

THE INFINITE POWER OF INNOVATION

UC184xA/284xA/384xA

CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

DESCRIPTION

The UC184xA family of control ICs provides all the necessary features to implement off-line fixed-frequency, current-mode switching power supplies with a minimum of external components. The current mode architecture demonstrates improved load regulation, pulse-by-pulse current limiting and inherent protection of the power supply output switch. The IC includes: A bandgap reference trimmed to ±1% accuracy, an error amplifier, a current sense comparator with internal clamp to 1V, a high current totem pole output stage for fast switching of power

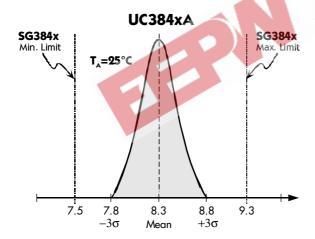
MOSFET's, and an externally programmable oscillator to set frequency and maximum duty cycle. The undervoltage lock-out is designed to operate with 250µA typ. start-up current, allowing an efficient bootstrap supply voltage design. Available options for this family of products, such as start-up voltage hysteresis and duty cycle, are summarized below in the Available Options section. The UC184xA family of control ICs is also available in 14-pin SOIC package which makes the Power Output Stage Collector and Ground pins available.

KEY FEATURES

- LOW START-UP CURRENT. (0.5mA max.)
- TRIMMED OSCILLATOR DISCHARGE CURRENT. (See Product Highlight)
- OPTIMIZED FOR OFF-LINE AND DC-TO-DC CONVERTERS.
- AUTOMATIC FEED FORWARD COMPENSATION.
- PULSE-BY-PULSE CURRENT LIMITING.
- ENHANCED LOAD RESPONSE CHARACTERISTICS.
- UNDER-VOLTAGE LOCKOUT WITH HYSTERESIS.
- DOUBLE PULSE SUPPRESSION.
- HIGH-CURRENT TOTEM POLE OUTPUT.
- ☐ INTERNALLY TRIMMED BANDGAP REFERENCE
- 500KHz OPERATION.
- LOW R ERROR AMPLIFIER.

PRODUCT HIGHLIGHT

COMPARISON OF UC384XA VS. SG384X DISCHARGE CURRENT



Discharge Current Distribution - mA

APPLICATIONS

- ECONOMICAL OFF-LINE FLYBACK OR FORWARD CONVERTERS.
- DC-DC BUCK OR BOOST CONVERTERS.
- LOW COST DC MOTOR CONTROL.

A VAILABLE OPTIONS

Part #	Start-Up Voltage	Hysteresis	Max. Duty Cycle
UCx842A	16V	6V	<100%
UCx843A	8.4V	0.8V	<100%
UCx844A	16V	6V	<50%
UCx845A	8.4V	0.8V	<50%

PACKAGE ORDER INFORMATION **DM** Plastic SOIC Plastic DIP Plastic SOIC Ceramic DIP T_{Δ} (°C) M 8-pin 8-pin 14-pin 8-pin 0 to 70 UC384xAM UC384xADM UC384xAD -40 to 85 UC284xAM UC284xADM UC284xAD UC284xAY UC184xAY -55 to 125

Note: All surface-mount packages are available in Tape & Reel. Append the letter "T" to part number. (i.e. UC3842ADMT)

CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

120°C/W

130°C/W

ABSOLUTE MAXIMUM RATINGS (Note 1)

Supply Voltage (Low Impedance Source) (V _{CC})	30V
Supply Voltage (I _{CC} < 30mA)	Self Limiting
Output Current	±1A
Output Energy (Capacitive Load)	
Analog Inputs (V _{FR} & I _{SENSE})	
Error Amp Output Sink Current	10mA
Power Dissipation at $T_A = 25^{\circ}C$ (M Package)	1W
Storage Temperature Range	65°C to +150°C
Lead Temperature (Soldering, 10 Seconds)	

Note 1. Exceeding these ratings could cause damage to the device. All voltages are with respect to Ground. Currents are positive into, negative out of the specified terminal. Pin numbers refer to DIL packages only.

