

SN74AVCAH164245

16-BIT DUAL-SUPPLY BUS TRANSCEIVER WITH CONFIGURABLE VOLTAGE TRANSLATION AND 3-STATE OUTPUTS

SCES396 – JULY 2002

- Member of the Texas Instruments Widebus™ Family
- DOC™ Circuitry Dynamically Changes Output Impedance, Resulting in Noise Reduction Without Speed Degradation
- Dynamic Drive Capability Is Equivalent to Standard Outputs With I_{OH} and I_{OL} of ± 24 mA at 2.5-V V_{CC}
- Control Inputs V_{IH}/V_{IL} Levels are Referenced to V_{CCA} Voltage
- If Either V_{CC} Input Is at GND, Both Ports Are in the High-Impedance State
- Overvoltage-Tolerant Inputs/Outputs Allow Mixed-Voltage-Mode Data Communications
- I_{off} Supports Partial-Power-Down Mode Operation
- Fully Configurable Dual-Rail Design Allows Each Port to Operate Over the Full 1.4-V to 3.6-V Power-Supply Range
- Bus Hold on Data Inputs Eliminates the Need for External Pullup/Pulldown Resistors
- Latch-Up Performance Exceeds 100 mA Per JESD 78, Class II
- ESD Protection Exceeds JESD 22
 - 2000-V Human-Body Model (A114-A)
 - 200-V Machine Model (A115-A)
 - 1000-V Charged-Device Model (C101)

description/ordering information

This 16-bit (dual-octal) noninverting bus transceiver uses two separate configurable power-supply rails. The A-port is designed to track V_{CCA} . V_{CCA} accepts any supply voltage from 1.4 V to 3.6 V. The B-port is designed to track V_{CCB} . V_{CCB} accepts any supply voltage from 1.4 V to 3.6 V. This allows for universal low-voltage bidirectional translation between any of the 1.5-V, 1.8-V, 2.5-V, and 3.3-V voltage nodes.

The SN74AVCAH164245 is designed for asynchronous communication between data buses. The device transmits data from the A bus to the B bus or from the B bus to the A bus, depending on the logic level at the direction-control (DIR) input. The output-enable (\overline{OE}) input can be used to disable the outputs so the buses are effectively isolated.

The SN74AVCAH164245 is designed so that the control pins (1DIR, 2DIR, $1\overline{OE}$, and $2\overline{OE}$) are supplied by V_{CCA} .

Active bus-hold circuitry is provided to hold unused or floating data inputs at a valid logic level. Use of pullup or pulldown resistors with the bus-hold circuitry is not recommended.

To ensure the high-impedance state during power up or power down, \overline{OE} should be tied to V_{CCA} through a pullup resistor; the minimum value of the resistor is determined by the current-sinking capability of the driver.

This device is fully specified for partial-power-down applications using I_{off} . The I_{off} circuitry disables the outputs, preventing damaging current backflow through the device when it is powered down. If either V_{CC} input is at GND, then both ports are in the high-impedance state.

ORDERING INFORMATION

| TA | PACKAGE† | | ORDERABLE PART NUMBER | TOP-SIDE MARKING |
|---------------|-------------|---------------|-----------------------|------------------|
| –40°C to 85°C | TSSOP – DGG | Tape and reel | SN74AVCAH164245GR | AVCAH164245 |
| | TVSOP – DGV | Tape and reel | SN74AVCAH164245VR | WAH4245 |
| | VFBGA – GQL | Tape and reel | SN74AVCAH164245KR | WAH4245 |

† Package drawings, standard packing quantities, thermal data, symbolization, and PCB design guidelines are available at www.ti.com/sc/package.



