

# **ADC with Microphone Input and Programmable Digital Filters**

## **DESCRIPTION**

The WM8950 is a low power, high quality mono ADC designed for portable applications such as Digital Still Camera, Digital Voice Recorder or games console accessories.

The device integrates support for a differential or single ended mic. External component requirements are reduced as no separate microphone amplifiers are required.

Advanced Sigma Delta Converters are used along with digital decimation filters to give high quality audio at sample rates from 8 to 48ks/s. Additional digital filtering options are available, to cater for application filtering such as wind noise reduction, noise rejection, plus an advanced mixed signal ALC function with noise gate is provided.

An on-chip PLL is provided to generate the required Master Clock from an external reference clock. The PLL clock can also be output if required elsewhere in the system.

The WM8950 operates at supply voltages from 2.5 to 3.6V, although the digital supplies can operate at voltages down to 1.71V to save power. Different sections of the chip can also be powered down under software control by way of the selectable two or three wire control interface.

WM8950 is supplied in a very small 4x4mm QFN package. offering high levels of functionality in minimum board area, with high thermal performance.

## **FEATURES**

- **Mono ADC:**
- Audio sample rates:8, 11.025, 16, 22.05, 24, 32, 44.1, 48kHz
- SNR 95dB, THD -85dB ('A'-weighted  $@ 8 48$ ks/s)
- Multiple auxiliary analog inputs
- **Mic Preamps:** 
	- Differential or single end Microphone Interface
	- Programmable preamp gain
	- Psuedo differential inputs with common mode rejection
	- Programmable ALC / Noise Gate in ADC path
- Low-noise bias supplied for electret microphones

## **OTHER FEATURES**

- 5 band EQ
- Programmable High Pass Filter (wind noise reduction)
- Fully Programmable IIR Filter (notch filter)
- On-chip PLL
- Low power, low voltage
	- 2.5V to 3.6V (digital: 1.71V to 3.6V)
	- power consumption TBD all-on 48ks/s mode
- 4x4x0.9mm 24 pin QFN package

## **APPLICATIONS**

- Digital Still Camera
- General Purpose low power audio ADC
- Games console accessories
- Voice recorders



**WOLFSON MICROELECTRONICS plc** 

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# **PIN CONFIGURATION**



## **ORDERING INFORMATION**



**Note:** 

Reel Quantity = 3,500



## **PIN DESCRIPTION**



## **Note:**

It is recommended that the QFN ground paddle should be connected to analogue ground on the application PCB.



## **ABSOLUTE MAXIMUM RATINGS**

Absolute Maximum Ratings are stress ratings only. Permanent damage to the device may be caused by continuously operating at or beyond these limits. Device functional operating limits and guaranteed performance specifications are given under Electrical Characteristics at the test conditions specified.



ESD Sensitive Device. This device is manufactured on a CMOS process. It is therefore generically susceptible to damage from excessive static voltages. Proper ESD precautions must be taken during handling and storage of this device.

Wolfson tests its package types according to IPC/JEDEC J-STD-020B for Moisture Sensitivity to determine acceptable storage conditions prior to surface mount assembly. These levels are:

MSL1 = unlimited floor life at <30°C / 85% Relative Humidity. Not normally stored in moisture barrier bag. MSL2 = out of bag storage for 1 year at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag. MSL3 = out of bag storage for 168 hours at <30°C / 60% Relative Humidity. Supplied in moisture barrier bag.

The Moisture Sensitivity Level for each package type is specified in Ordering Information.



#### **Notes**

- 1. Analogue and digital grounds must always be within 0.3V of each other.
- 2. All digital and analogue supplies are completely independent from each other.

# **RECOMMENDED OPERATING CONDITIONS**



**Notes** 

1. When using PLL, DCVDD must be 1.9V or higher.



# **ELECTRICAL CHARACTERISTICS**

## **Test Conditions**

DCVDD = 1.8V, AVDD = DBVDD = 3.3V, SPKVDD = 3.3V,  $T_A$  = +25<sup>o</sup>C, 1kHz signal, fs = 48kHz, 24-bit audio data unless otherwise stated.





#### **Test Conditions**

 $DCVDD = 1.8V$ ,  $AVDD = DBVDD = 3.3V$ ,  $SPKVDD = 3.3V$ ,  $T_A = +25^{\circ}C$ ,  $1kHz$  signal,  $fs = 48kHz$ , 24-bit audio data unless otherwise stated.



## **TERMINOLOGY**

- 1. MICN input only in single ended microphone configuration. Maximum input signal to MICP without distortion is -3dBV.
- 2. Hold Time is the length of time between a signal detected being too quiet and beginning to ramp up the gain. It does not apply to ramping down the gain when the signal is too loud, which happens without a delay.
- 3. Ramp-up and Ramp-Down times are defined as the time it takes for the PGA to change it's gain by 6dB.<br>4. All hold, ramp-up and ramp-down times soals proportionally with MOLK.
- 4. All hold, ramp-up and ramp-down times scale proportionally with MCLK
- 5. Signal-to-noise ratio (dB) SNR is a measure of the difference in level between the full scale output and the output with no signal applied. (No Auto-zero or Automute function is employed in achieving these results).
- 6. THD+N (dB) THD+N is a ratio, of the rms values, of (Noise + Distortion)/Signal.



# **SIGNAL TIMING REQUIREMENTS**

## **SYSTEM CLOCK TIMING**



## **Figure 1 System Clock Timing Requirements**

#### **Test Conditions**

 $DCVDD = 1.8V$ , DBVDD=AVDD=SPKVDD=3.3V, DGND=AGND=SPKGND=0V, T<sub>A</sub> = +25°C, Slave Mode fs = 48kHz, MCLK = 256fs, 24-bit data, unless otherwise stated.



## **AUDIO INTERFACE TIMING – MASTER MODE**



**Figure 2 Digital Audio Data Timing – Master Mode (see Control Interface)** 



### **Test Conditions**

DCVDD=1.8V, DBVDD=AVDD=SPKVDD=3.3V, DGND=AGND=SPKGND=0V, T<sub>A</sub>=+25°C, Slave Mode, fs=48kHz, MCLK=256fs, 24-bit data, unless otherwise stated.



