## MJE13009

## NPN SILICON TRANSISTOR

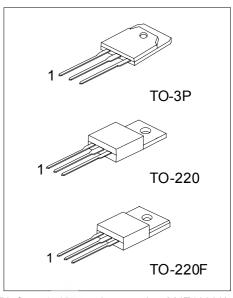
# SWITCHMODE SERIES NPN SILICON POWER **TRANSISTORS**

#### DESCRIPTION

The MJE13009 is designed for high-voltage, high-speed power switching inductive circuits where fall time is critical. They are particularly suited for 115 and 220 V switch mode applications such as Switching Regulators, Inverters, Motor Controls, Solenoid/Relay drivers and Deflection circuits.

#### **FEATURES**

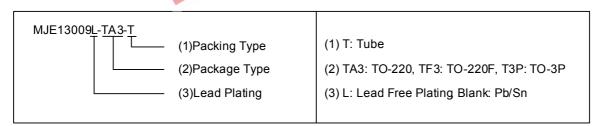
- \*  $V_{\text{CEO}}$  400 V and 300 V
- \* Reverse Bias SOA with Inductive Loads @ T<sub>C</sub> = 100
- \* Inductive Switching Matrix 3 ~ 12 Amp, 25 and 100 tc @ 8 A, 100 is 120 ns (Typ).
- \* 700 V Blocking Capability
- \* SOA and Switching Applications Information.



\*Pb-free plating product number:MJE13009L

### **ORDERING INFORMATION**

| Order I        | Number            | Dookaga | Pin Assignment |   |   | Dooking |  |
|----------------|-------------------|---------|----------------|---|---|---------|--|
| Normal         | Lead Free Plating | Package | 1              | 2 | 3 | Packing |  |
| MJE13009-TA3-T | MJE13009L-TA3-T   | TO-220  | В              | C | Е | Tube    |  |
| MJE13009-TF3-T | MJE13009L-TF3-T   | TO-220F | В              | C | Е | Tube    |  |
| MJE13009-T3P-T | MJE13009L-T3P-T   | TO-3P   | В              | С | Е | Tube    |  |



## ■ ABSOLUTE MAXIMUM RATINGS (Ta = 25 )

| PARAMETER   | SYMBOL           | RATINGS          | UNIT |     |  |
|---|------------------|------------------|------|-----|--|
| Collector-Emitter Voltage                                     | $V_{CEO}$        | 400              | V    |     |  |
| Collector-Base Voltage  | $V_{CBO}$        | 700              | V    |     |  |
| Emitter Base Voltage  |                  | I <sub>EBO</sub> | 9    | V   |  |
| Collector Current   | Continuous       | I <sub>C</sub>   | 12   | _ A |  |
| Collector Current   | Peak*            | I <sub>CM</sub>  | 24   | A   |  |
| Dage Current  | Continuous       | Ι <sub>Β</sub>   | 6    |     |  |
| Base Current  | Peak*            | I <sub>BM</sub>  | 12   | _ A |  |
| Freitter Correct  | Continuous       | Ι <sub>Ε</sub>   | 18   |     |  |
| Emitter Current   | Peak*            | I <sub>EM</sub>  | 36   | _ A |  |
| Total Power Dissipation @ Ta = 25                             | Б                | 2                | W    |     |  |
| Derate above 25   | P <sub>D</sub>   | 16               | mW/  |     |  |
| Total Power Dissipation @ T <sub>C</sub> = 25 Derate above 25 |                  |                  | 100  | W   |  |
|   |                  | P <sub>D</sub>   | 800  | mW/ |  |
| Junction Temperature  |                  | TJ               | +150 |     |  |
| Storage Temperature   | T <sub>STG</sub> | -40 ~ +150       |      |     |  |

Note: 1. Pulse Test: Pulse Width = 5ms, Duty Cycle 10%

#### ■ THERMAL DATA

DADAMETED

| PARAMETER                              | SYMBOL        | RATINGS | UNIT |
|--|---------------|---------|------|
| Thermal Resistance Junction to Ambient | $\theta_{JA}$ | 54      | /W   |
| Thermal Resistance Junction to Case    | θjc           | 4       | /W   |