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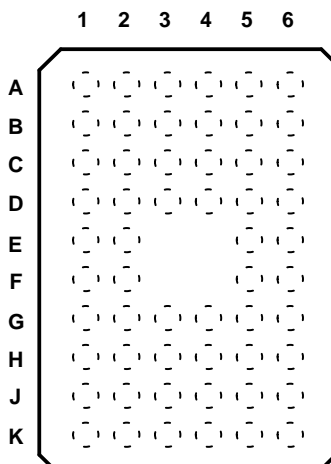
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terminal assignments

DGG OR DGV PACKAGE
(TOP VIEW)

| | | | |
|------------------|----|----|-------------------|
| 1DIR | 1 | 48 | 1 \overline{OE} |
| 1B1 | 2 | 47 | 1A1 |
| 1B2 | 3 | 46 | 1A2 |
| GND | 4 | 45 | GND |
| 1B3 | 5 | 44 | 1A3 |
| 1B4 | 6 | 43 | 1A4 |
| V _{CCB} | 7 | 42 | V _{CCA} |
| 1B5 | 8 | 41 | 1A5 |
| 1B6 | 9 | 40 | 1A6 |
| GND | 10 | 39 | GND |
| 1B7 | 11 | 38 | 1A7 |
| 1B8 | 12 | 37 | 1A8 |
| 2B1 | 13 | 36 | 2A1 |
| 2B2 | 14 | 35 | 2A2 |
| GND | 15 | 34 | GND |
| 2B3 | 16 | 33 | 2A3 |
| 2B4 | 17 | 32 | 2A4 |
| V _{CCB} | 18 | 31 | V _{CCA} |
| 2B5 | 19 | 30 | 2A5 |
| 2B6 | 20 | 29 | 2A6 |
| GND | 21 | 28 | GND |
| 2B7 | 22 | 27 | 2A7 |
| 2B8 | 23 | 26 | 2A8 |
| 2DIR | 24 | 25 | 2 \overline{OE} |

GQL PACKAGE
(TOP VIEW)



terminal assignments

| | 1 | 2 | 3 | 4 | 5 | 6 |
|---|------|-----|------------------|------------------|-----|-------------------|
| A | 1DIR | NC | NC | NC | NC | 1 \overline{OE} |
| B | 1B2 | 1B1 | GND | GND | 1A1 | 1A2 |
| C | 1B4 | 1B3 | V _{CCB} | V _{CCA} | 1A3 | 1A4 |
| D | 1B6 | 1B5 | GND | GND | 1A5 | 1A6 |
| E | 1B8 | 1B7 | | | 1A7 | 1A8 |
| F | 2B1 | 2B2 | | | 2A2 | 2A1 |
| G | 2B3 | 2B4 | GND | GND | 2A4 | 2A3 |
| H | 2B5 | 2B6 | V _{CCB} | V _{CCA} | 2A6 | 2A5 |
| J | 2B7 | 2B8 | GND | GND | 2A8 | 2A7 |
| K | 2DIR | NC | NC | NC | NC | 2 \overline{OE} |

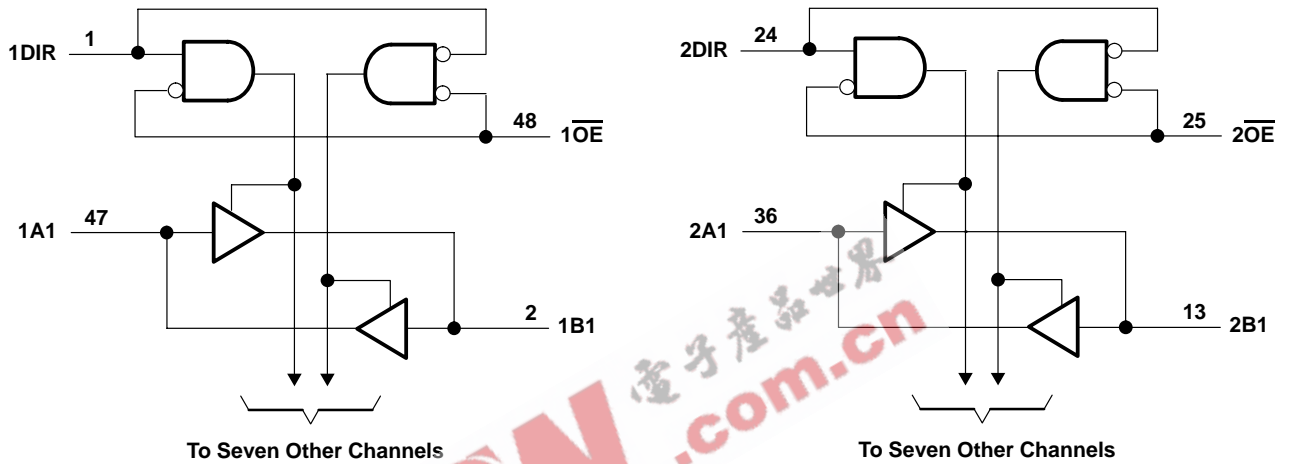
NC – No internal connection

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FUNCTION TABLE
(each 8-bit section)

