1M/inner track	Butterworth	1.07, 1.14, 1.23, 1.33, 1.45, 1.60, 2.00			
1.6M, 2M/outer track	Butterworth	1.33 , 1.39 , 1.45 , 1.52 , 1.60 , 1.68 , 1.78 , 1.88 , 2.00 , 2.13 , 2.29 , 2.46 , 2.67			
1.6M, 2M/inner track	Butterworth Chebyshev (1dB ripple)	1.33 , 1.39 , 1.45 , 1.52 , 1.60 , 1.68 , <u>1.78</u> , 1.88 , 2.00 , 2.13 , 2.29 , 2.46 , 2.67			
* The boxed ratio indicates the setting for the CXA3010Q.					
Write Current Setting Method					
Assuming the outer track as 1.00, the write current ratio is fixed within the IC for each mode. The write curren					

Write Current Setting Method

Assuming the outer track as 1.00, the write current ratio is fixed within the IC for each mode. The write current for the outer track is set in each mode by the resistors connected to Pins 25, 26, and 27. The current ratio for the inner track in each mode can be selected according to the following table.

The setting is for the outer track current when XCI is Low, and for the inner track current when XCI is High.

Write current inner track setting ratios

Track	Write current inner track setting ratio	
1M mode	1.00 , 0.92 , 0.86 ,0.80 , 0.75 , 0.71 , 0.66 , 0.63	
1.6M mode	1.00 , 0.92 , 0.86 ,0.80 , 0.75 , 0.71 , 0.66 , 0.63	
2M mode	1.00 , 0.92 , 0.86 , 0.80 , 0.75 , 0.71 ,0.66, 0.63	

* The boxed ratio indicates the setting for the CXA3010Q.

The write current setting for the outer track is determined according to the following formula:

 $Iw = 3.53/Rw (mAO-P) Rw: [k\Omega]$

Erase Current Setting Method

The erase circuit in this IC generates the erase current by using a constant current circuit; the current value is determined according to the following formula, based on the resistor R_E connected to Pin 28.

 $IE = 11.8/RE [mA] RE: [k\Omega]$

Erase Current Rise and Fall Times (Refer to Fig. 3)

In this IC, time constants are provided for the erase current rise and fall in order to prevent bad writes due to write head crosstalk.

The current rise and fall times of the constant current circuit in the IC is 1.3µs, but the potential difference VA that develops in the head when the erase current is turned on and off is as shown below. Because the circuit clamp is generated according to this VA value, the rise and fall times differ. Therefore, refer to the explanation provided below when using this IC.

VA = L $\times \frac{di}{dt}$ (L: head inductance; di: erase current; dt: 1.3µs)

1. When erase current turns on

(1) When the potential difference VA in the head is (Vcc - 1.8V) or more

When the current turns on, potential difference VA is generated in the head; if VA is equal to (Vcc -1.8V) or more, the erase output transistor Q1 shown in the circuit in Fig. 3 becomes saturated, and the pin voltage is clamped at approximately 1.8V. Voltage driving results, and the rise time Tr is as follows:

Tr = $\frac{L \times IE}{Vcc - 1.8} \times \frac{1}{1000}$ [µs] L: [µH], IE: [mA], Vcc: [V]

(2) When the potential difference VA in the head is (Vcc - 1.8V) or less

In this case, because VA does not reach clamping level, the rise time becomes the rise time of I_E in the circuits within the IC.

Current rise time $Tr = 1.3 \mu s$

2. When erase current turns off

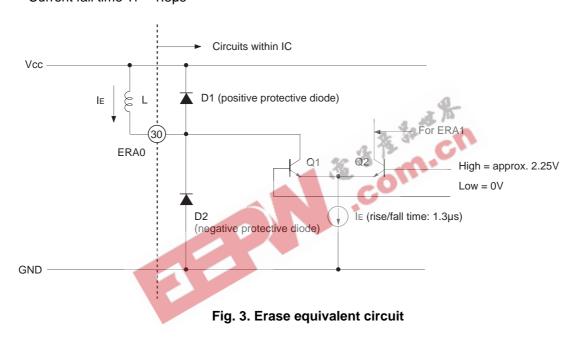
(1) When the potential difference VA in the head is 0.7V or more

When the current turns off, potential difference VA is generated in the head by counterelectromotive force; if VA is equal to approximately 0.7V or more, the positive protective diode D1 shown in the circuit in Fig. 3 turns on, and the pin voltage is clamped at approximately (Vcc + 0.7V). As when the erase current is turned on, voltage driving results, and the fall time Tf is as follows:

$$Tf = \frac{L \times IE}{0.7} \times \frac{1}{1000} \text{ [}\mu\text{s]} \text{ L: [}\mu\text{H]}\text{, IE: [}m\text{A]}$$