THERMAL DATA

M PACKAGE:

THERMAL RESISTANCE-JUNCTION TO AMBIENT, θ_{JA} **DM PACKAGE:** 165°C/W

THERMAL RESISTANCE-JUNCTION TO AMBIENT, θ

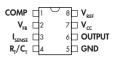
D PACKAGE:

THERMAL RESISTANCE-JUNCTION TO AMBIENT, θ **Y PACKAGE:**

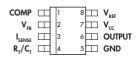
THERMAL RESISTANCE-JUNCTION TO AMBIENT, $\theta_{\rm JA}$

Junction Temperature Calculation: $T_J = T_A + (P_D \times \theta_{JA})$. The θ_{IA} numbers are guidelines for the thermal performance of the device/pc-board system. All of the above assume no ambient airflow

PACKAGE PIN OUTS

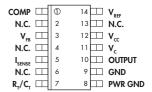


M & Y PACKAGE (Top View)



DM PACKAGE

(Top View)



D PACKAGE

(Top View)

CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

ELECTRICAL CHARACTERISTICS

(Unless otherwise specified, these specifications apply over the operating ambient temperatures for UC384xA with 0°C \leq $T_A \leq$ 70°C, UC284xA with -40°C \leq $T_A \leq$ 85°C, UC184xA with -55°C \leq $T_A \leq$ 125°C; V_{CC} =15V; R_T =10K; C_T =3.3nF. Low duty cycle pulse testing techniques are used which maintains junction and case temperatures equal to the ambient temperature.)