| INPUTS | | OPERATION |
|-----------------|-----|-----------------|
| \overline{OE} | DIR | |
| L | L | B data to A bus |
| L | H | A data to B bus |
| H | X | Isolation |

logic diagram (positive logic)



Pin numbers shown are for the DGG and DGV packages.

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recommended operating conditions (see Notes 4 through 6)

| | | V _{CCI} | V _{CCO} | MIN | MAX | UNIT |
|------------------|------------------------------------|---|------------------|-------------------------|-------------------------|------|
| V _{CCA} | Supply voltage | | | 1.4 | 3.6 | V |
| V _{CCB} | Supply voltage | | | 1.4 | 3.6 | V |
| V _{IH} | High-level input voltage | Data inputs | 1.4 V to 1.95 V | V _{CCI} × 0.65 | V _{CCI} | V |
| | | | 1.95 V to 2.7 V | 1.7 | V _{CCI} | |
| | | | 2.7 V to 3.6 V | 2 | V _{CCI} | |
| V _{IL} | Low-level input voltage | Data inputs | 1.4 V to 1.95 V | 0 | V _{CCI} × 0.35 | V |
| | | | 1.95 V to 2.7 V | 0 | 0.7 | |
| | | | 2.7 V to 3.6 V | 0 | 0.8 | |
| V _{IH} | High-level input voltage | Control inputs (Referenced to V _{CCA}) | 1.4 V to 1.95 V | V _{CCA} × 0.65 | V _{CCA} | V |
| | | | 1.95 V to 2.7 V | 1.7 | V _{CCA} | |
| | | | 2.7 V to 3.6 V | 2 | V _{CCA} | |
| V _{IL} | Low-level input voltage | Control inputs (Referenced to V _{CCA}) | 1.4 V to 1.95 V | 0 | V _{CCA} × 0.35 | V |
| | | | 1.95 V to 2.7 V | 0 | 0.7 | |
| | | | 2.7 V to 3.6 V | 0 | 0.8 | |
| V _O | Output voltage | | | 0 | V _{CCO} | V |
| I _{OH} | High-level output current | | 1.4 V to 1.6 V | | -2 | mA |
| | | | 1.65 V to 1.95 V | | -4 | |
| | | | 2.3 V to 2.7 V | | -8 | |
| | | | 3 V to 3.6 V | | -12 | |
| I _{OL} | Low-level output current | | 1.4 V to 1.6 V | | 2 | mA |
| | | | 1.65 V to 1.95 V | | 4 | |
| | | | 2.3 V to 2.7 V | | 8 | |
| | | | 3 V to 3.6 V | | 12 | |
| Δt/Δv | Input transition rise or fall rate | | | | 5 | ns/V |
| T _A | Operating free-air temperature | | | -40 | 85 | °C |

- NOTES: 4. V_{CCI} is the V_{CC} associated with the data input port.
5. V_{CCO} is the V_{CC} associated with the output port.
6. All unused data inputs of the device must be held at V_{CCI} or GND to ensure proper device operation. Refer to the TI application report, *Implications of Slow or Floating CMOS Inputs*, literature number SCBA004.