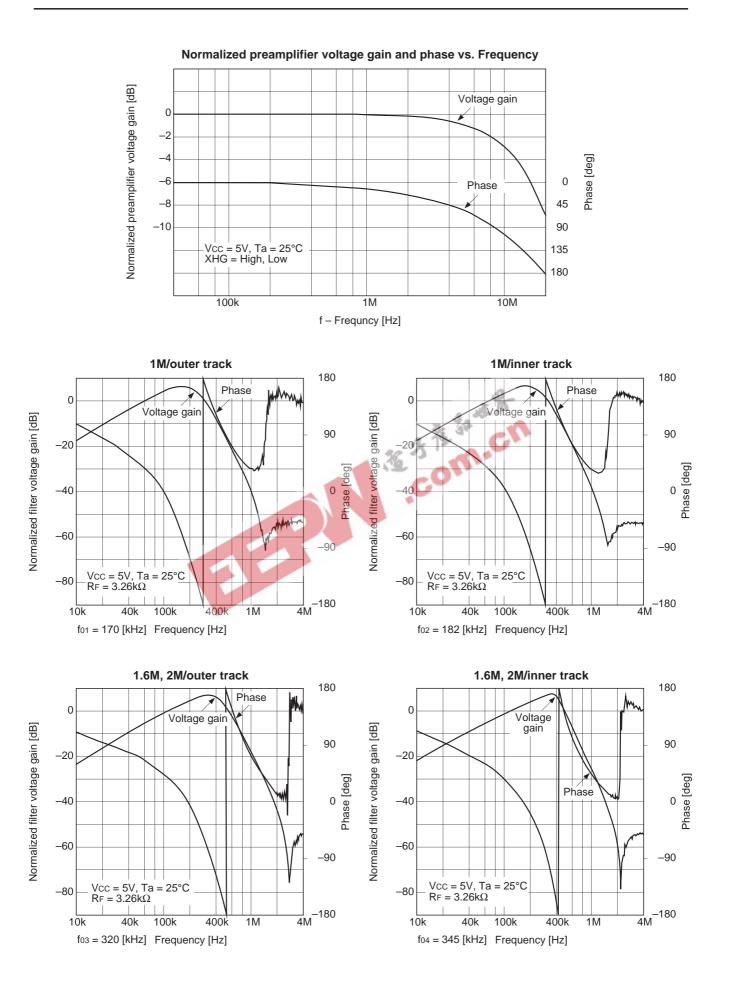
(2) When the potential difference VA in the head is 0.7V or less

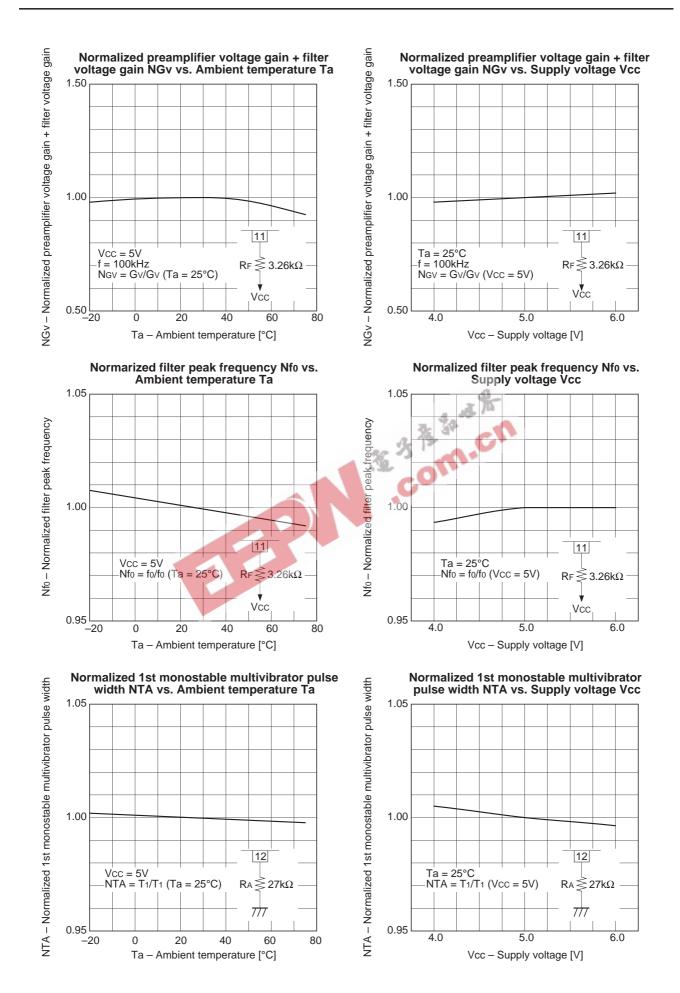
In this case, because VA does not reach clamping level, the fall time becomes the fall time of IE in the circuits within the IC.