Parameter	Symbol	Test Conditions		UC184xA/284xA					
- raidinetei	Symbol	rest conditions	Min.	Тур.	Max.	Min.	Тур.	Max.	Unit
Reference Section									
Output Voltage	V _{REF}	$T_{J} = 25^{\circ}C, I_{L} = 1 \text{mA}$	4.95	5.00	5.05	4.90	5.00	5.10	٧
Line Regulation		$12 \le V_{ N} \le 25V$		6	20		6	20	m۷
Load Regulation		1 ≤ I _o ≤ 20mA		6	25		6	25	m۷
Temperature Stability (Note 2 & 7)				0.2	0.4		0.2	0.4	mV/°
Total Output Variation		Over Line, Load, and Temperature	4.9		5.1	4.82		5.18	٧
Output Noise Voltage (Note 2)	V _N	10Hz ≤ f ≤ 10kHz, T _J = 25°C		50			50		μV
Long Term Stability (Note 2)		T _A = 125°C, t = 1000hrs		5	25		5	25	m۷
Output Short Circuit Current	I _{sc}		-30	-100	-180	-30	-100	-180	mA
Oscillator Section	,	T _j = 25°C	, /10						
Initial Accuracy (Note 6)		T, = 25°C	47	52	57	47	52	57	kHz
Voltage Stability		12 ≤ V _{cc} ≤ 25V	Chr.	0.2	1		0.2	1	%
Temperature Stability (Note 2)		$T_{MIN} \le T_A \le T_{MAX}$		5			5		%
Amplitude (Note 2)		MIN A MAA		1.7			1.7		٧
Discharge Current		$T_1 = 25^{\circ}C, V_{PIN 4} = 2V$	7.8	8.3	8.8	7.8	8.3	8.8	m/
3		$V_{PIN 4} = 2V$, $T_{MIN} \le T_A \le T_{MAX}$	7.5		8.8	7.6		8.8	mA
Error Amp Section		PIN 4 - 7 MIN - A - MAX	1						
Input Voltage		V _{PIN 1} = 2.5V	2.45	2.50	2.55	2.42	2.50	2.58	V
Input Bias Current	I _B	PIN 1 — Z.S.	2.10	-0.3	-1	2.12	-0.3	-2	<u>.</u> µА
Open Loop Gain	A _{VOL}	$2 \le V_0 \le 4V$	65	90		65	90	_	dB
Unity Gain Bandwidth (Note 2)		T _i = 25°C	0.7	1		0.7	1		MH:
Power Supply Rejection Ratio (Note 3)	PSRR	$12 \le V_{cc} \le 25V$	60	70		60	70		dB
Output Sink Current	I _{OL}	$V_{PIN 2} = 2.7V, V_{PIN 1} = 1.1V$	2	6		2	6		mA
Output Source Current	I _{OH}	$V_{PIN 2} = 2.3V, V_{PIN 1} = 5V$	-0.5	-0.8		-0.5	-0.8		m/
Output Voltage High Level	V _{OH}	$V_{PIN 9} = 2.3V, R_L = 15K \text{ to ground}$	5	6		5	6		V
Output Voltage Low Level	V _{OL}	$V_{\text{PIN }2} = 2.5 \text{ V}, R_{\text{L}} = 15 \text{ K to } V_{\text{REF}}$	+ -	0.7	1.1	<u> </u>	0.7	1.1	V
Current Sense Section	I 'OL	TPIN 2 — Z.77, N _L — TSK CS T _{REF}	ı			I			
Gain (Note 3 & 4)	Ι.Δ		2.85	3	3.15	2.85	3	3.15	V/V
Maximum Input Signal (Note 3)	A _{VOL}	$V_{PIN 1} = 5V$	0.9	1	1.1	0.9	1	1.1	V
Power Supply Rejection Ratio (Note 3)	PSRR	$v_{\text{PIN-1}} = 3V$ $12 \le V_{\text{CC}} \le 25V$	0.9	70	1.1	0.9	70	1.1	v dB
Input Bias Current	+	12 ≤ V _{CC} ≤ 23V	-	-2	-10		-2	-10	μА
Delay to Output (Note 2)	I _B	V _{PIN 3} = 0 to 2V	-	150	300		150	300	ns
Output Section	T _{pd}	V _{PIN 3} = 0 to 2V		130	300	<u> </u>	130	300	115
<u> </u>	1								
Output Low Level	V _{OL}	$I_{SINK} = 20mA$	_	0.1	0.4		0.1	0.4	٧
	J 01	I _{SINK} = 200mA		1.5	2.2		1.5	2.2	٧
Output High Level	V _{OH}	I _{SOURCE} = 20mA	13	13.5		13	13.5		٧
		I _{SOURCE} = 200mA	12	13.5		12	13.5		٧
Rise Time (Note 2)	T _R	$T_J = 25^{\circ}C$, $C_L = 1nF$		50	150		50	150	ns
Fall Time (Note 2)	T _F	$T_J = 25$ °C, $C_L = 1$ nF		50	150		50	150	ns
UVLO Saturation	V _{SAT}	$V_{cc} = 5V$, $I_{SINK} = 10mA$		0.7	1.2		0.7	1.2	٧

(Electrical Characteristics continue next page.)



CURRENT MODE PWM CONTROLLER

PRODUCTION DATA

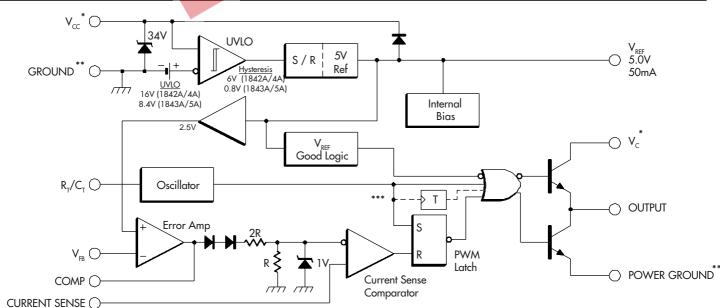
Parameter	Symbol Test Conditions		UC184xA/284xA							
		lest Conditions	Min.	Тур.	Max.	Min.	Тур.	Max.	Units	
Under-Voltage Lockout Section										
Start Threshold		x842A/4A		15	16	17	14.5	16	17.5	٧
		x843A/5A		7.8	8.4	9.0	7.8	8.4	9.0	٧
Min. Operation Voltage After Turn-On		x842A/4A		9	10	11	8.5	10	11.5	٧
		x843A/5A		7.0	7.6	8.2	7.0	7.6	8.2	٧
PWM Section										
Maximum Duty Cycle		x842A/3A		94	96	100	94	96	100	%
		x844A/5A		47	48	50	47	48	50	%
Minimum Duty Cycle						0			0	%
Total Standby Section										
Start-Up Current				4	0.3	0.5		0.3	0.5	mA
Operating Supply Current	I _{cc}		. A.	15	11	17		11	17	mA
Zener Voltage	V ₇	$I_{cc} = 25 \text{mA}$	4.4	30	35		30	35		V

Notes: 2. These parameters, although guaranteed, are not 100% tested in production.