#### ■ ELECTRICAL CHARACTERISTICS (T<sub>C</sub>= 25), unless otherwise specified.)

| SYMBOL               | TEST CONDITIONS  | MIN   | TYP   | MAX   | UNIT  |
|----------------------|--|---|---|---|---|
|                      |  |   |   |   |   |
| V <sub>CEO</sub>     | $I_{\rm C} = 10 {\rm mA}, I_{\rm B} = 0$   | 400   |   |   | V   |
| I <sub>CBO</sub>     | $V_{BE(OFF)} = 1.5Vdc$   |   |   | 1   | mA  |
|                      | $V_{BE(OFF)} = 1.5Vdc, T_C = 100$  |   |   | 5   | ША  |
| I <sub>EBO</sub>     | $V_{EB} = 9Vdc, I_C = 0$   |   |   | 1   | mA  |
|                      |  |   |   |   |   |
| h <sub>FE1</sub>     | $I_C = 5A, V_{CE} = 5V$  |   |   | 40  |   |
| h <sub>FE 2</sub>    | $I_C = 8A, V_{CE} = 5V$  |   |   | 30  |   |
|                      | $I_{C} = 5A, I_{B} = 1A$   |   |   | 1   | V   |
| V                    | $I_C = 8A, I_B = 1.6A$   |   |   | 1.5   | V   |
| V CE(SAT)            | $I_{\rm C} = 12A, I_{\rm B} = 3A$  |   |   | 3   | V   |
|                      | $I_C = 8A$ , $I_B = 1.6A$ , $T_C = 100$  |   |   | 2   | V   |
| V <sub>BE(SAT)</sub> | $I_{C} = 5A, I_{B} = 1A$   |   |   | 1.2   | V   |
|                      | $I_C = 8A, I_B = 1.6A$   |   |   | 1.6   | V   |
|                      | $I_C = 8A$ , $I_B = 1.6A$ , $T_C = 100$  |   |   | 1.5   | V   |
|                      |  |   | •   |   |   |
| f <sub>T</sub>       | I <sub>C</sub> = 500mA, V <sub>CE</sub> = 10V, f = 1MHz  | 4   |   |   | MHz   |
| $C_ob$               | $V_{CB} = 10V$ , $I_E = 0$ , $f = 0.1MHz$  |   | 180   |   | pF  |
| sistive Load         | , Table 1)   |   |   |   |   |
| t <sub>DLY</sub>     | \/ = 125\/do   = 9A  |   | 0.06  | 0.1   | μs  |
| t <sub>R</sub>       | • •  |   | 0.45  | 1   | μs  |
| ts                   |  |   | 1.3   | 3   | μs  |
| t <sub>F</sub>       | Duty Cycle 31 /0   |   | 0.2   | 0.7   | μs  |
| igure 13)            |  |   |   |   |   |
| ts                   | I <sub>C</sub> =8A, V <sub>clamp</sub> =300V, I <sub>B1</sub> =1.6A  |   | 0.92  | 2.3   | μs  |
| tc                   | $V_{BE(OFF)} = 5V$ , $T_C = 100$   |   | 0.12  | 0.7   | μs  |
|                      | $V_{CEO}$ $I_{CBO}$ $I_{EBO}$ $h_{FE1}$ $h_{FE2}$ $V_{CE(SAT)}$ $V_{BE(SAT)}$ $f_{T}$ $C_{ob}$ esistive Load $t_{DLY}$ $t_{R}$ $t_{S}$ $t_{F}$ $igure 13)$ $t_{S}$ | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ |

<sup>\*</sup>Pulse Test: Pulse Wieth = 300µs, Duty Cycle = 2%

<sup>2.</sup> Absolute maximum ratings are those values beyond which the device could be permanently damaged. Absolute maximum ratings are stress ratings only and functional device operation is not implied.