## **AUDIO INTERFACE TIMING – SLAVE MODE**



## **Test Conditions**

DCVDD=1.8V, DBVDD=AVDD=SPKVDD=3.3V, DGND=AGND=SPKGND=0V, T<sub>A</sub>=+25°C, Slave Mode, fs=48kHz, MCLK= 256fs, 24-bit data, unless otherwise stated.



**Note:** 

BCLK period should always be greater than or equal to MCLK period.



## **CONTROL INTERFACE TIMING – 3-WIRE MODE**

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#### **Figure 4 Control Interface Timing – 3-Wire Serial Control Mode**

### **Test Conditions**

DCVDD = 1.8V, DBVDD = AVDD = SPKVDD = 3.3V, DGND = AGND = SPKGND = 0V,  $T_A$  = +25<sup>o</sup>C, Slave Mode, fs = 48kHz, MCLK = 256fs, 24-bit data, unless otherwise stated.





## **CONTROL INTERFACE TIMING – 2-WIRE MODE**



**Figure 5 Control Interface Timing – 2-Wire Serial Control Mode** 

#### **Test Conditions**

 $DCVDD = 1.8V$ ,  $DBVDD = AVDD = SPKVDD = 3.3V$ ,  $DGND = AGND = SPKGND = 0V$ ,  $T_A = +25^{\circ}C$ , Slave Mode, fs = 48kHz, MCLK = 256fs, 24-bit data, unless otherwise stated.





## **DEVICE DESCRIPTION**

#### **INTRODUCTION**

The WM8950 is a low power audio ADC, with flexible line and microphone input. Applications for this device include games console accessories, digital still cameras, voice recorders and other general purpose audio applications.

#### **FEATURES**

The chip offers great flexibility in use, and so can support many different modes of operation as follows:

#### **MICROPHONE INPUTS**

Microphone inputs are provided, allowing for either a differential microphone input or a single ended microphone to be connected. These inputs have a user programmable gain range of -12dB to +35.25dB using internal resistors. After the input PGA stage comes a boost stage which can add a further 20dB of gain. A microphone bias is output from the chip which can be used to bias the microphones. The signal routing can be configured to allow manual adjustment of mic levels, or to allow the ALC loop to control the level of mic signal that is transmitted.

Total gain through the microphone paths of up to +55.25dB can be selected.

#### **PGA AND ALC OPERATION**

A programmable gain amplifier is provided in the input path to the ADC. This may be used manually or in conjunction with a mixed analogue/digital automatic level control (ALC) which keeps the recording volume constant. recording volume constant.

#### **AUX INPUT**

The device includes a mono input, AUX, that can be used as an input for warning tones (beep) etc. This path can also be summed into the input in a flexible fashion, either to the input PGA as a second microphone input or as a line input. The configuration of this circuit, with integrated on-chip resistors allows several analogue signals to be summed into the single AUX input if required.

#### **ADC**

The mono ADC uses a multi-bit high-order oversampling architecture to deliver optimum performance with low power consumption. Various sample rates are supported, from the 8ks/s rate typically used in voice dictation, up to the 48ks/s rate used in high quality audio applications.

#### **DIGITAL FILTERING**

Advanced Sigma Delta Converters are used along with digital decimation and interpolation filters to give high quality audio at sample rates from 8ks/s to 48ks/s.

Application specific digital filters are also available which help to reduce the effect of specific noise sources such as 'wind noise'. The filters include a programmable ADC high pass filter, an IIR filter with fully programmable coefficients, and a 5-band equaliser that can be applied to the record path in order to improve the overall audio sound from the device.

#### **AUDIO INTERFACES**

The WM8950 has a standard audio interface, to support the transmission of audio data from the chip. This interface is a 4 wire standard audio interface which supports a number of audio data formats including I<sup>2</sup>S, DSP Mode, MSB-First, left justified and MSB-First, right justified, and can operate in master or slave modes.

#### **CONTROL INTERFACES**

To allow full software control over all its features, the WM8950 offers a choice of 2 or 3 wire MPU control interface. It is fully compatible and an ideal partner for a wide range of industry standard microprocessors, controllers and DSPs. The selection between 2-wire mode and 3-wire mode is determined by the state of the MODE pin. If MODE is high then 3-wire control mode is selected, if MODE is low then 2-wire control mode is selected.

In 2 wire mode, only slave operation is supported, and the address of the device is fixed as 0011010.

#### **CLOCKING SCHEMES**

WM8950 offers the normal audio clocking scheme operation, where 256fs MCLK is provided to the ADC.



However, a PLL is also included which may be used to generate the internal master clock frequency in the event that this is not available from the system controller. This PLL uses an input clock, typically the 12MHz USB or ilink clock, to generate high quality audio clocks. If this PLL is not required for generation of these clocks, it can be reconfigured to generate alternative clocks which may then be output on the CSB/GPIO pin and used elsewhere in the system.

### **POWER CONTROL**

The design of the WM8950 has given much attention to power consumption without compromising performance. It operates at low supply voltages, and includes the facility to power off any unused parts of the circuitry under software control, includes standby and power off modes.

## **INPUT SIGNAL PATH**

The WM8950 has 3 flexible analogue inputs: two microphone inputs, and an auxiliary input. These inputs can be used in a variety of ways. The input signal path before the ADC has a flexible PGA block which then feeds into a gain boost/mixer stage.

#### **MICROPHONE INPUTS**

The WM8950 can accommodate a variety of microphone configurations including single ended and differential inputs. The inputs through the MICN, MICP and optionally AUX pins are amplified through the input PGA as shown in Figure 6 .

A pseudo differential input is the preferential configuration where the positive terminal of the input PGA is connected to the MICP input pin by setting MICP2INPPGA=1. The microphone ground should then be connected to MICN (when MICN2INPPGA=1) or optionally to AUX (when AUX2INPPGA=1) input pins.

Alternatively a single ended microphone can be connected to the MICN input with MICN2INPPGA set to 1. The non-inverting terminal of the input PGA should be connected internally to VMID by setting MICP2INPPGA to 0. N.



**Figure 6 Microphone Input PGA Circuit (switch positions shown are for differential mic input)** 





The input PGA is enabled by the IPPGAEN register bit.