- 3. Parameter measured at trip point of latch with $V_{VFB} = 0$.
- 5. Adjust V_{cc} above the start threshold before setting at 15V
- 6. Output frequency equals oscillator frequency for the UC1842A and UC1843A. Output frequency is one half oscillator frequency for the UC1844A and UC1845A.
- 7. "Temperature stability, sometimes referred to as average temperature coefficient, is described by the equation:

Temp Stability =
$$\frac{V_{REF} (max.) - V_{REF} (min.)}{T_{J} (max.) - T_{J} (min.)}$$

REF (max.) & VREF (min.) are the maximum & minimum reference voltage measured over the appropriate temperature range. Note that the extremes in voltage do not necessarily occur at the extremes in temperature."



- * $\,V_{_{CC}}\,$ and $\,V_{_{C}}\,$ are internally connected for 8 pin packages. ** POWER GROUND and GROUND are internally connected for 8 pin packages.
- *** Toggle flip flop used only in x844A and x845A series.

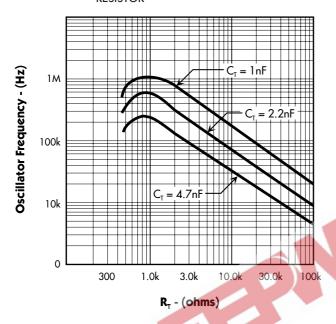


CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

CHARACTERISTIC CURVES

FIGURE 1. — OSCILLATOR FREQUENCY vs. TIMING RESISTOR

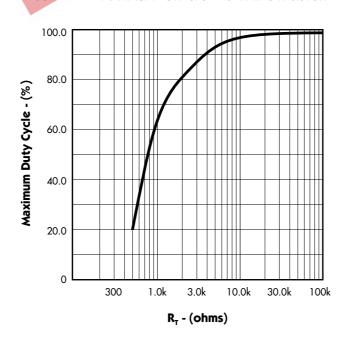


 V_{REF} 8 R_T/C_T 4 C_T R_T/C_T 5

For $R_T > 5k$, $f = \frac{1.72}{R_T}$

Note: Output drive frequency is half the oscillator frequency for the UCx844A/5A devices.

FIGURE 2. — MAXIMUM DUTY CYCLE vs. TIMING RESISTOR

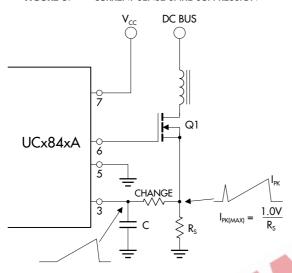


CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

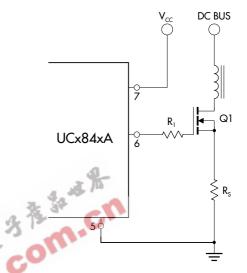
TYPICAL APPLICATION CIRCUITS

FIGURE 3. — CURRENT SENSE SPIKE SUPPRESSION



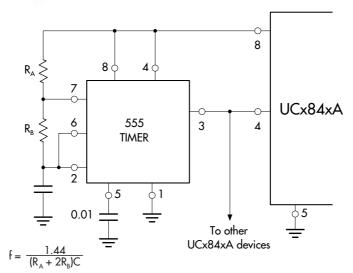
The RC low pass filter will eliminate the leading edge current spike caused by parasitics of Power MOSFET.

FIGURE 4. — MOSFET PARASITIC OSCILLATIONS



A resistor (R_i) in series with the MOSFET gate will reduce overshoot & ringing caused by the MOSFET input capacitance and any inductance in series with the gate drive. (Note: It is very important to have a low inductance ground path to insure correct operation of the I.C. This can be done by making the ground paths as short and as wide as possible.)