## ■ TABLE 1. TEST CONDITIONS FOR DYNAMIC PERFORMANCE

|                | REVERSE BIAS SAFE OPERATING AREA AND INDUCTIVE SWITCHING   | RESISTIVE SWITCHING  |
|----------------|--|--|
| TEST CIRCUITS  | DUTY CYCLE 10% 68 $\frac{1}{1000}$  | +125V  Rc  TUT  SCOPE  -4.0V   |
| CIRCUIT VALUES | Coil Data: Ferroxcube Core #6656 GAP for 200 $\mu$ H/20 A $V_{CC}$ = 20 V Full Bobbin (~16 Turns) #16 $L_{coil}$ = 200 $\mu$ H $V_{clamp}$ = 300 Vdc   | $V_{CC}$ = 125 V<br>$R_{C}$ = 15 $\Omega$<br>D1 = 1N5820 or Equiv.<br>$R_{B}$ = $\Omega$   |
| TEST WAVEFORMS | OUTPUT WAVEFORMS $t_{F} \text{ CLAMPED}$ $t_{F} \text{ UNCLAMPED 9 } t_{2} \qquad t_{1} \text{ ADJUSTED TO}$ $OBTAIN \text{ IC}$ $V_{CE} \downarrow \qquad \qquad t_{1} \qquad \downarrow \qquad t_{2} \qquad$ | $+10V$ $25 \mu s$ $-8V$ $10 \mu s$ |

## ■ TABLE 2. APPLICATIONS EXAMPLES OF SWITCHING CIRCUITS

| CIRCUIT                            | LOAD LINE DIAGRAMS   | TIME DIAGRAMS  |
|------------------------------------|--|--|
| SERIES SWITCHING REGULATOR         | TURN-ON (FORWARD BIAS) SOA $t_{ON}$ 10 ms DUTY CYCLE 10% $P_D$ = 4000 W (2)  TURN-OF (REVERSE BIAS) SOA 1.5 V $V_{BE(off)}$ 9.0 V DUTY CYCLE 10% $V_{CC}$ 400V (1) 700V (1) COLLECTOR VOLTAGE  | TIME t  VCE  VCC  TIME t   |
| RINGING CHOKE INVERTER  Vcc Vout   | TURN-ON (FORWARD BIAS) SOA $t_{ON}$ 10 ms DUTY CYCLE 10% $T_{C} = 100^{\circ}\text{C}$ $12A$ $TURN-OFF$ $TURN-OFF$ $TURN-OFF$ $TURN-OFF$ $TURN-ON$ $+ V_{CC}$ $400V$ $TORN-OFF$ $TURN-ON$ $+ V_{CC}$ $TURN-O$  | LEAKAGE SPIKE  V <sub>CC</sub> V <sub>CC</sub> V <sub>CC</sub> V <sub>CC</sub> t  t  t  t  t  t  t  t  t  t  t  t  t |
| PUSH-PULL INVERTER/CONVERTER  Vour | TURN-ON (FORWARD BIAS) SOA $t_{ON}$ 10 ms  DUTY CYCLE 10% $T_{C} = 100^{\circ}\text{C}$ $T_{C} $ | V <sub>CE</sub> V <sub>CC</sub> V <sub>CC</sub> toN  toFF  t  t  |
| SOLENOID DRIVER  Vcc  SOLENOID     | TURN-ON (FORWARD BIAS) SOA $t_{ON}$ 10 ms DUTY CYCLE 10% $T_{C} = 100^{\circ}\text{C}$ $T_{C} = 4000 \text{ W (2)}$ TURN-OFF (REVERSE BIAS) SOA  1.5 V V <sub>BE(off)</sub> 9.0 V DUTY CYCLE 10%  TURN-OFF  TURN-ON $T_{C} = 4000 \text{ W (2)}$ COLLECTOR VOLTAGE   | V <sub>CE</sub> V <sub>CC</sub> t <sub>ON</sub> t <sub>OFF</sub> t   |