## **INPUT PGA VOLUME CONTROL**

The input microphone PGA has a gain range from -12dB to +35.25dB in 0.75dB steps. The gain from the MICN input to the PGA output and from the AUX amplifier to the PGA output are always common and controlled by the register bits INPPGAVOL[5:0]. These register bits also affect the MICP pin when MICP2INPPGA=1.

C ä

When the Automatic Level Control (ALC) is enabled the input PGA gain is then controlled automatically and the INPPGAVOL bits should not be used.



**Table 1 Input PGA Volume Control** 



#### **AUXILIARY INPUT**

An auxiliary input circuit (Figure 7) is provided which consists of an amplifier which can be configured either as an inverting buffer for a single input signal or as a mixer/summer for multiple inputs with the use of external resistors. The circuit is enabled by the register bit AUXEN.



#### **Figure 7 Auxiliary Input Circuit**

The AUXMODE register bit controls the auxillary input mode of operation:

In buffer mode (AUXMODE=0) the switch labelled AUXSW in Figure 7 is open and the signal at the AUX pin will be buffered and inverted through the aux circuit using only the internal components.

In mixer mode (AUXMODE=1) the on-chip input resistor is bypassed, this allows the user to sum in multiple inputs with the use of external resistors. When used in this mode there will be gain variations through this path from part to part due to the variation of the internal 20kΩ resistors relative to the higher tolerance external resistors.



**Table 2 Auxiliary Input Buffer Control** 

#### **INPUT BOOST**

The input BOOST circuit has 3 selectable inputs: the input microphone PGA output, the AUX amplifier output and the MICP input pin (when not using a differential microphone configuration). These three inputs can be mixed together and have individual gain boost/adjust as shown in Figure 8.





#### **Figure 8 Input Boost Stage**

The input PGA path can have a +20dB boost (PGABOOST=1) a 0dB pass through (PGABOOST=0) or be completely isolated from the input boost circuit (INPPGAMUTE=1).



#### **Table 3 Input BOOST Stage Control**

The Auxiliary amplifier path to the BOOST stage is controlled by the AUX2BOOSTVOL[2:0] register bits. When AUX2BOOSTVOL=000 this path is completely disconnected from the BOOST stage. Settings 001 through to 111 control the gain in 3dB steps from -12dB to +6dB.

The MICP path to the BOOST stage is controlled by the MICP2BOOSTVOL[2:0] register bits. When MICP2BOOSTVOL=000 this input pin is completely disconnected from the BOOST stage. Settings 001 through to 111 control the gain in 3dB steps from -12dB to +6dB.



**Table 4 Input BOOST Stage Control** 



The BOOST stage is enabled under control of the BOOSTEN register bit.



**Table 5 Input BOOST Enable Control** 

### **MICROPHONE BIASING CIRCUIT**

The MICBIAS output provides a low noise reference voltage suitable for biasing electret type microphones and the associated external resistor biasing network. Refer to the Applications Information section for recommended external components. The MICBIAS voltage can be altered via the MBVSEL register bit. When MBVSEL=0, MICBIAS=0.9\*AVDD and when MBVSEL=1, MICBIAS=0.75\*AVDD. The output can be enabled or disabled using the MICBEN control bit.



**Table 6 Microphone Bias Enable** 



**Table 7 Microphone Bias Voltage Control** 

The internal MICBIAS circuitry is shown in Figure 9. Note that the maximum source current capability for MICBIAS is 3mA. The external biasing resistors therefore must be large enough to limit the MICBIAS current to 3mA.



 **Figure 9 Microphone Bias Schematic** 



## **ANALOGUE TO DIGITAL CONVERTER (ADC)**

The WM8950 uses a multi-bit, oversampled sigma-delta ADC channel. The use of multi-bit feedback and high oversampling rates reduces the effects of jitter and high frequency noise. The ADC Full Scale input level is proportional to AVDD. With a 3.3V supply voltage, the full scale level is 1.0V<sub>rms</sub>. Any voltage greater than -1dBfs may overload the ADC and cause distortion.

#### **ADC DIGITAL FILTERS**

The ADC filters perform true 24 bit signal processing to convert the raw multi-bit oversampled data from the ADC to the correct sampling frequency to be output on the digital audio interface. The digital filter path is illustrated in Figure 10 **.**



The ADC is enabled by the ADCEN register bit.



**Table 8 ADC Enable** 

The polarity of the output signal can also be changed under software control using the ADCPOL register bit. The oversampling rate of the ADC can be adjusted using the ADCOSR register bit. With ADCOSR=0 the oversample rate is 64x which gives lowest power operation and when ADCOSR=1 the oversample rate is 128x which gives best performance.



**Table 9 ADC Oversample Rate Select** 



## **SELECTABLE HIGH PASS FILTER**

A selectable high pass filter is provided. To disable this filter set HPFEN=0. The filter has two modes controlled by HPFAPP. In Audio Mode (HPFAPP=0) the filter is first order, with a cut-off frequency of 3.7Hz. In Application Mode (HPFAPP=1) the filter is second order, with a cut-off frequency selectable via the HPFCUT register. The cut-off frequencies when HPFAPP=1 are shown in Table 11.



**Table 10 ADC Filter Select** 



**Table 11 High Pass Filter Cut-off Frequencies (HPFAPP=1) Values in Hz** 

Note that the High Pass filter values (when HPFAPP=1) work on the basis that the SR register bits are set correctly for the actual sample rate as shown in Table 11.



## **PROGRAMMABLE IIR FILTER**

An IIR filter with fully programmable coefficients is provided, typically used as a notch filter for removing narrow band noise at a given frequency. This notch filter has a variable centre frequency and bandwidth, programmable via two coefficients, a0 and a1. a0 and a1 are represented by the register bits NFA0[13:0] and NFA1[13:0]. Because these coefficient values require four register writes to setup there is an NFU (Notch Filter Update) flag which should be set only when all four registers are setup.