FIGURE 5. — EXTERNAL DUTY CYCLE CLAMP AND MULTI-UNIT SYNCHRONIZATION

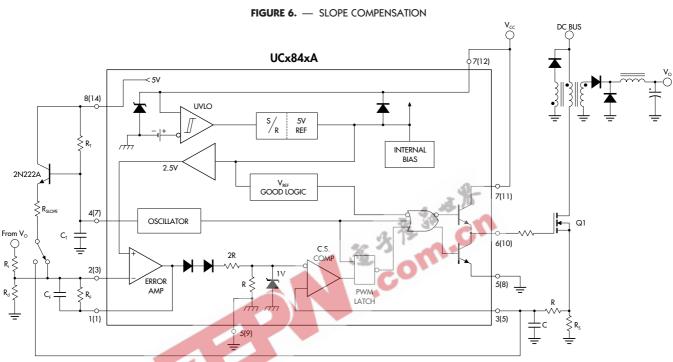


 $E = \frac{R_B}{R_A + 2R_B}$ Precision duty cycle limiting as well as synchronizing several parts is possible with the above circuitry.

CURRENT MODE PWM CONTROLLER

PRODUCTION DATA

TYPICAL APPLICATION CIRCUITS (continued)



Due to inherent instability of current mode converters running above 50% duty cycle, slope compensation should be added to either the current sense pin or the error amplifier. Figure 6 shows a typical slope compensation technique.

 V_{REF} $\leq R_T$ UCx84xA 2N2222 4.7K < COMP 100K 1K 2 0.1µF ERROR AMP **ADJUST** OUTPUT OUTPUT 6 4.7K ≥ 3 ADJUST 4 R_TC_T GROUND → GROUND

FIGURE 7. — OPEN LOOP LABORATORY FIXTURE

High peak currents associated with capacitive loads necessitate careful grounding techniques. Timing and bypass capacitors should be connected to pin 5 in a single point ground. The transistor and 5k potentiometer are used to sample the oscillator waveform and apply an adjustable ramp to pin 3.

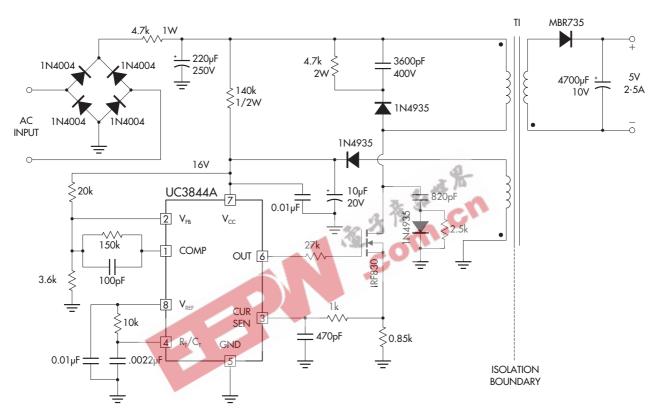


CURRENT MODE PWM CONTROLLER

PRODUCTION DATA SHEET

TYPICAL APPLICATION CIRCUITS (continued)

FIGURE 8. — OFF-LINE FLYBACK REGULATOR



SPECIFICATIONS

Input line voltage: 90VAC to 130VAC Input frequency: 50 or 60Hz
Switching frequency: 40KHz ±10%
Output power: 25W maximum
Output voltage: 5V +5%
Output current: 2 to 5A

Output current: 2 to 5ALine regulation: 0.01%/VLoad regulation: $8\%/A^*$

Efficiency @ 25 Watts,

 $V_{|N} = 90VAC:$ 70% $V_{|N} = 130VAC:$ 65%

Output short-circuit current: 2.5Amp average

* This circuit uses a low-cost feedback scheme in which the DC voltage developed from the primary-side control winding is sensed by the UC3844A error amplifier. Load regulation is therefore dependent on the coupling between secondary and control windings, and on transformer leakage inductance.