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electrical characteristics over recommended operating free-air temperature range (unless otherwise noted) (see Notes 7 and 8)

| PARAMETER | | TEST CONDITIONS | | V _{CCA} | V _{CCB} | MIN | TYP† | MAX | UNIT |
|---------------------|----------------|---|-----------------------------------|------------------|------------------|--------------------------|------|------|------|
| V _{OH} | | I _{OH} = -100 µA | V _I = V _{IH} | 1.4 V to 3.6 V | 1.4 V to 3.6 V | V _{CCO} - 0.2 V | | | V |
| | | I _{OH} = -2 mA | V _I = V _{IH} | 1.4 V | 1.4 V | 1.05 | | | |
| | | I _{OH} = -4 mA | V _I = V _{IH} | 1.65 V | 1.65 V | 1.2 | | | |
| | | I _{OH} = -8 mA | V _I = V _{IH} | 2.3 V | 2.3 V | 1.75 | | | |
| | | I _{OH} = -12 mA | V _I = V _{IH} | 3 V | 3 V | 2.3 | | | |
| V _{OL} | | I _{OH} = 100 µA | V _I = V _{IL} | 1.4 V to 3.6 V | 1.4 V to 3.6 V | | | 0.2 | V |
| | | I _{OH} = 2 mA | V _I = V _{IL} | 1.4 V | 1.4 V | | | 0.35 | |
| | | I _{OH} = 4 mA | V _I = V _{IL} | 1.65 V | 1.65 V | | | 0.45 | |
| | | I _{OH} = 8 mA | V _I = V _{IL} | 2.3 V | 2.3 V | | | 0.55 | |
| | | I _{OH} = 12 mA | V _I = V _{IL} | 3 V | 3 V | | | 0.7 | |
| I _I | Control inputs | V _I = V _{CCA} or GND | | 1.4 V to 3.6 V | 3.6 V | | | ±2.5 | µA |
| I _{BHL} ‡ | | V _I = 0.49 V | | 1.4 V | 1.4 V | 11 | | | µA |
| | | V _I = 0.57 V | | 1.65 V | 1.65 V | 30 | | | |
| | | V _I = 0.7 V | | 2.3 V | 2.3 V | 45 | | | |
| | | V _I = 0.8 V | | 3 V | 3 V | 75 | | | |
| I _{BHH} § | | V _I = 0.49 V | | 1.4 V | 1.4 V | -11 | | | µA |
| | | V _I = 1.07 V | | 1.65 V | 1.65 V | -30 | | | |
| | | V _I = 1.7 V | | 2.3 V | 2.3 V | -45 | | | |
| | | V _I = 2 V | | 3 V | 3 V | -75 | | | |
| I _{BHLO} ¶ | | V _I = 0 to V _{CC} | | 1.6 V | 1.6 V | 100 | | | µA |
| | | | | 1.95 V | 1.95 V | 200 | | | |
| | | | | 2.7 V | 2.7 V | 300 | | | |
| | | | | 3.6 V | 3.6 V | 525 | | | |
| I _{BHHO} # | | V _I = 0 to V _{CC} | | 1.6 V | 1.6 V | -100 | | | µA |
| | | | | 1.95 V | 1.95 V | -200 | | | |
| | | | | 2.7 V | 2.7 V | -300 | | | |
| | | | | 3.6 V | 3.6 V | -525 | | | |
| I _{off} | A port | V _I or V _O = 0 to 3.6 V | | 0 V | 0 to 3.6 V | ±10 | | | µA |
| | B port | | | 0 to 3.6 V | 0 V | ±10 | | | |
| I _{OZ} | A or B ports | V _O = V _{CCO} or GND, V _I = V _{CCI} or GND | \overline{OE} = V _{IH} | 3.6 V | 3.6 V | ±12.5 | | | µA |
| | B port | | \overline{OE} = don't care | 0 V | 3.6 V | ±12.5 | | | |
| | A port | | | 3.6 V | 0 V | ±12.5 | | | |

† All typical values are at T_A = 25°C.

‡ The bus-hold circuit can sink at least the minimum low sustaining current at V_{IL} max. I_{BHL} should be measured after lowering V_{IN} to GND and then raising it to V_{IL} max.

§ The bus-hold circuit can source at least the minimum high sustaining current at V_{IH} min. I_{BHH} should be measured after raising V_{IN} to V_{CC} and then lowering it to V_{IH} min.

¶ An external driver must source at least I_{BHLO} to switch this node from low to high.