**Table 12 Notch Filter Function** 

The coefficients are calculated as follows:

$$
a_0 = \frac{1 - \tan(w_b/2)}{1 + \tan(w_b/2)}
$$

$$
a_1 = -(1 + a_0)\cos(w_0)
$$

Where:

$$
w_0 = 2\pi f_c / f_s
$$

$$
w_b = 2\pi f_b / f_s
$$

 $f_c$  = centre frequency in Hz,  $f_b$  = -3dB bandwidth in Hz,  $f_s$  = sample frequency in Hz

The actual register values can be determined from the coefficients as follows:

 NFA0 = -a0 x 213 NFA1 = -a1 x 212



### **DIGITAL ADC VOLUME CONTROL**

The output of the ADCs can be digitally attenuated over a range from -127dB to 0dB in 0.5dB steps. The gain for a given eight-bit code X is given by:



<b>REGISTER</b> <b>ADDRESS</b>	BIT	LABEL	<b>DEFAULT</b>	<b>DESCRIPTION</b>
R <sub>15</sub>	7:0	<b>ADCVOL</b>	11111111	<b>ADC Digital Volume Control</b>
<b>ADC Digital</b>		[7:0]	$0dB$ )	$0000 0000 =$ Digital Mute
Volume				$00000001 = -127dB$
				$00000010 = -126.5dB$
				$\dots$ 0.5dB steps up to
				$1111 1111 = OdB$

**Table 13 ADC Volume** 

## **INPUT LIMITER / AUTOMATIC LEVEL CONTROL (ALC)**

The WM8950 has an automatic pga gain control circuit, which can function as an input peak limiter or as an automatic level control (ALC).

In input peak limiter mode (ALCMODE bit = 1), a digital peak detector detects when the input signal goes above a predefined level and will ramp the pga gain down to prevent the signal becoming too large for the input range of the ADC. When the signal returns to a level below the threshold, the pga gain is slowly returned to its starting level. The peak limiter cannot increase the pga gain above its static level.



**Figure 11 Input Peak Limiter Operation** 

In ALC mode (ALCMODE bit  $= 0$ ) the circuit aims to keep a constant recording volume irrespective of the input signal level. This is achieved by continuously adjusting the PGA gain so that the signal level at the ADC input remains constant. A digital peak detector monitors the ADC output and changes the PGA gain if necessary.





The ALC/Limiter function is enabled by setting the register bit ALCSEL. When enabled, the recording volume can be programmed between –6dB and –28.5dB (relative to ADC full scale) using the ALCLVL register bits. An upper limit for the PGA gain can be imposed by setting the ALCMAX control bits and a lower limit for the PGA gain can be imposed by setting the ALCMIN control bits.

ALCHLD, ALCDCY and ALCATK control the hold, decay and attack times, respectively:

**Hold** time is the time delay between the peak level detected being below target and the PGA gain beginning to ramp up. It can be programmed in power-of-two  $(2^n)$  steps, e.g. 2.67ms, 5.33ms, 10.67ms etc. up to 43.7s. Alternatively, the hold time can also be set to zero. The hold time is not active in limiter mode (ALCMODE = 1). The hold time only applies to gain ramp-up, there is no delay before ramping the gain down when the signal level is above target.

**Decay** (Gain Ramp-Up) Time is the time that it takes for the PGA gain to ramp up and is given as a time per gain step, time per 6dB change and time to ramp up over 90% of it's range. The decay time can be programmed in power-of-two  $(2^n)$  steps, from 3.3ms/6dB, 6.6ms/6dB, 13.1ms/6dB, etc. to 3.36s/6dB.

**Attack** (Gain Ramp-Down) Time is the time that it takes for the PGA gain to ramp down and is given as a time per gain step, time per 6dB change and time to ramp down over 90% of it's range. The attack time can be programmed in power-of-two  $(2^n)$  steps, from 832us/6dB, 1.66ms/6dB, 3.328us/6dB, etc. to 852ms/6dB.

NB, In peak limiter mode the gain control circuit runs approximately 4x faster to allow reduction of fast peaks. Attack and Decay times for peak limiter mode are given below.

The hold, decay and attack times given in Table 14 are constant across sample rates so long as the SR bits are set correctly. E.g. when sampling at 48kHz the sample rates stated in Table 14 will only be correct if the SR bits are set to 000 (48kHz). If the actual sample rate was only 44.1kHz then the hold, decay and attack times would be scaled down by 44.1/48.







**WM8950** Preliminary Technical Data



**Table 14 ALC Control Registers** 



#### **ALC CLIP PROTECTION**

To prevent clipping when a large signal occurs just after a period of quiet, the ALC circuit includes a clip protection function. If the ADC input signal exceeds 87.5% of full scale (–1.16dB), the PGA gain is ramped down at the maximum attack rate (as when ALCATK = 0000), until the signal level falls below 87.5% of full scale. This function is automatically enabled whenever the ALC is enabled.

#### **Note:**

If ATK = 0000, then the clip protection circuit makes no difference to the operation of the ALC. It is designed to prevent clipping when long attack times are used.

#### **NOISE GATE**

When the signal is very quiet and consists mainly of noise, the ALC function may cause "noise pumping", i.e. loud hissing noise during silence periods. The WM8950 has a noise gate function that prevents noise pumping by comparing the signal level at the input pins against a noise gate threshold, NGTH. The noise gate cuts in when:

Signal level at ADC [dB] < NGTH [dB] + PGA gain [dB] + Mic Boost gain [dB]

This is equivalent to:

Signal level at input pin [dB] < NGTH [dB]

The PGA gain is then held constant (preventing it from ramping up as it normally would when the signal is quiet).

The table below summarises the noise gate control register. The NGTH control bits set the noise gate threshold with respect to the ADC full-scale range. The threshold is adjusted in 6dB steps. Levels at the extremes of the range may cause inappropriate operation, so care should be taken with set-up of the function. Note that the noise gate only works in conjunction with the ALC function.



**Table 15 ALC Noise Gate Control** 

#### **GRAPHIC EQUALISER**

A 5-band graphic EQ is provided, which can be applied to the ADC data under control of the EQMODE register bit.



**Table 16 EQ Select** 



The equaliser consists of low and high frequency shelving filters (Band 1 and 5) and three peak filters for the centre bands. Each has adjustable cut-off or centre frequency, and selectable boost (+/- 12dB in 1dB steps). The peak filters have selectable bandwidth.