#### TABLE 3. TYPICAL INDUCTIVE SWITCHING PERFORMANCE

| $I_{C}(A)$ | T <sub>C</sub> ( ) | t <sub>sv</sub> (ns) | t <sub>rv</sub> (ns) | t <sub>fi</sub> (ns) | t <sub>ti</sub> (ns) | t <sub>c</sub> (ns) |
|------------|--------------------|----------------------|----------------------|----------------------|----------------------|---------------------|
| 0          | 25                 | 770                  | 100                  | 150                  | 200                  | 240                 |
| 3          | 100                | 1000                 | 230                  | 160                  | 200                  | 320                 |
| 5          | 25                 | 630                  | 72                   | 26                   | 10                   | 100                 |
|            | 100                | 820                  | 100                  | 55                   | 30                   | 180                 |
| 8          | 25                 | 720                  | 55                   | 27                   | 2                    | 77                  |
|            | 100                | 920                  | 70                   | 50                   | 8                    | 120                 |
| 10         | 25                 | 640                  | 20                   | 17                   | 2                    | 41                  |
| 12         | 100                | 800                  | 32                   | 24                   | 4                    | 54                  |

#### **SWITCHING TIME NOTES**

In resistive switching circuits, rise, fall, and storage times have been defined and apply to both current and

waveforms since they are in phase. However, for inductive loads which are common to SWITCHMODE power supplies and hammer drivers, current and voltage waveforms are not in phase. Therefore, separate measurements must be made on each waveform to determine the total switching time. For this reason, the following new terms have been defined.

 $t_{sv}$  = Voltage Storage Time, 90%  $I_{B1}$  to 10%  $V_{CEM}$ 

 $t_{rv}$  = Voltage Rise Time, 10–90%  $V_{CEM}$ 

t<sub>fi</sub> = Current Fall Time, 90–10% I<sub>CM</sub>

t<sub>ti</sub> = Current Tail, 10–2% I<sub>CM</sub>

 $t_c$  = Crossover Time, 10%  $V_{CEM}$  to 10%  $I_{CM}$ 

在各世界 An enlarged portion of the turn-off waveforms is shown in Figure 13 to aid in the visual identity of these terms.

For the designer, there is minimal switching loss during storage time and the predominant switching power losses occur during the crossover interval and can be obtained using the standard equation from AN-222:

 $P_{SWT} = 1/2 V_{CC}I_{C}(t_{c}) f$ 

Typical inductive switching waveforms are shown in Figure 14. In general, t<sub>rv</sub> + t<sub>fi</sub> t<sub>c</sub>. However, at lower test currents this relationship may not be valid.

As is common with most switching transistors, resistive switching is specified at 25 and has become a benchmark for designers. However, for designers of high frequency converter circuits, the user oriented specifications which make this a "SWITCHMODE" transistor are the inductive switching speeds (tc and tsv) which are guaranteed at 100 .

#### ■ TYPICAL CHARATERISTICS

Figure 1. Forward Bias Safe Operating Area

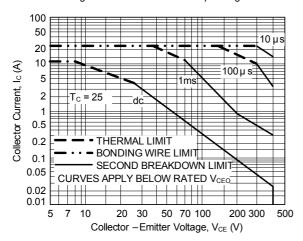


Figure 3. Forward Bias Power Derating

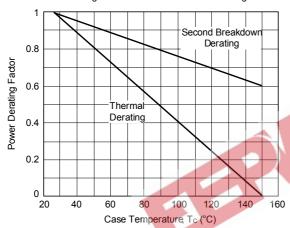
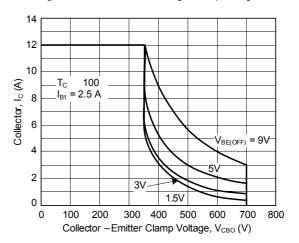


Figure 2. Reverse Bias Switching Safe Operating Area

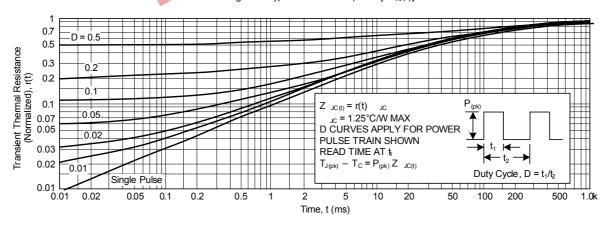


There are two limitations on the power handling ability of a transistor: average junction temperature and second breakdown Safe operating area curves indicate  $I_{\rm C}-V_{\rm CE}$  limits of the transistor that must be observed for reliable operation; i.e., the transistor must not be subjected to greater dissipation than the curves indicate.