An external driver must sink at least I_{BHHO} to switch this node from high to low.

|| For I/O ports, the parameter I_{OZ} includes the input leakage current.

NOTES: 7. V_{CCO} is the V_{CC} associated with the output port.

8. V_{CCI} is the V_{CC} associated with the input port.

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electrical characteristics over recommended operating free-air temperature range (continued)
(unless otherwise noted) (see Note 9)

| PARAMETER | | TEST CONDITIONS | V _{CCA} | V _{CCB} | MIN | TYP† | MAX | UNIT |
|------------------|----------------|--|------------------|------------------|-----|------|-----|------|
| I _{CCA} | | V _I = V _{CCI} or GND, I _O = 0 | 1.6 V | 1.6 V | | | 20 | μA |
| | | | 1.95 V | 1.95 V | | | 20 | |
| | | | 2.7 V | 2.7 V | | | 30 | |
| | | | 0 V | 3.6 V | | | -40 | |
| | | | 3.6 V | 0 V | | | 40 | |
| | | | 3.6 V | 3.6 V | | | 40 | |
| I _{CCB} | | V _I = V _{CCI} or GND, I _O = 0 | 1.6 V | 1.6 V | | | 20 | μA |
| | | | 1.95 V | 1.95 V | | | 20 | |
| | | | 2.7 V | 2.7 V | | | 30 | |
| | | | 0 V | 3.6 V | | | 40 | |
| | | | 3.6 V | 0 V | | | -40 | |
| | | | 3.6 V | 3.6 V | | | 40 | |
| C _i | Control inputs | V _I = 3.3 V or GND | 3.3 V | 3.3 V | | 4 | pF | |
| C _{io} | A or B ports | V _O = 3.3 V or GND | 3.3 V | 3.3 V | | 5 | pF | |

† All typical values are at T_A = 25°C.

NOTE 9: V_{CCI} is the V_{CC} associated with the input port.

switching characteristics over recommended operating free-air temperature range,
V_{CCA} = 1.5 V ± 0.1 V (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | V _{CCB} = 1.5 V ± 0.1 V | | V _{CCB} = 1.8 V ± 0.15 V | | V _{CCB} = 2.5 V ± 0.2 V | | V _{CCB} = 3.3 V ± 0.3 V | | UNIT |
|------------------|------------------------|-------------|----------------------------------|-----|-----------------------------------|------|----------------------------------|------|----------------------------------|------|------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | |
| t _{pd} | A | B | 1.7 | 6.7 | 1.9 | 6.3 | 1.8 | 5.5 | 1.7 | 5.8 | ns |
| | B | A | 1.8 | 6.8 | 2.2 | 7.4 | 2.1 | 7.6 | 2.1 | 7.3 | |
| t _{en} | $\overline{\text{OE}}$ | A | 2.6 | 8.4 | 2.7 | 8.2 | 2.3 | 6.3 | 2.1 | 5.6 | ns |
| | $\overline{\text{OE}}$ | B | 2.7 | 8.6 | 3.2 | 10.2 | 3.2 | 10.8 | 3.2 | 10.7 | |
| t _{dis} | $\overline{\text{OE}}$ | A | 2.1 | 7 | 2.5 | 7 | 1.7 | 5.3 | 2 | 6.1 | ns |
| | $\overline{\text{OE}}$ | B | 2.1 | 7.1 | 2.5 | 7.1 | 2.1 | 6.5 | 2.1 | 6.4 | |