**Table 17 EQ Band 1 Control** 



**Table 18 EQ Band 2 Control** 



**Table 19 EQ Band 3 Control** 





**Table 20 EQ Band 4 Control** 



**Table 21 EQ Band 5 Control** 



**Table 22 Gain Register Table** 



**NICN** MICP **AUX** AVDD/2 AVDD/2 $\bullet$ **BUFIOEN**  $R1[2]$ Used to tie off all unused inputs

A dedicated buffer is available for tieing off unused analogue input pins as shown below Figure 13. This buffer can be enabled using the BUFIOEN register bit.

 **Figure 13 Unused Input Pin Tie-off Buffers** 

## **THERMAL SHUTDOWN**



To protect the WM8950 from overheating a thermal shutdown circuit is included. If the device<br>temperature reaches approximately 125<sup>0</sup>C and the thermal shutdown circuit is enabled (TSDEN=1), an interrupt can be generated. See the GPIO and Interrupt Controller section for details.

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**Table 23 Thermal Shutdown** 



## **DIGITAL AUDIO INTERFACES**

The audio interface has three pins:

- ADCDAT: ADC data output
- FRAME: Data alignment clock
- BCLK: Bit clock, for synchronisation

The clock signals BCLK, and FRAME can be outputs when the WM8950 operates as a master, or inputs when it is a slave (see Master and Slave Mode Operation, below).

Five different audio data formats are supported:

- Left justified
- Right justified
- $\cdot$   $I^2S$
- DSP mode early
- DSP mode late

All of these modes are MSB first. They are described in Audio Data Formats, below. Refer to the Electrical Characteristic section for timing information.

#### **MASTER AND SLAVE MODE OPERATION**

The WM8950 audio interface may be configured as either master or slave. As a master interface device the WM8950 generates BCLK and FRAME and thus controls sequencing of the data transfer on ADCDAT. To set the device to master mode register bit MS should be set high. In slave mode (MS=0), the WM8950 responds with data to clocks it receives over the digital audio interfaces.

#### **AUDIO DATA FORMATS**

In Left Justified mode, the MSB is available on the first rising edge of BCLK following an FRAME transition. The other bits up to the LSB are then transmitted in order. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles before each FRAME transition.



## **Figure 14 Left Justified Audio Interface (assuming n-bit word length)**

In Right Justified mode, the LSB is available on the last rising edge of BCLK before a FRAME transition. All other bits are transmitted before (MSB first). Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles after each FRAME transition.





**Figure 15 Right Justified Audio Interface (assuming n-bit word length)** 

In  $I^2$ S mode, the MSB is available on the second rising edge of BCLK following a FRAME transition. The other bits up to the LSB are then transmitted in order. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles between the LSB of one sample and the MSB of the next.





In DSP/PCM mode, the left channel MSB is available on either the 1<sup>st</sup> (mode B) or  $2<sup>nd</sup>$  (mode A) rising edge of BCLK (selectable by FRAMEP) following a rising edge of FRAME. Right channel data immediately follows left channel data. Depending on word length, BCLK frequency and sample rate, there may be unused BCLK cycles between the LSB of the right channel data and the next sample.

In device master mode, the LRC output will resemble the frame pulse shown in Figure 17 and Figure 18. In device slave mode, Figure 19 and Figure 20, it is possible to use any length of frame pulse less than 1/fs, providing the falling edge of the frame pulse occurs greater than one BCLK period before the rising edge of the next frame pulse.



**Figure 17 DSP/PCM Mode Audio Interface (mode A, LRP=0, Master)** 





#### **Figure 18 DSP/PCM Mode Audio Interface (mode B, LRP=1, Master)**







**Figure 20 DSP/PCM Mode Audio Interface (mode B, LRP=0, Slave)** 

![](_page_30_Picture_8.jpeg)

![](_page_31_Picture_160.jpeg)

When using ADCLRSWAP = 1 in DSP/PCM mode, the data will appear in the Right Phase of the FRAME, which will be 16/20/24/32 bits after the FRAME pulse.

**Table 24 Audio Interface Control** 

## **AUDIO INTERFACE CONTROL**

The register bits controlling audio format, word length and master / slave mode are summarised below. Each audio interface can be controlled individually.

Register bit MS selects audio interface operation in master or slave mode. In Master mode BCLK, and FRAME are outputs. The frequency of BCLK and FRAME in master mode are controlled with BCLKDIV. These are divided down versions of master clock. This may result in short BCLK pulses at the end of a frame if there is a non-integer ratio of BCLKs to FRAME clocks.

![](_page_31_Picture_8.jpeg)

![](_page_32_Picture_149.jpeg)

**Table 25 Clock Control** 

## **COMPANDING**

The WM8950 supports A-law and µ-law companding. Companding can be enabled on the ADC audio interface by writing the appropriate value to the ADC\_COMP register bit.

![](_page_32_Picture_6.jpeg)

![](_page_33_Picture_214.jpeg)

#### **Table 26 Companding Control**

Companding involves using a piecewise linear approximation of the following equations (as set out by ITU-T G.711 standard) for data compression:

µ-law (where µ=255 for the U.S. and Japan):

 $F(x) = \ln(1 + \mu|x|) / \ln(1 + \mu)$  -1 x 1

A-law (where A=87.6 for Europe):

![](_page_33_Picture_215.jpeg)

The companded data is also inverted as recommended by the G.711 standard (all 8 bits are inverted for µ-law, all even data bits are inverted for A-law). The data will be transmitted as the first 8 MSB's of data.

Companding converts 13 bits (µ-law) or 12 bits (A-law) to 8 bits using non-linear quantization. The input data range is separated into 8 levels, allowing low amplitude signals better precision than that of high amplitude signals. This is to exploit the operation of the human auditory system, where louder sounds do not require as much resolution as quieter sounds. The companded signal is an 8 bit word containing sign (1-bit), exponent (3-bits) and mantissa (4-bits).

![](_page_33_Picture_216.jpeg)

**Table 27 8-bit Companded Word Composition** 

![](_page_33_Figure_13.jpeg)

**Figure 21 u-Law Companding** 

![](_page_33_Picture_15.jpeg)

![](_page_34_Figure_2.jpeg)

**Figure 22 A-Law Companding** 

## **AUDIO SAMPLE RATES**

The WM8950 sample rate for the ADC is set using the SR register bits. The cutoffs for the digital filters and the ALC attack/decay times stated are determined using these values and assume a 256fs master clock rate.