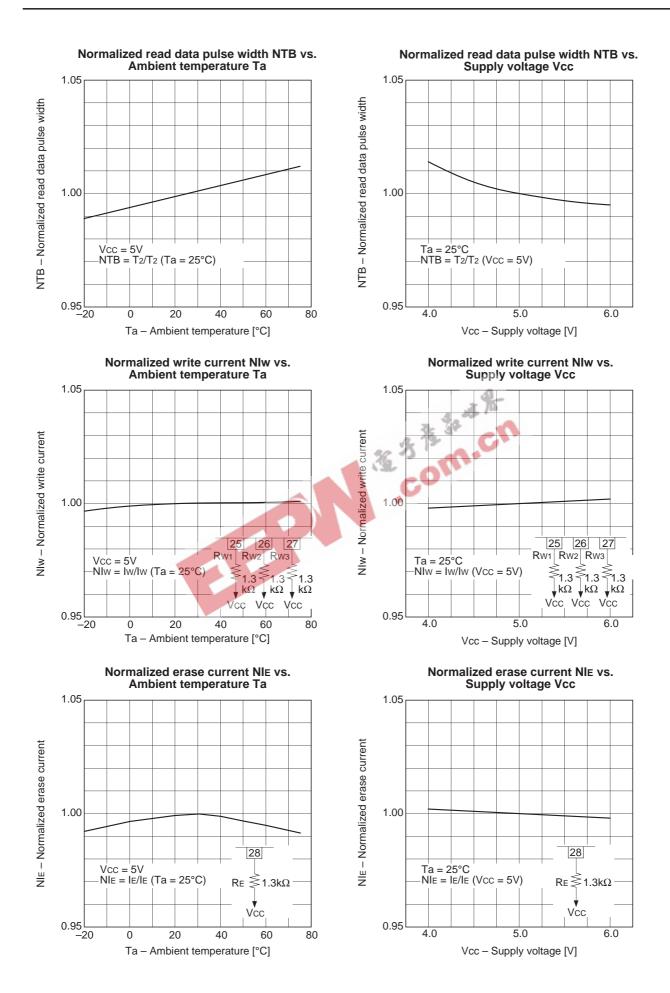
However, in the specifications, because the value indicated is with the erase head pin shorted with the power supply so that the head voltage described earlier is not generated, the rise and fall times for the constant current circuit itself are given.

Current fall time Tf = 1.3µs

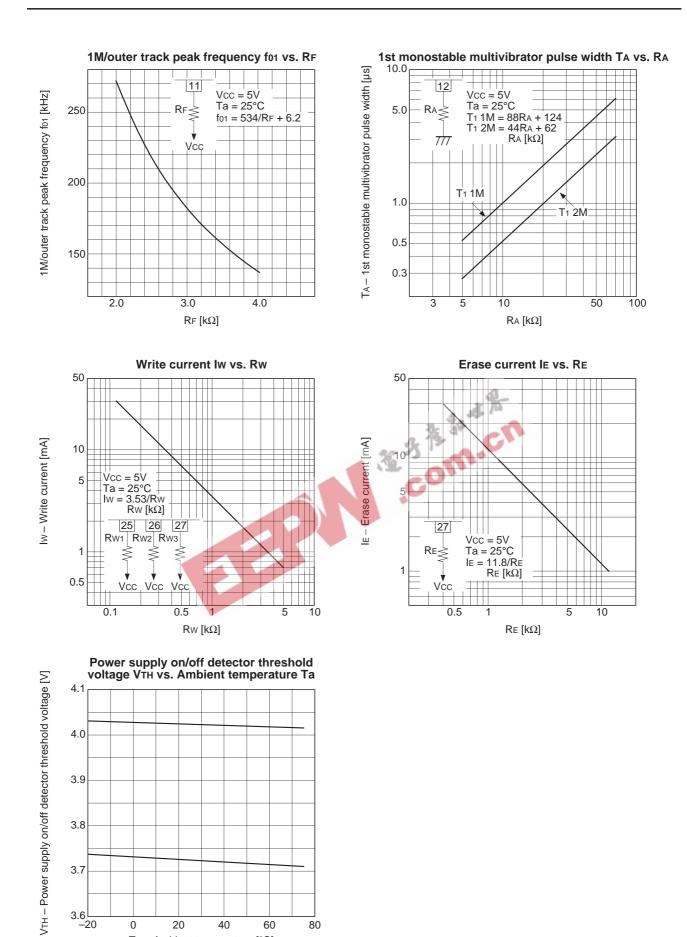




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Ta – Ambient temperature [°C]

Package Outline Unit: mm

32PIN QFP (PLASTIC)