switching characteristics over recommended operating free-air temperature range,
V_{CCA} = 1.8 V ± 0.15 V (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | V _{CCB} = 1.5 V ± 0.1 V | | V _{CCB} = 1.8 V ± 0.15 V | | V _{CCB} = 2.5 V ± 0.2 V | | V _{CCB} = 3.3 V ± 0.3 V | | UNIT |
|------------------|------------------------|-------------|----------------------------------|-----|-----------------------------------|-----|----------------------------------|-----|----------------------------------|-----|------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | |
| t _{pd} | A | B | 1.7 | 6.4 | 1.8 | 6 | 1.7 | 4.7 | 1.6 | 4.3 | ns |
| | B | A | 1.4 | 5.5 | 1.8 | 6 | 1.8 | 5.8 | 1.8 | 5.5 | |
| t _{en} | $\overline{\text{OE}}$ | A | 2.5 | 8 | 2.7 | 7.8 | 2.2 | 5.8 | 2 | 5.1 | ns |
| | $\overline{\text{OE}}$ | B | 1.8 | 6.7 | 2.7 | 7.8 | 2.7 | 8.1 | 2.7 | 8.1 | |
| t _{dis} | $\overline{\text{OE}}$ | A | 2.1 | 6.4 | 2.5 | 6.4 | 1.5 | 4.5 | 1.8 | 5 | ns |
| | $\overline{\text{OE}}$ | B | 2.1 | 6.6 | 2.5 | 6.4 | 2 | 5.5 | 2 | 5.5 | |

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switching characteristics over recommended operating free-air temperature range,
 $V_{CCA} = 2.5 \text{ V} \pm 0.2 \text{ V}$ (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | $V_{CCB} = 1.5 \text{ V} \pm 0.1 \text{ V}$ | | $V_{CCB} = 1.8 \text{ V} \pm 0.15 \text{ V}$ | | $V_{CCB} = 2.5 \text{ V} \pm 0.2 \text{ V}$ | | $V_{CCB} = 3.3 \text{ V} \pm 0.3 \text{ V}$ | | UNIT |
|-----------|-----------------|-------------|---|-----|--|-----|---|-----|---|-----|------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | |
| t_{pd} | A | B | 1.6 | 6 | 1.8 | 5.6 | 1.5 | 4 | 1.4 | 3.4 | ns |
| | B | A | 1.3 | 4.6 | 1.7 | 4.4 | 1.5 | 4 | 1.4 | 3.7 | |
| t_{en} | \overline{OE} | A | 2.6 | 7.4 | 2.7 | 7.2 | 2.2 | 5.3 | 2 | 4.5 | ns |
| | \overline{OE} | B | 1.2 | 4.1 | 2.2 | 5.1 | 2.2 | 5.3 | 2.2 | 5.3 | |
| t_{dis} | \overline{OE} | A | 2 | 5.7 | 2.3 | 5.7 | 1.4 | 3.7 | 1.6 | 4 | ns |
| | \overline{OE} | B | 0.9 | 4.5 | 1.7 | 4.5 | 1.4 | 3.7 | 1.4 | 3.7 | |

switching characteristics over recommended operating free-air temperature range,
 $V_{CCA} = 3.3 \text{ V} \pm 0.3 \text{ V}$ (see Figure 2)

| PARAMETER | FROM (INPUT) | TO (OUTPUT) | $V_{CCB} = 1.5 \text{ V} \pm 0.1 \text{ V}$ | | $V_{CCB} = 1.8 \text{ V} \pm 0.15 \text{ V}$ | | $V_{CCB} = 2.5 \text{ V} \pm 0.2 \text{ V}$ | | $V_{CCB} = 3.3 \text{ V} \pm 0.3 \text{ V}$ | | UNIT |
|-----------|-----------------|-------------|---|-----|--|-----|---|-----|---|-----|------|
| | | | MIN | MAX | MIN | MAX | MIN | MAX | MIN | MAX | |
| t_{pd} | A | B | 1.5 | 5.9 | 1.7 | 5.4 | 1.5 | 3.7 | 1.4 | 3.1 | ns |
| | B | A | 1.3 | 4.5 | 1.6 | 3.8 | 1.5 | 3.3 | 1.4 | 3.1 | |
| t_{en} | \overline{OE} | A | 2.5 | 7 | 2.6 | 6.9 | 2.1 | 5 | 1.9 | 4.1 | ns |
| | \overline{OE} | B | 0.8 | 2.6 | 1.9 | 4 | 2 | 4.1 | 1.9 | 4.1 | |
| t_{dis} | \overline{OE} | A | 1.2 | 5.4 | 2.2 | 5.2 | 1.2 | 3.3 | 1.5 | 3.6 | ns |
| | \overline{OE} | B | 1.2 | 5.4 | 1.7 | 4.4 | 1.5 | 3.6 | 1.5 | 3.6 | |