If a sample rate that is not explicitly supported by the SR register settings is required then the closest SR value to that sample rate should be chosen, the filter characteristics and the ALC attack, decay and hold times will scale appropriately.

![](_page_34_Picture_204.jpeg)

**Table 28 Sample Rate Control** 

## **MASTER CLOCK AND PHASE LOCKED LOOP (PLL)**

The WM8950 has an on-chip phase-locked loop (PLL) circuit that can be used to:

Generate master clocks for the WM8950 audio functions from another external clock, e.g. in telecoms applications.

Generate and output (on pin CSB/GPIO) a clock for another part of the system that is derived from an existing audio master clock.

Figure 23 shows the PLL and internal clocking arrangment on the WM8950.

The PLL can be enabled or disabled by the PLLEN register bit.

![](_page_34_Picture_15.jpeg)

![](_page_35_Picture_197.jpeg)

**Table 29 PLLEN Control Bit** 

![](_page_35_Figure_4.jpeg)

## **Figure 23 PLL and Clock Select Circuit**

 $PLLN = int R$ 

## PLLK = int  $(2^{24}$  (R-PLLN) **EXAMPLE:**

MCLK=12MHz, required clock = 12.288MHz.

R should be chosen to ensure 5 < PLLN < 13. There is a fixed divide by 4 in the PLL and a selectable divide by N after the PLL which should be set to divide by 2 to meet this requirement.

Enabling the divide by 2 sets the required  $f_2 = 4 \times 2 \times 12.288$ MHz = 98.304MHz.

```
R = 98.304 / 12 = 8.192
```

$$
PLLN = int R = 8
$$

 $k = int (2^{24} \times (8.192 - 8)) = 3221225 = 3126E9h$ 

![](_page_35_Picture_198.jpeg)

**Table 30 PLL Frequency Ratio Control** 

![](_page_35_Picture_17.jpeg)

## Preliminary Technical Data **WM8950**

![](_page_36_Picture_219.jpeg)

![](_page_36_Picture_220.jpeg)

**Table 31 PLL Frequency Examples** 

# **GENERAL PURPOSE INPUT/OUTPUT**

₹

The CSB/GPIO pin can be configured to perform a variety of useful tasks by setting the GPIOSEL register bits. The GPIO is only available in 2 wire mode.

![](_page_36_Picture_221.jpeg)

**Table 32 CSB/GPIO Control** 

![](_page_36_Picture_9.jpeg)

#### **CONTROL INTERFACE**

#### **SELECTION OF CONTROL MODE AND 2-WIRE MODE ADDRESS**

The control interface can operate as either a 3-wire or 2-wire MPU interface. The MODE pin determines the 2 or 3 wire mode as shown in Table 33.

The WM8950 is controlled by writing to registers through a serial control interface. A control word consists of 16 bits. The first 7 bits (B15 to B9) are address bits that select which control register is accessed. The remaining 9 bits (B8 to B0) are register bits, corresponding to the 9 bits in each control register.

![](_page_37_Picture_146.jpeg)

**Table 33 Control Interface Mode Selection** 

### **3-WIRE SERIAL CONTROL MODE**

In 3-wire mode, every rising edge of SCLK clocks in one data bit from the SDIN pin. A rising edge on CSB/GPIO latches in a complete control word consisting of the last 16 bits.

![](_page_37_Figure_10.jpeg)

**Figure 24 3-Wire Serial Control Interface** 

#### **2-WIRE SERIAL CONTROL MODE**

The WM8950 supports software control via a 2-wire serial bus. Many devices can be controlled by the same bus, and each device has a unique 7-bit device address (this is not the same as the 7-bit address of each register in the WM8950).

The WM8950 operates as a slave device only. The controller indicates the start of data transfer with a high to low transition on SDIN while SCLK remains high. This indicates that a device address and data will follow. All devices on the 2-wire bus respond to the start condition and shift in the next eight bits on SDIN (7-bit address + Read/Write bit, MSB first). If the device address received matches the address of the WM8950, then the WM8950 responds by pulling SDIN low on the next clock pulse (ACK). If the address is not recognised or the R/W bit is '1' when operating in write only mode, the WM8950 returns to the idle condition and wait for a new start condition and valid address.

During a write, once the WM8950 has acknowledged a correct address, the controller sends the first byte of control data (B15 to B8, i.e. the WM8950 register address plus the first bit of register data). The WM8950 then acknowledges the first data byte by pulling SDIN low for one clock pulse. The controller then sends the second byte of control data (B7 to B0, i.e. the remaining 8 bits of register data), and the WM8950 acknowledges again by pulling SDIN low.

Transfers are complete when there is a low to high transition on SDIN while SCLK is high. After a complete sequence the WM8950 returns to the idle state and waits for another start condition. If a start or stop condition is detected out of sequence at any point during data transfer (i.e. SDIN changes while SCLK is high), the device jumps to the idle condition.

![](_page_37_Picture_17.jpeg)

![](_page_38_Figure_2.jpeg)

#### **Figure 25 2-Wire Serial Control Interface**

In 2-wire mode the WM8950 has a fixed device address, 0011010.

## **RESETTING THE CHIP**

The WM8950 can be reset by performing a write of any value to the software reset register (address 0 hex). This will cause all register values to be reset to their default values. In addition to this there is a Power-On Reset (POR) circuit which ensures that the registers are set to default when the device is powered up.

## **POWER SUPPLIES**

The WM8950 can use up to three separate power supplies:

AVDD, AVDD2, AGND and AGND2: Analogue supply, powers all analogue functions. AVDD can range from 2.5V to 3.6V and has the most significant impact on overall power consumption. A large AVDD slightly improves audio quality.

DCVDD: Digital core supply, powers all digital functions except the audio and control interfaces. DCVDD can range from 1.71V to 3.6V, and has no effect on audio quality. The return path for DCVDD is DGND, which is shared with DBVDD.

DBVDD Can range from 1.71V to 3.6V. DBVDD return path is through DGND.

It is possible to use the same supply voltage for all supplies. However, digital and analogue supplies should be routed and decoupled separately on the PCB to keep digital switching noise out of the analogue signal paths.

## **POWER MANAGEMENT**

#### **SAVING POWER BY REDUCING OVERSAMPLING RATE**

The default mode of operation of the ADC digital filters is in 64x oversampling mode. Under the control of ADCOSR the oversampling rate may be doubled. 64x oversampling results in a slight decrease in noise performance compared to 128x but lowers the power consumption of the device.