The data of Figure 1 is based on  $T_C=25$ ;  $T_{J(ph)}$  is variable depending on power level. Second breakdown pulse limits are valid for duty cycles to 10% but must be derated when  $T_C=25$ . Second breakdown limitations do not derate the same as thermal limitations. Allowable current at the voltages shown on Figure 1 may be found at any case temperature by using the appropriate curve on Figure 3.

 $T_{\text{J(pK)}}$  may be calculated from the data in Figure 4. At high case temperatures, thermal limitations will reduce the power that can be handled to values less than the limitations imposed by second breakdown. Use of reverse biased safe operating area data (Figure 2) is discussed in the applications information section .

Figure 4. Typical Thermal Response [Z  $_{\text{JC}}(t)$ ]



## **■ TYPICAL CHARACTERISTICS (Cont.)**

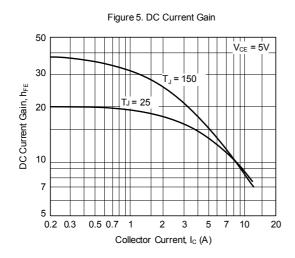
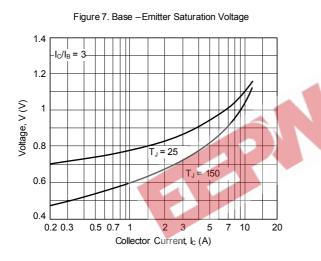


Figure 6. Collector Saturation Region

2
1.6
1.6
1.2
1.0
0.0
0.050.07 0.1
0.2 0.3 0.5 0.7 1 2 3 5

Base Current, I<sub>B</sub> (A)



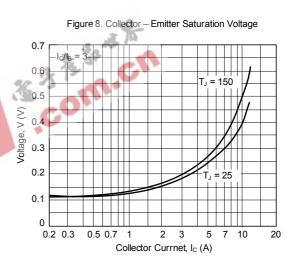


Figure 9. Collector Cutoff Region 10k  $V_{CE} = 250V_{CE}$ 1k Collector Current, I<sub>c</sub> (mA)  $T_{\rm J} = 150$ 125 100 100 10 50 25 REVERSE FORWARD 0.1 -0.4 +0.2 Base – Emitter Voltage,  $V_{BE}(V)$ 

4k
2k
C<sub>ib</sub>
T<sub>J</sub> = 25

1k
0 800
80
0 600
8 400
100
80
60
40
0.1 0.2 0.5 1 2 5 10 20 50 100 200 500
Reverse Voltage, V<sub>R</sub> (V)

Figure 10. Capacitance

#### RESISTIVE SWITCHING PERFORMANCE

Figure 11. Turn - On Time

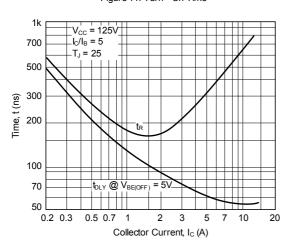


Figure 12. Turn - Off Time

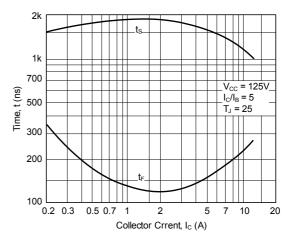
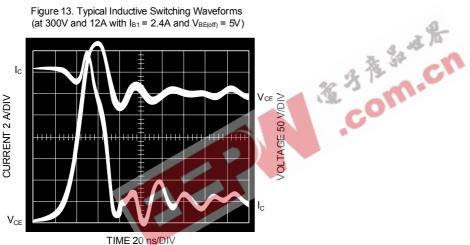


Figure 13. Typical Inductive Switching Waveforms (at 300V and 12A with  $I_{B1} = 2.4A$  and  $V_{BE(off)} = 5V$ )



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