operating characteristics, V_{CCA} and $V_{CCB} = 3.3 \text{ V}$, $T_A = 25^\circ\text{C}$

| PARAMETER | | TEST CONDITIONS | TYP | UNIT |
|-----------|--|------------------|-----|------|
| C_{pdA} | Power dissipation capacitance per transceiver, A port input, B port output | Outputs enabled | 14 | pF |
| | | Outputs disabled | 7 | |
| | Power dissipation capacitance per transceiver, B port input, A port output | Outputs enabled | 20 | |
| | | Outputs disabled | 7 | |
| C_{pdB} | Power dissipation capacitance per transceiver, A port input, B port output | Outputs enabled | 14 | pF |
| | | Outputs disabled | 7 | |
| | Power dissipation capacitance per transceiver, B port input, A port output | Outputs enabled | 20 | |
| | | Outputs disabled | 7 | |

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output description

The DOC™ circuitry is implemented, which, during the transition, initially lowers the output impedance to effectively drive the load and, subsequently, raises the impedance to reduce noise. Figure 1 shows typical V_{OL} vs I_{OL} and V_{OH} vs I_{OH} curves to illustrate the output impedance and drive capability of the circuit. At the beginning of the signal transition, the DOC circuit provides a maximum dynamic drive that is equivalent to a high-drive standard-output device. For more information, refer to the TI application reports, *AVC Logic Family Technology and Applications*, literature number SCEA006, and *Dynamic Output Control (DOC™) Circuitry Technology and Applications*, literature number SCEA009.

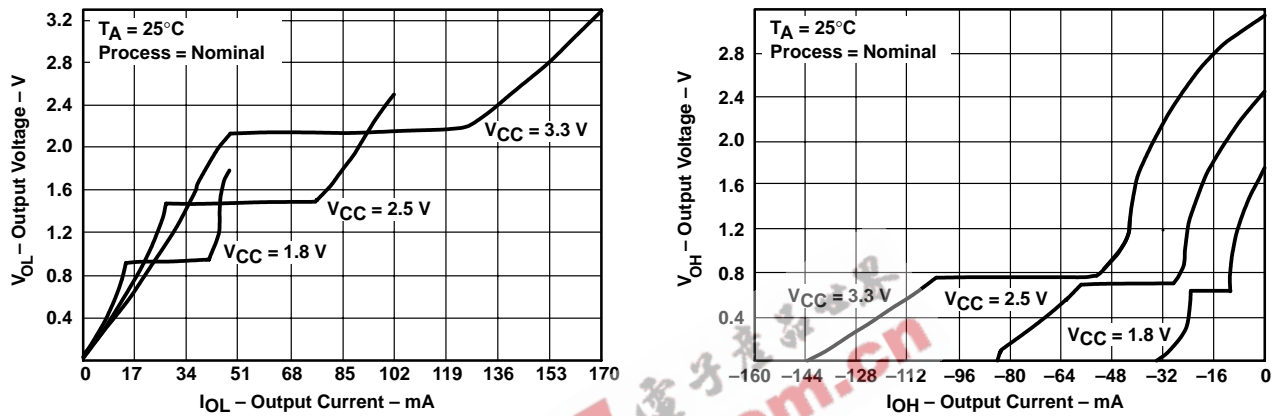
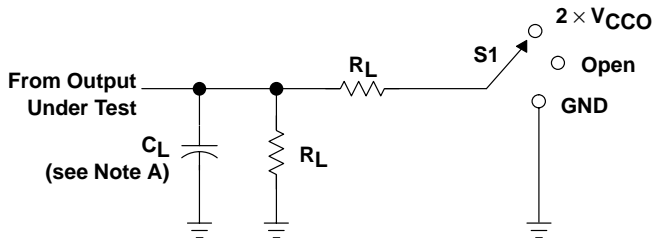


Figure 1. Output Voltage vs Output Current

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PARAMETER MEASUREMENT INFORMATION