![](_page_38_Picture_252.jpeg)

**Table 34 ADC Oversampling Rate Selection** 

#### **VMID**

The analogue circuitry will not work unless VMID is enabled (VMIDSEL 00). The impedance of the VMID resistor string, together with the decoupling capacitor on the VMID pin will determine the startup time of the VMID circuit.

![](_page_38_Picture_253.jpeg)

**Table 35 VMID Impedance Control** 

![](_page_38_Picture_22.jpeg)

**BIASEN** 

![](_page_39_Picture_97.jpeg)

**Table 36 BIASEN Control** 

## **ESTIMATED SUPPLY CURRENTS**

When the ADC is enabled it is estimated that approximately 4mA will be drawn from DCVDD when fs=48kHz (This will be lower at lower sample rates). When the PLL is enabled an additional 700 microamps will be drawn from DCVDD.

Table 59 shows the estimated 3.3V AVDD current drawn by various circuits, by register bit.

![](_page_39_Picture_98.jpeg)

**Table 37 AVDD Supply Current** 

![](_page_39_Picture_10.jpeg)

## **REGISTER MAP**

![](_page_40_Picture_260.jpeg)

# **DIGITAL FILTER CHARACTERISTICS**

![](_page_41_Picture_85.jpeg)

**Table 38 Digital Filter Characteristics** 

## **TERMINOLOGY**

- 1. Stop Band Attenuation (dB) the degree to which the frequency spectrum is attenuated (outside audio band) 2. Pass-band Ripple – any variation of the frequency response in the pass-band region<br>2. Pass-band Ripple – any variation of the frequency response in the pass-band region<br>2. Pass-band Ripple – any variation of the frequen
- 

![](_page_41_Picture_8.jpeg)

![](_page_42_Figure_2.jpeg)

# **ADC FILTER RESPONSES**

![](_page_42_Figure_4.jpeg)

![](_page_42_Picture_7.jpeg)

![](_page_42_Picture_8.jpeg)

## **DE-EMPHASIS FILTER RESPONSES**

![](_page_43_Figure_3.jpeg)

![](_page_43_Figure_4.jpeg)

Figure 28 De-emphasis Frequency Response (32kHz) Figure 29 De-emphasis Error (32kHz)

![](_page_43_Figure_6.jpeg)

![](_page_43_Figure_7.jpeg)

Frequency (Hz)  **Figure 32 De-emphasis Frequency Response (48kHz) Figure 33 De-emphasis Error (48kHz)** 

0 5000 10000 15000 20000

![](_page_43_Figure_9.jpeg)

0 5000 10000 15000 20000 Frequency (Hz)

 $-0.10 + 0$ 

-10

The WM8950 has a selectable digital highpass filter in the ADC filter path. This filter has two modes, audio and applications. In audio mode the filter is a 1<sup>st</sup> order IIR with a cutoff of around 3.7Hz. In applications mode the filter is a  $2<sup>nd</sup>$  order high pass filter with a selectable cutoff frequency.

![](_page_44_Figure_3.jpeg)

**Figure 36 ADC Highpass Filter Responses (24kHz), HPFAPP=1, all cutoff settings shown.** 

Frequency (Hz)

**Figure 37 ADC Highpass Filter Responses (12kHz), HPFAPP=1, all cutoff settings shown.** 

### **5-BAND EQUALISER**

The WM8950 has a 5-band equaliser which can be applied to the ADC path. The plots from Figure 38 to Figure 51 show the frequency responses of each filter with a sampling frequency of 48kHz, firstly showing the different cut-off/centre frequencies with a gain of ±12dB, and secondly a sweep of the gain from -12dB to +12dB for the lowest cut-off/centre frequency of each filter.

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![](_page_45_Figure_4.jpeg)

![](_page_45_Figure_5.jpeg)

7 TITAN

 **Figure 38 EQ Band 1 – Low Frequency Shelf Filter Cut-offs Figure 39 EQ Band 1 – Gains for Lowest Cut-off Frequency**

![](_page_45_Figure_7.jpeg)

15 <u>t i i i i i i </u>  $+11100$  $+111111$ **TTTTM**  $1111111$  $\begin{array}{c} 1.144100 \\ 1.444400 \end{array}$ n militar<br>Hermitian i i i iii ii um  $\frac{1}{1}$ 中間 10 Ĵ iiii iini  $\begin{array}{c} 1 \\ 1 \\ 1 \end{array}$ Magnitude (dB) <u>ani</u> -5 שעורכו במערכות<br>שעורכו בשעורכו  $\begin{array}{c} 1.1.111101 \\ 1.1.111101 \end{array}$  $\frac{1}{4}\frac{14}{14}\frac{140}{160} =$ 十尺間 四期 1000 국수보변.<br>국수보변.  $\frac{1}{1}$ 胃器 -10  $\mathbb{M}$  . The set **TELESCO**  $\begin{array}{c} 1.1111111 \\ 1.11111111 \end{array}$ 11111 1111111 1111111 1.1.11110 **TTHE**  $10^{5}$   $10^{1}$   $10^{1}$   $10^{2}$   $10^{3}$   $10^{4}$   $10^{5}$  $10^{-1}$   $10^{0}$ 10<sup>1</sup> <sup>10</sup><sup>2</sup> Frequency (Hz)  $10^{3}$ 10<sup>4</sup>

ã.

**Figure 40 EQ Band 2 – Peak Filter Centre Frequencies, EQ2BW=0** 

![](_page_45_Figure_10.jpeg)

**Figure 42 EQ Band 2 – EQ2BW=0, EQ2BW=1** 

![](_page_45_Picture_12.jpeg)

![](_page_46_Figure_2.jpeg)

 $\overline{\text{min}}$ TTTM कामा mm mm 1111111  $\frac{13.14444}{13.14444}$ 1.111.000 **TELLUM**  $\begin{array}{c} 1.111111\\ 1.111111 \end{array}$  $1.111$ **THE STATE** THEFT 1111111 i i i i 1999 非常血 1899 1899 10 i i i i i i i i . . . . . . . AH ii iii i i i i i i ii iii 5  $\widehat{\mathbf{g}}$ Magnitude (dB) Magnitude UШ 0 ya<br>Katifa יייייי<br>יייייי a o um.<br>Tri min יים בו<br>ייייידי שעות ב<br>תחום ב  $\perp$  0 000 பய -5 **THIL** 1111111  $111100$ 1.11100  $1.111111$  $1111$ 1111111 1.11100 1.111111  $1111$ ப்பய பெய்ட் ம் பயட د د h. பயம  $\overline{1}$ பய -10 TTTHI TTTHI TETHE ī T TERRI  $\overline{1}$ **LITTLE**  $11100$  $\pm 11100$ a na Mii<br>a na mii  $\begin{array}{c} 1 & 1 & 111111 \\ 1 & 1 & 1111111 \end{array}$ **TTH** . . . .  $10^{-1}$  10<sup>-1</sup> 10<sup>0</sup> 10<sup>1</sup> 10<sup>2</sup> 10<sup>3</sup> 10<sup>4</sup> 10<sup>5</sup> Frequency (Hz)

15

**Figure 43 EQ Band 3 – Peak Filter Centre Frequencies, EQ3BW=0** 

**Figure 44 EQ Band 3 – Peak Filter Gains for Lowest Cut-off Frequency, EQ3BW=0** 

![](_page_46_Figure_6.jpeg)

**Figure 45 EQ Band 3 – EQ3BW=0, EQ3BW=1** 

![](_page_46_Figure_8.jpeg)

![](_page_47_Figure_2.jpeg)

**Figure 46 EQ Band 4 – Peak Filter Centre Frequencies, EQ3BW=0** 

	$-15$ $10^{2}$	пиш $10^{-1}$	111111 $10^{\circ}$	TTUT 10 <sup>1</sup> Frequency (Hz)	111100 10 <sup>2</sup>	<b>LETTIN</b> $10^{3}$	ттин 10 <sup>4</sup>
Magnitude (dB)	$-10$	ш тин 11111 шш	ш 1111 Ш Ш	ш нш Ш an m	пш THE пш TШ	an m THILL THI 11111	ПH 1111 $\mathbf{H}$ HH
		ш Ш шш	Ш Ш 1111	Ш Ш 11111	THE нш 1111	VIII илти ш	шш шш шш
	$-5$	ш ш 11111	ш 1111 ш	Ш Ш 11111	LIND шв THE	ши ы ИΠ	ÆШ TН шш
	$\Omega$	ш 11111 1111111 11111	Ш ш 111111 11111	Ш шш <b>I LIHA</b> шш	11111 Ш 111111 <b>RNII</b>	THE ш 11111 шш	ш 1111 . 1111
	5	ш ш шш	Ш ш 1111	Ш Ш ш	ити Иш 'nш ∕∣⊧	ш ш 11110	Ш ш шш
	10	ш ш 111111 шш	Ш ш THE Ш	Ш ш 11111 Ш	ш TШ ⊓ıīn 11700	willi <b>NNII</b> TINN ШN	Ш ш ш Ш
	15	шш	11111	THE	11111	11111	Ш

**Figure 48 EQ Band 4 – EQ3BW=0, EQ3BW=1** 

![](_page_47_Figure_6.jpeg)

שונותו<br>שטורתו  $111111$ T TITULI<br>T TITULI  $\begin{array}{c} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ \end{array}$ 111111  $1111$ 青苔器 半晶晶 半骨髓 非常温 т пти  $1111$ 10 T 1111111 111000 стании  $\frac{1}{1}$  $1.111111$ **LILL** 1111111 1111111 **COURT** 1111111  $\begin{tabular}{c} - & - & - \\ - &$ 半月期 中央职 非常咖 ₹ 5 TELLUI ........ THEFT tude (dB) . . . . . . . . . . . . . . . ....... Magnitude (dB) . . . . . . iiiii 0 fannit -5 i ituu חות הדר -10 1111111  $1111$ 1111111  $\frac{1}{2}$  )  $\frac{1}{2}$  )  $\frac{1}{2}$  )  $\frac{1}{2}$ гтниц 111000 1111111  $1111$ 10<sup>1</sup> 10<sup>0</sup> 10<sup>1</sup> 10<sup>1</sup> 10<sup>2</sup> 10<sup>3</sup> 10<sup>4</sup> 10<sup>5</sup><br>10<sup>1</sup> 10<sup>0</sup> 10<sup>1</sup> 10<sup>2</sup> 10<sup>3</sup> 10<sup>4</sup> 10<sup>5</sup>

 $\overline{m}$ 

 $\overline{\text{mm}}$ 

<del>. . . . . .</del>

**Figure 49 EQ Band 5 – High Frequency Shelf Filter Cut-offsFigure 50 EQ Band 5 – Gains for Lowest Cut-off Frequency**

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mmm

![](_page_47_Picture_9.jpeg)

**Figure 47 EQ Band 4 – Peak Filter Gains for Lowest Cut-off Frequency, EQ4BW=0** 

![](_page_47_Figure_11.jpeg)

![](_page_47_Picture_606.jpeg)

Figure 51shows the result of having the gain set on more than one channel simultaneously. The blue traces show each band (lowest cut-off/centre frequency) with ±12dB gain. The red traces show the cumulative effect of all bands with +12dB gain and all bands -12dB gain, with EQxBW=0 for the peak filters.

![](_page_48_Figure_3.jpeg)

![](_page_48_Figure_4.jpeg)

![](_page_48_Picture_5.jpeg)

## **APPLICATIONS INFORMATION**

## **RECOMMENDED EXTERNAL COMPONENTS**

![](_page_49_Figure_4.jpeg)

 **Figure 52 Recommended External Components** 

![](_page_49_Picture_6.jpeg)

## **PACKAGE DIAGRAM**

![](_page_50_Figure_3.jpeg)

NOTES:<br>1. DIMENSION b APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.15 mm AND 0.30 mm FROM TERMINAL TIP.<br>2. FALLS WITHIN JEDEC, MO-220, VARIATION VGGD-2.<br>3. ALL DIMENSIONS ARE IN MILLIMETRES.<br>4. THE TERMINAL #1

![](_page_50_Picture_11.jpeg)

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![](_page_51_Picture_12.jpeg)