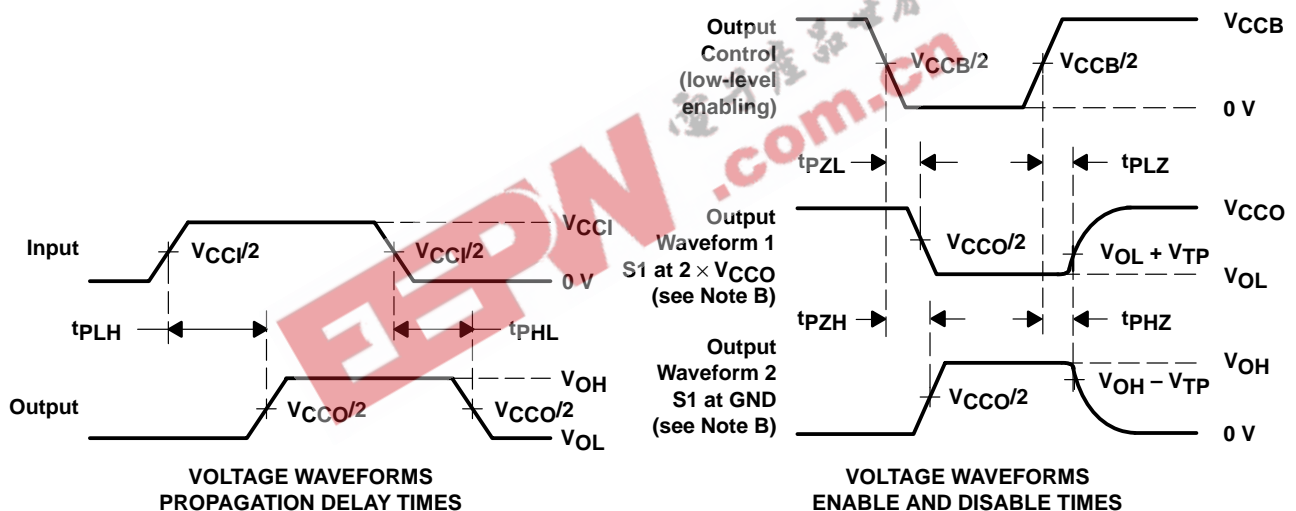
LOAD CIRCUIT

| TEST | S1 |
|-------------------|--------------------|
| t_{pd} | Open |
| t_{PLZ}/t_{PZL} | $2 \times V_{CCO}$ |
| t_{PHZ}/t_{PZH} | GND |

| V_{CCO} | C_L | R_L | V_{TP} |
|----------------------------------|-------|--------------|----------|
| $1.5\text{ V} \pm 0.1\text{ V}$ | 15 pF | 2 k Ω | 0.1 V |
| $1.8\text{ V} \pm 0.15\text{ V}$ | 30 pF | 1 k Ω | 0.15 V |
| $2.5\text{ V} \pm 0.2\text{ V}$ | 30 pF | 500 Ω | 0.15 V |
| $3.3\text{ V} \pm 0.3\text{ V}$ | 30 pF | 500 Ω | 0.3 V |



VOLTAGE WAVEFORMS
PULSE DURATION



VOLTAGE WAVEFORMS
PROPAGATION DELAY TIMES

VOLTAGE WAVEFORMS
ENABLE AND DISABLE TIMES

- NOTES:
- C_L includes probe and jig capacitance.
 - Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.
 - All input pulses are supplied by generators having the following characteristics: $PRR \leq 10\text{ MHz}$, $Z_O = 50\ \Omega$, $dv/dt \geq 1\text{ V/ns}$, $dv/dt \geq 1\text{ V/ns}$.
 - The outputs are measured one at a time with one transition per measurement.
 - t_{PLZ} and t_{PHZ} are the same as t_{dis} .
 - t_{PZL} and t_{PZH} are the same as t_{en} .
 - t_{PLH} and t_{PHL} are the same as t_{pd} .
 - V_{CC1} is the V_{CC} associated with the input port.
 - V_{CCO} is the V_{CC} associated with the output port.

Figure 2. Load Circuit and Voltage Waveforms

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